

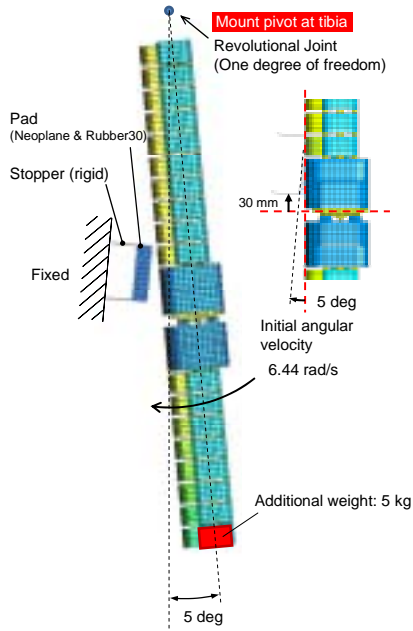
**Development of A Dynamic Assembly
Calibration Test Procedure for Flex-GTR
using an FE Flex-GT-prototype model**

Computer Simulation Analysis

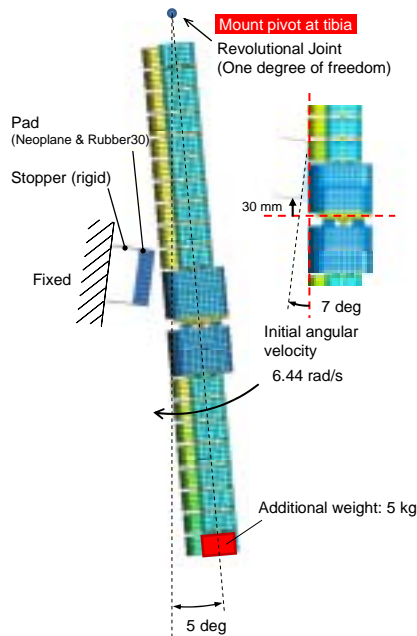
Conditions of the Computer Simulation Analysis

Stopper angle: 5 deg, 7 deg., 10 deg., 12 deg.

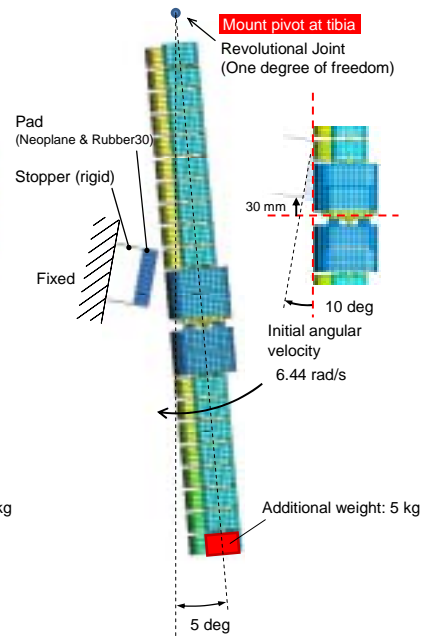
Type A-2-PAD5-5 (5deg.)



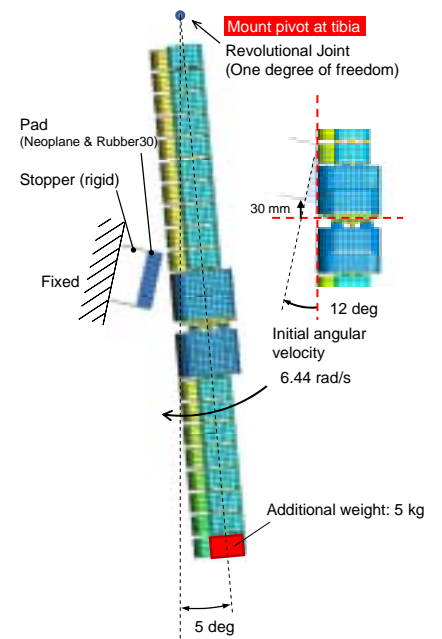
Type A-2-PAD5-6 (7deg.)



