|  |  |
| --- | --- |
|  | E/ECE/324/Rev.1/Add.78/Rev.4/Amend.5−E/ECE/TRANS/505/Rev.1/Add.78/Rev.4/Amend.5 |
|  |  | 17 March 2022 |

 Agreement

 Concerning the Adoption of Harmonized Technical United Nations Regulations for Wheeled Vehicles, Equipment and Parts which can be Fitted and/or be Used on Wheeled Vehicles and the Conditions for Reciprocal Recognition of Approvals Granted on the Basis of these United Nations Regulations[[1]](#footnote-2)\*

(Revision 3, including the amendments which entered into force on 14 September 2017)

\_\_\_\_\_\_\_\_\_

 Addendum 78 – UN Regulation No. 79

 Revision 4 - Amendment 5

Supplement 5 to the 03 series of amendments – Date of entry into force: 7 January 2022

 Uniform provisions concerning the approval of vehicles with regard to steering equipment

This document is meant purely as documentation tool. The authentic and legal binding text is: ECE/TRANS/WP.29/2021/72.

**\_\_\_\_\_\_\_\_\_**

**UNITED NATIONS**

*Renumber paragraph 2.3.4.18.* to paragraph 2.4.18.

*Paragraph 5.6.4.1.2,* amend to read:

"5.6.4.1.2. When the ACSF of Category C is in standby mode, the ACSF of Category B1 shall aim to centre the vehicle in the lane, unless a different position in lane is deemed reasonable due to the situation or resulting from driver input (e.g. when another vehicle is driving close beside).

This shall be demonstrated by the vehicle manufacturerto the Technical Service during type approval."

*Paragraph 5.6.4.2.3.,* amend to read:

"5.6.4.2.3. The system shall …

… These conditions shall be ensured by the use of at least two independent means.

In the case of a transition from a road type with a classification permitting an ACSF of Category C, to a type of road where an ACSF of Category C is not permitted, the system shall be deactivated automatically (off mode), unless a missing second lane in driving direction is the only condition not fulfilled from the above (e.g. a connector between two highways)."

*Paragraph 5.6.4.3.,* amend to read:

"5.6.4.3. Overriding

 A steering input by the driver shall override the steering action of the system. The steering control effort necessary to override the directional control provided by the system shall not exceed 50 N.

 The system may remain active, provided that priority is given to the driver during the overriding period."

*Paragraph 5.6.4.7.,* amend to read:

"5.6.4.7. Critical situation

 A situation is deemed to be critical when, at the time a lane change manoeuvre starts, an approaching vehicle in the target lane would have to decelerate at a higher level than 3m/s², 0.4 seconds after the lane change manoeuvre has started, to ensure the distance between the two vehicles is never less than that which the lane change vehicle travels in 1 second.

 The resulting critical distance at the start of the lane change manoeuvre shall be calculated using the following formula:

S*critical = (vrear - vACSF) \* tB + (vrear - vACSF)2 / (2 \* a) + vACSF \* tG*

 Where:

vrear is The actual speed of the approaching vehicle or 130 km/h whatever value is lower

vACSF is The actual speed of the ACSF vehicle

a = 3 m/s² (Deceleration of the approaching vehicle)

tB = 0.4 s (Time after the start of the lane change manoeuvre at which the deceleration of the approaching vehicle starts)

tG = 1 s (Remaining gap of the vehicles after the deceleration of the approaching vehicle)."

*Annex 8*

*Paragraph 2.,* amend to read:

"2. Testing conditions

The tests shall be performed on a flat, dry asphalt or concrete surface affording good adhesion. The ambient temperature shall be between 0 °C and 45 °C.

At the request of the manufacturer and with the agreement of the Technical Service tests may be conducted under deviating test conditions (suboptimal conditions, e.g. on a not dry surface; below the specified minimum ambient temperature), whilst the performance requirements are still to be met."

*Paragraph 3.5.1.2.,* amend to read:

"3.5.1.2. The requirements of the test are fulfilled if:

(a) The lateral movement towards the marking does not start earlier than 1 second after the lane change procedure was initiated,

(b) The lateral movement to approach the lane marking and the lateral movement necessary to complete the lane change manoeuvre are completed as one continuous movement,

 […]

(j) The direction indicator is deactivated not before the end of the lane change manoeuvre and no later than 0.5 seconds after ACSF of Category B1 has resumed, in case the lateral movement is initiated automatically and the direction indicator control was not fully engaged (latched position) during the lane change manoeuvre."

1. \* Former titles of the Agreement:

 Agreement concerning the Adoption of Uniform Conditions of Approval and Reciprocal Recognition of Approval for Motor Vehicle Equipment and Parts, done at Geneva on 20 March 1958 (original version);

 Agreement concerning the Adoption of Uniform Technical Prescriptions for Wheeled Vehicles, Equipment and Parts which can be Fitted and/or be Used on Wheeled Vehicles and the Conditions for Reciprocal Recognition of Approvals Granted on the Basis of these Prescriptions, done at Geneva on 5 October 1995 (Revision 2). [↑](#footnote-ref-2)