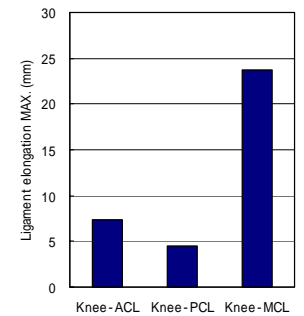
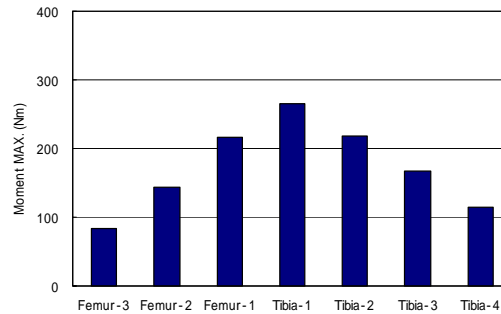
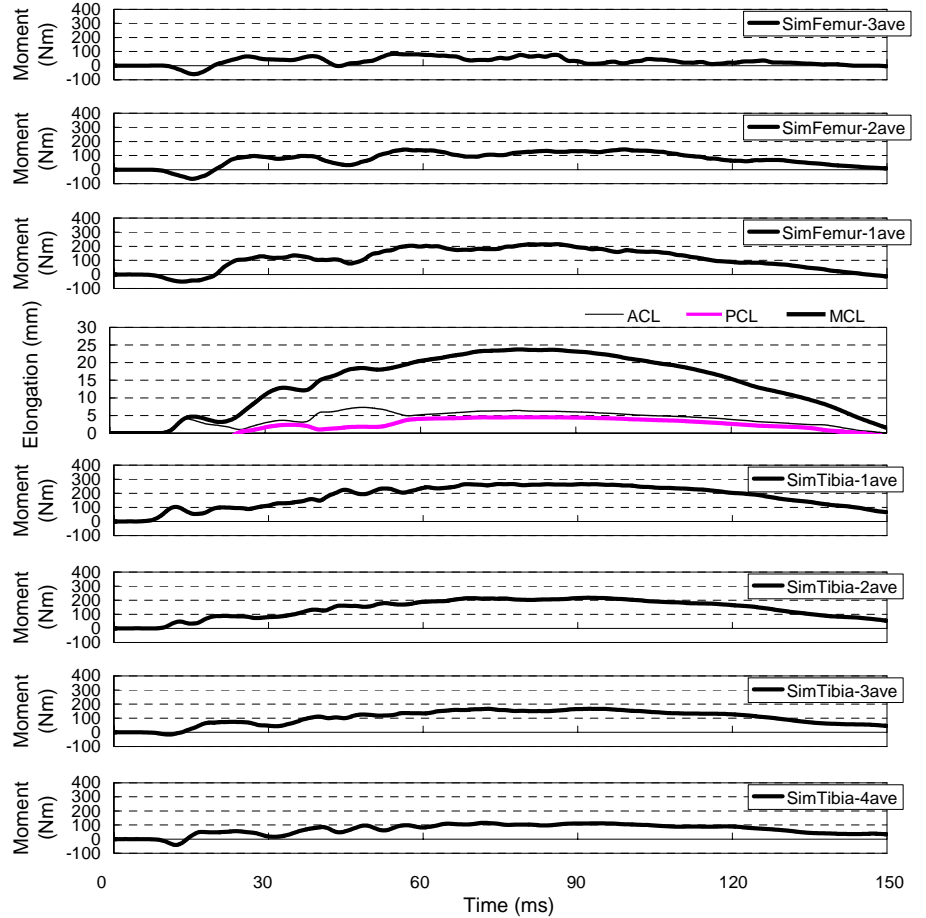
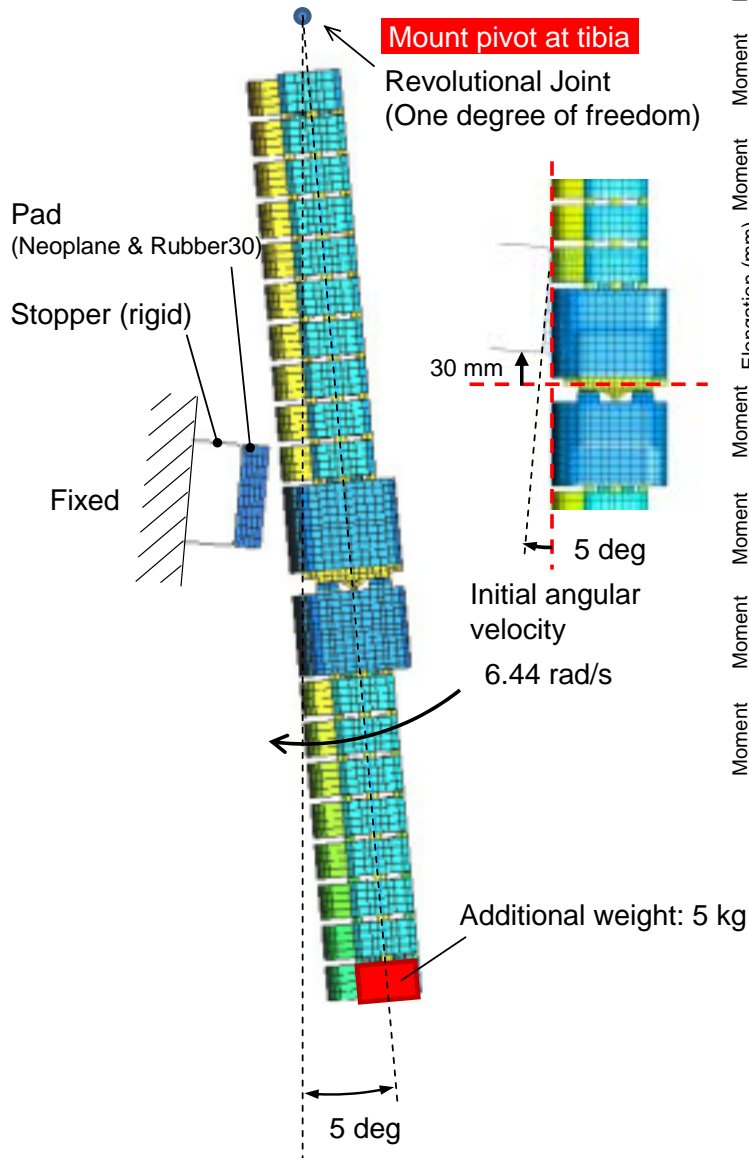
Type A-2-PAD5-7 (10deg.)



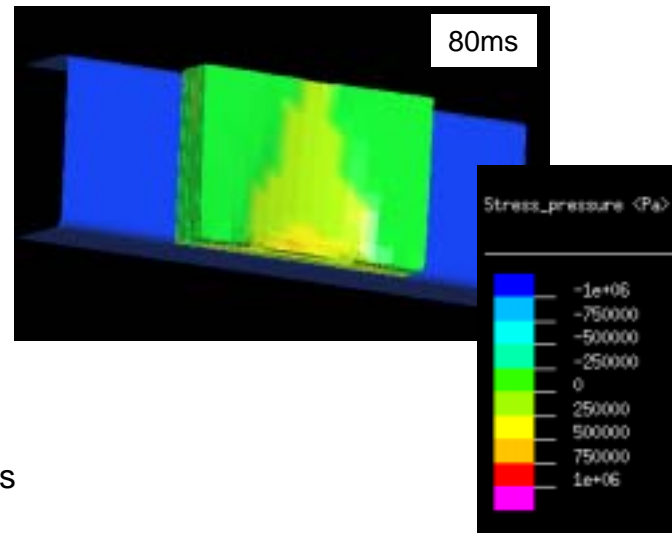
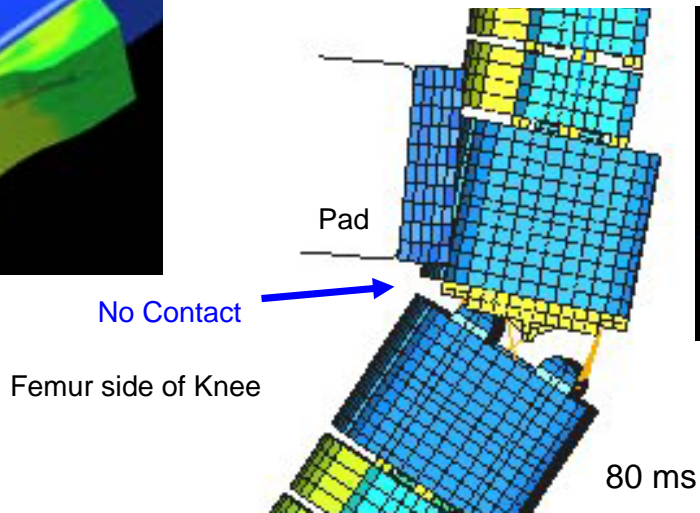
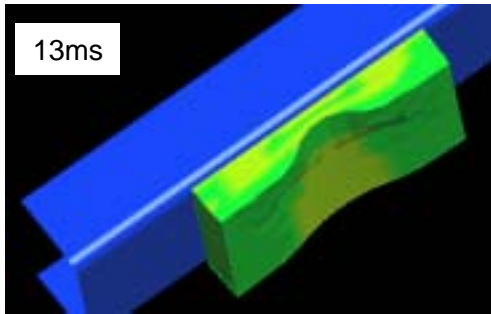
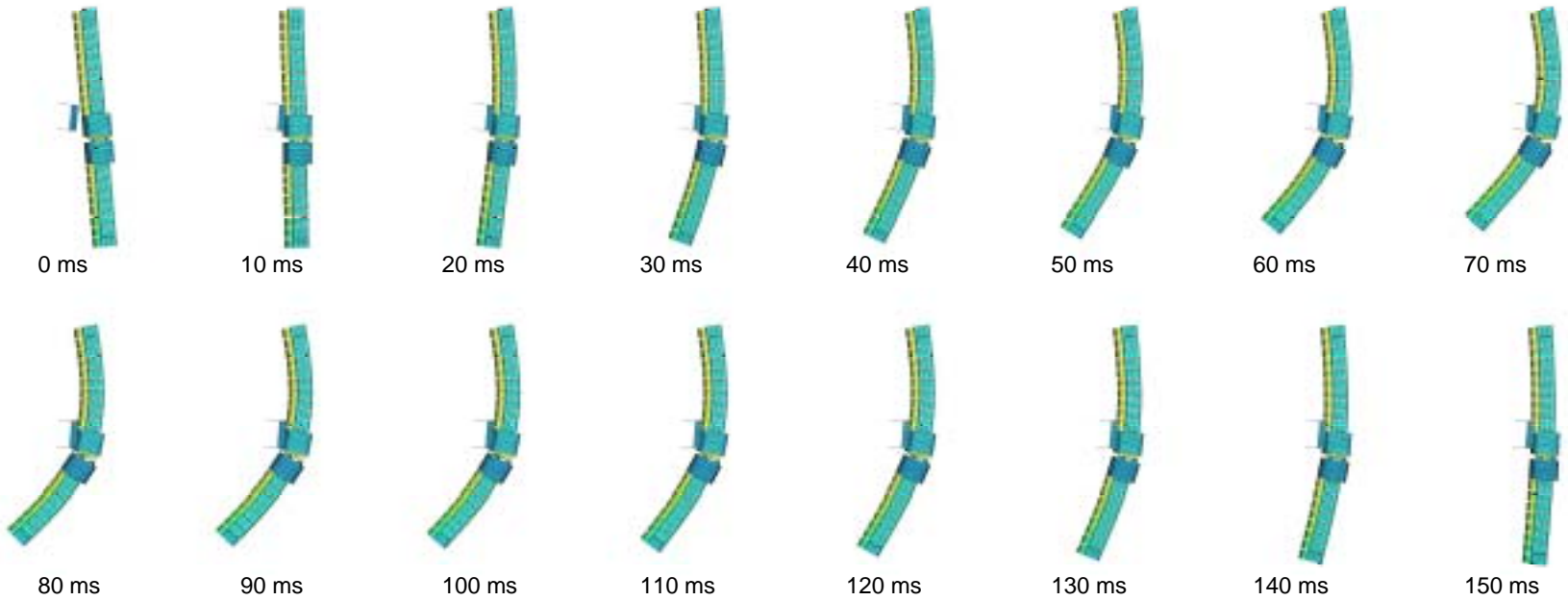
Type A-2-PAD5-8 (12 deg.)



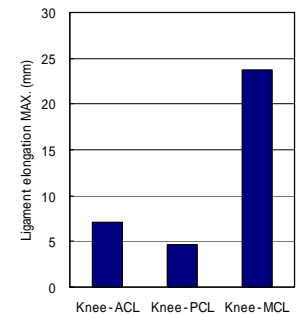
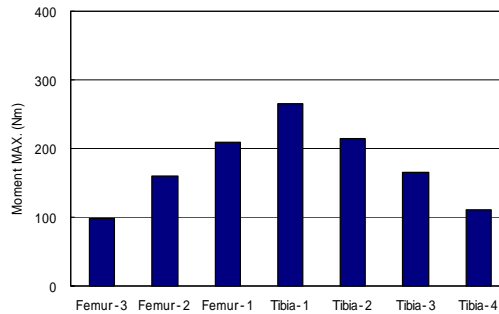
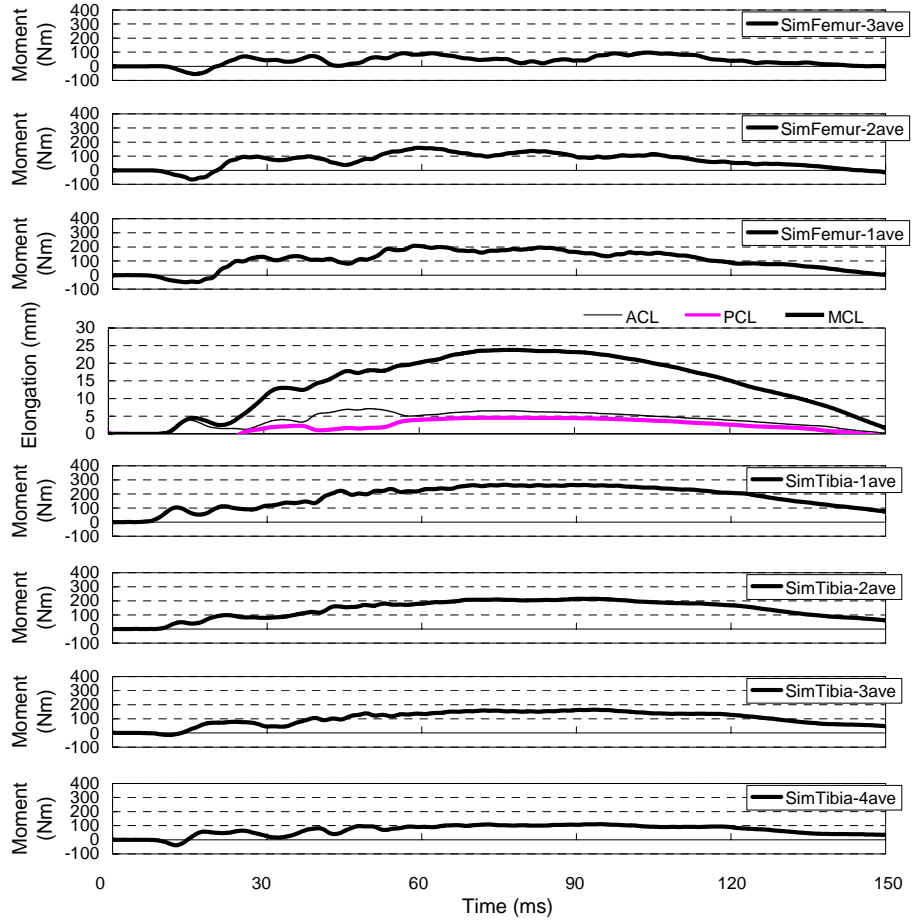
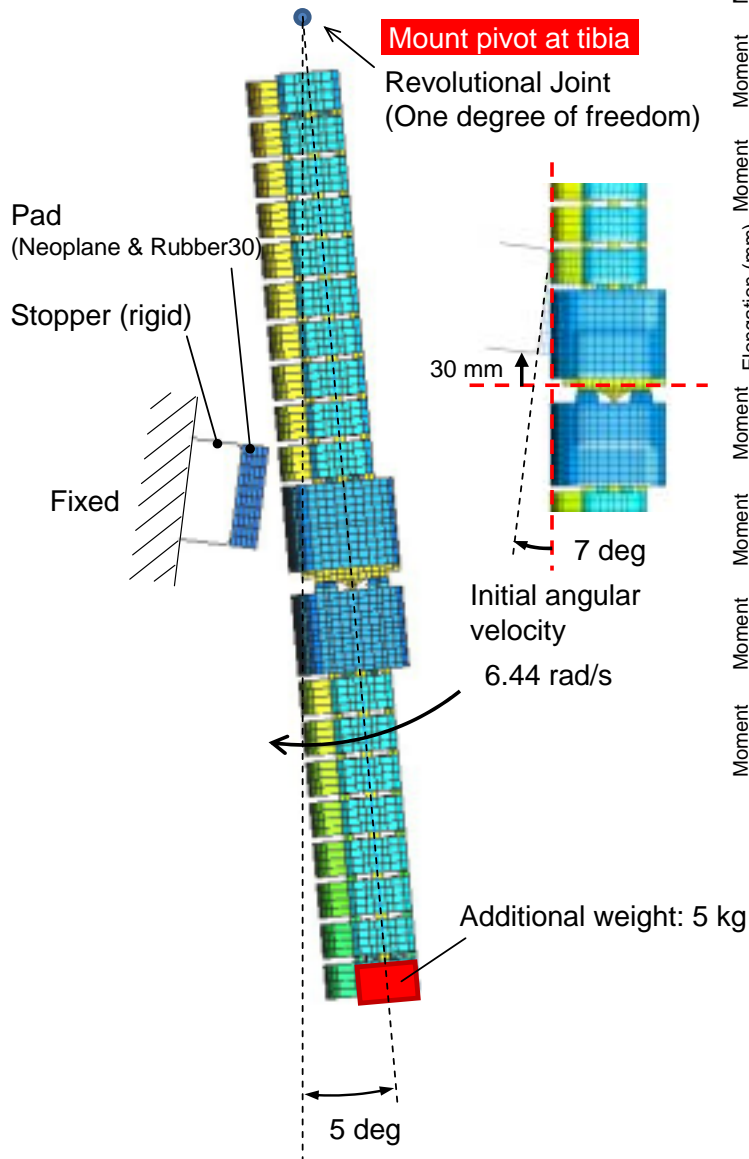
Type A-2-PAD5-5 (5deg.)



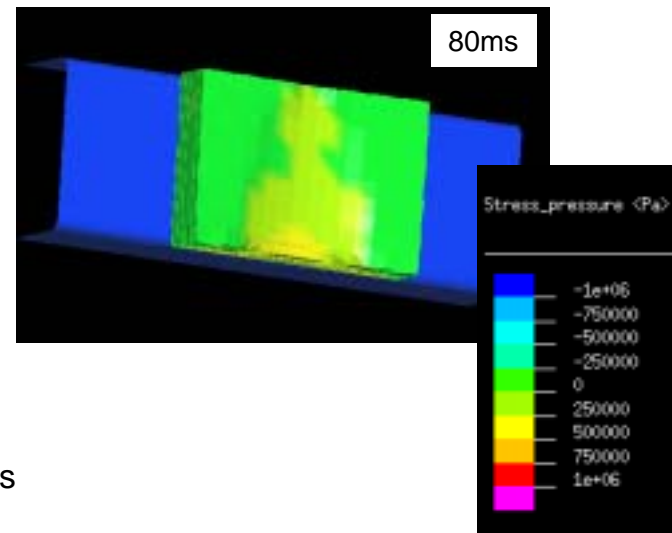
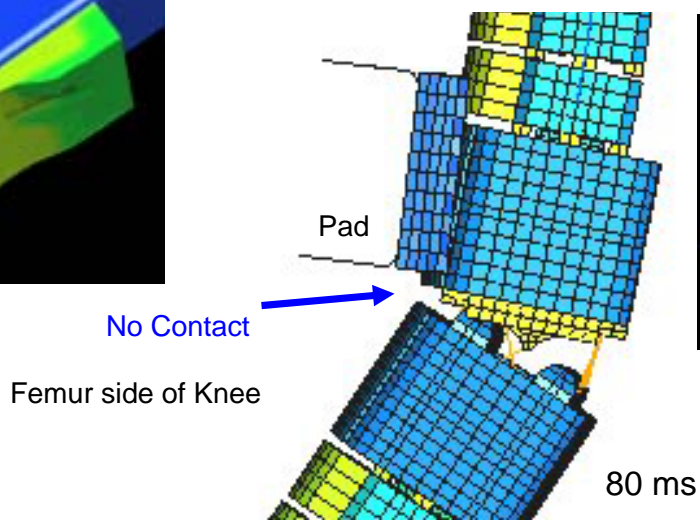
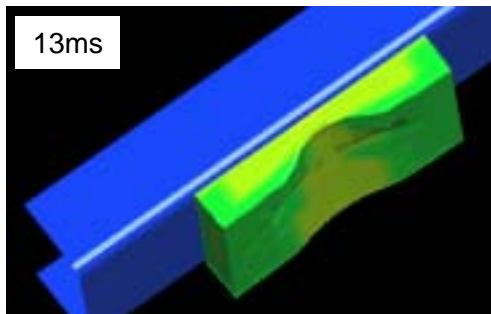
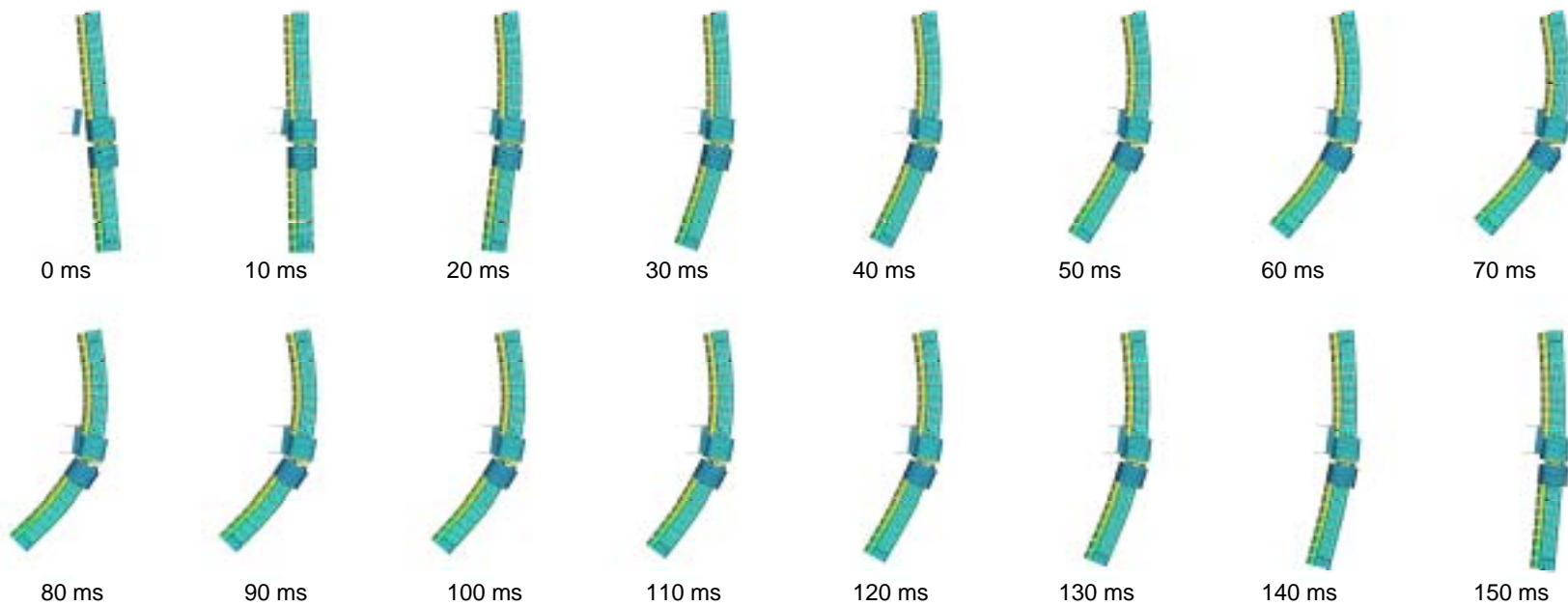
Type A-2-PAD5-5 (5deg.)



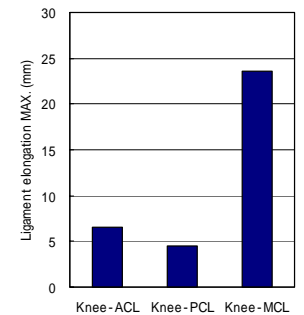
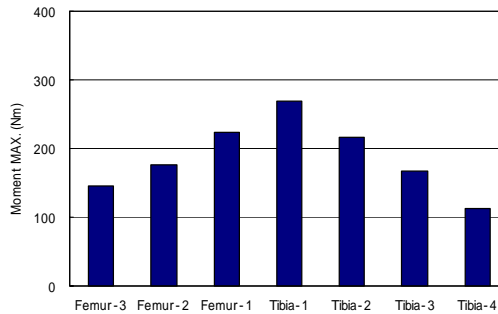
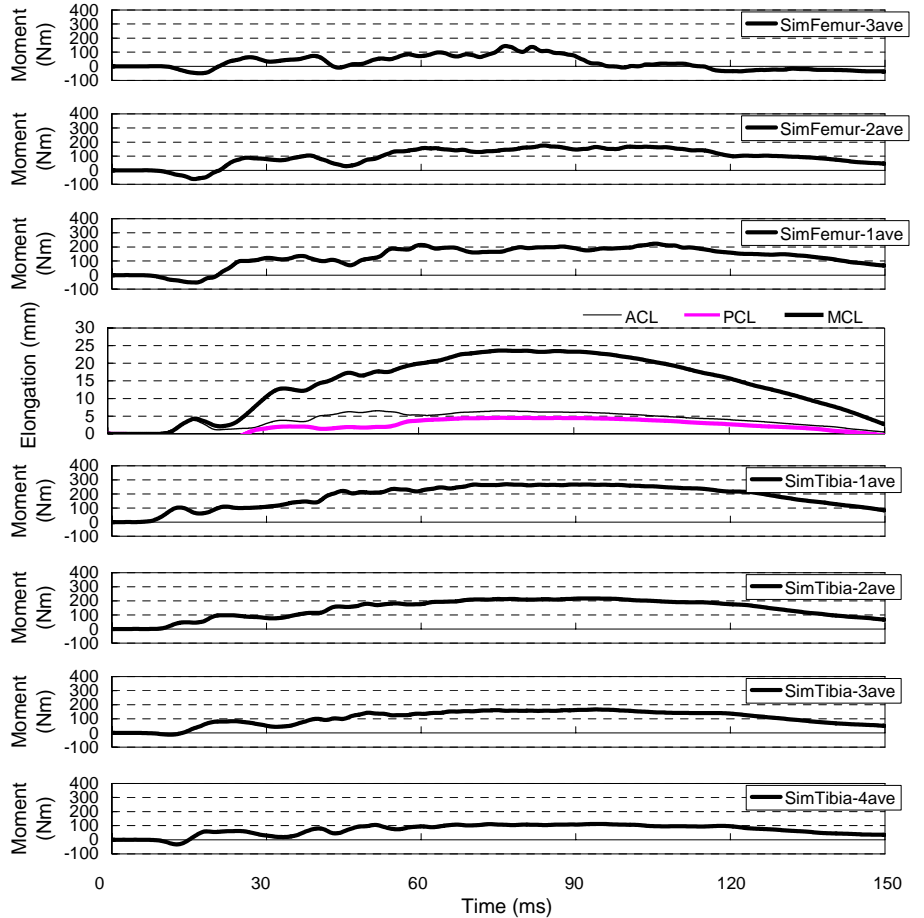
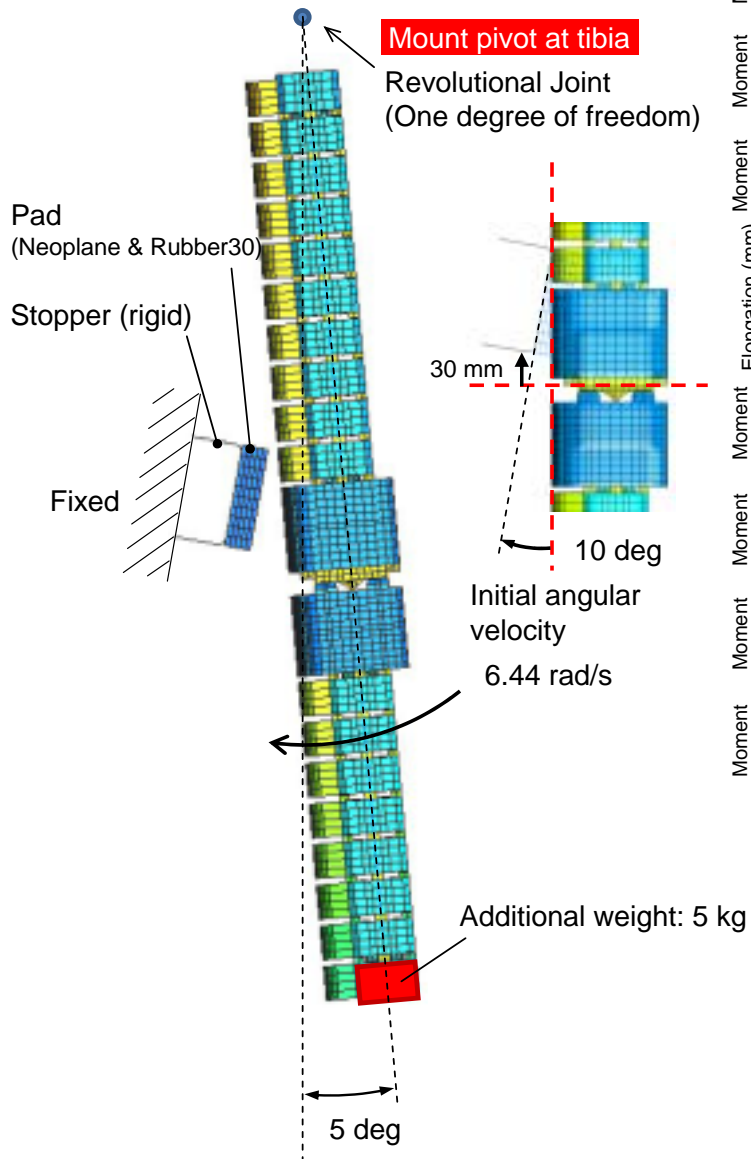
Type A-2-PAD5-6 (7deg.)



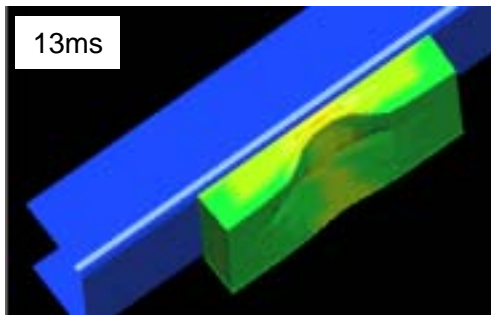
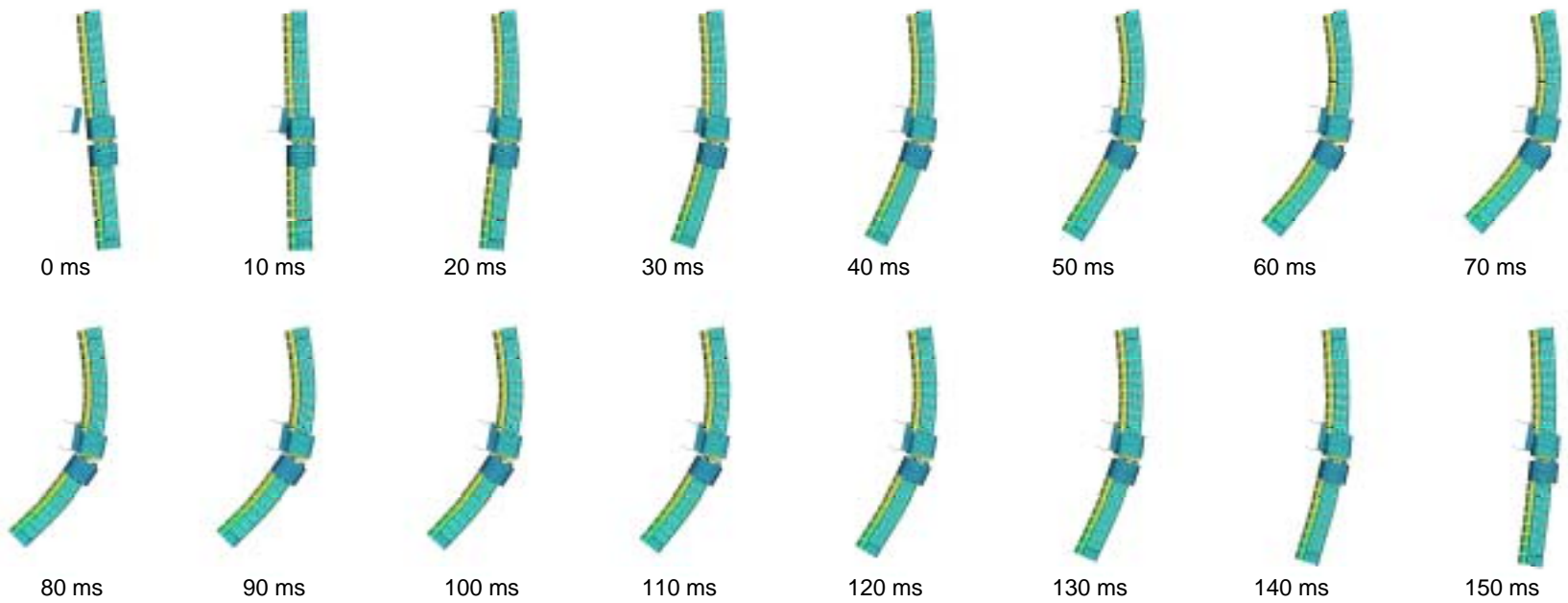
Type A-2-PAD5-6 (7deg.)



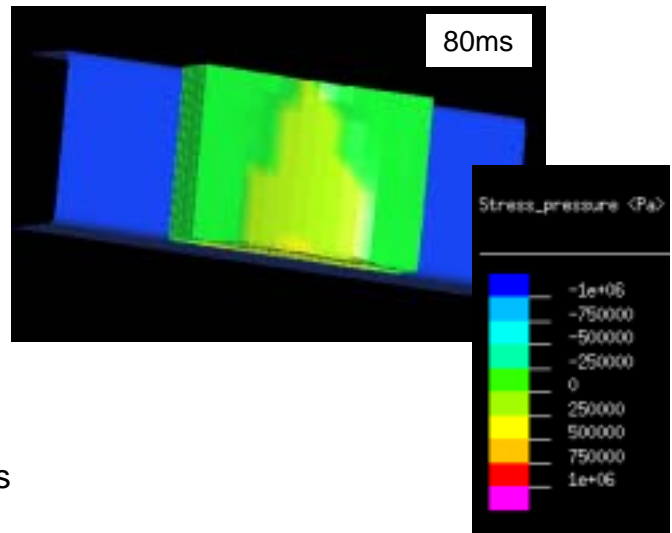
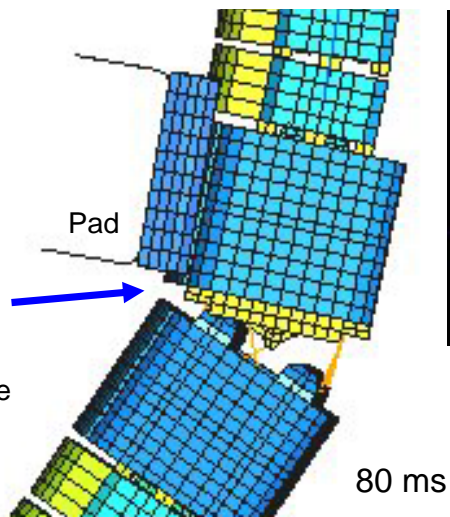
Type A-2-PAD5-7 (10deg.)



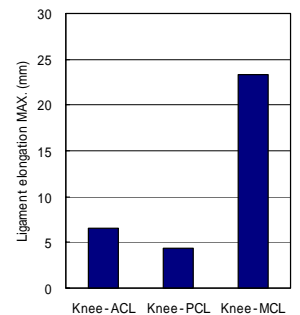
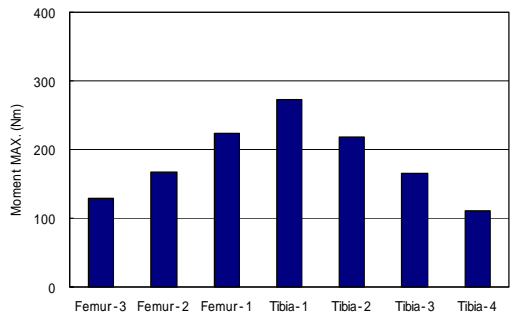
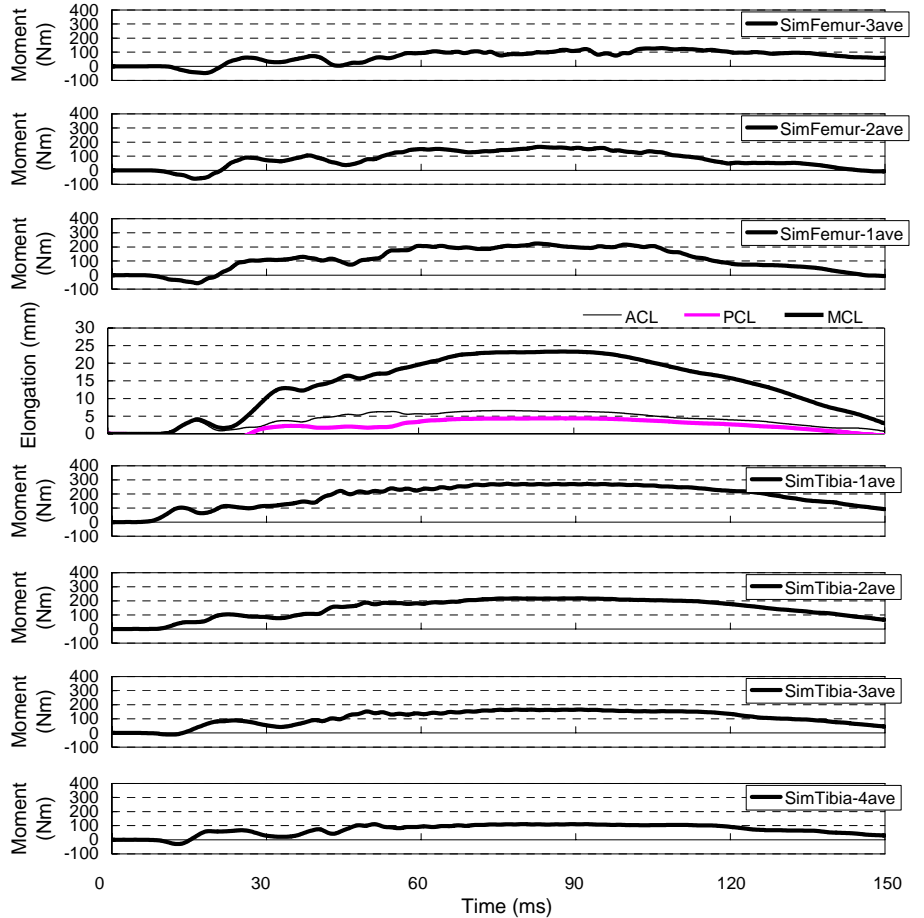
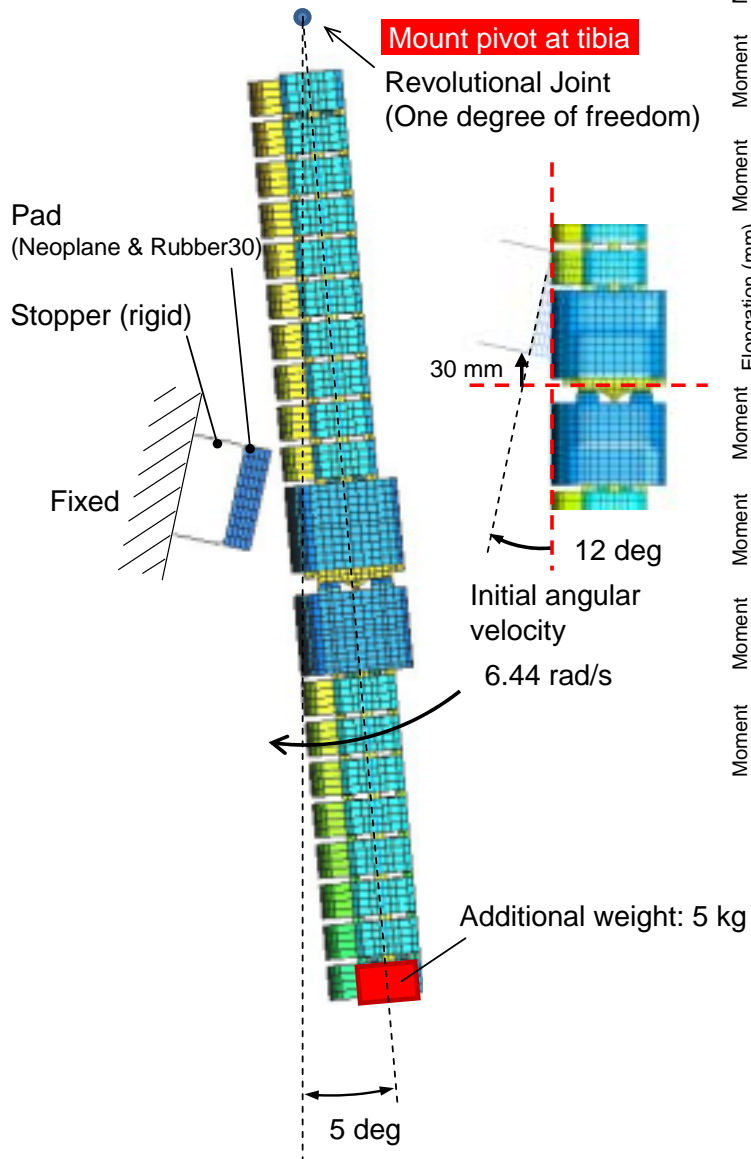
Type A-2-PAD5-7 (10 deg.)



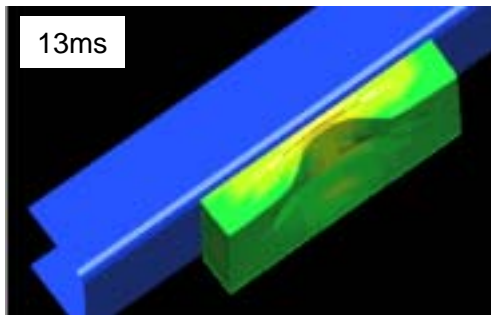
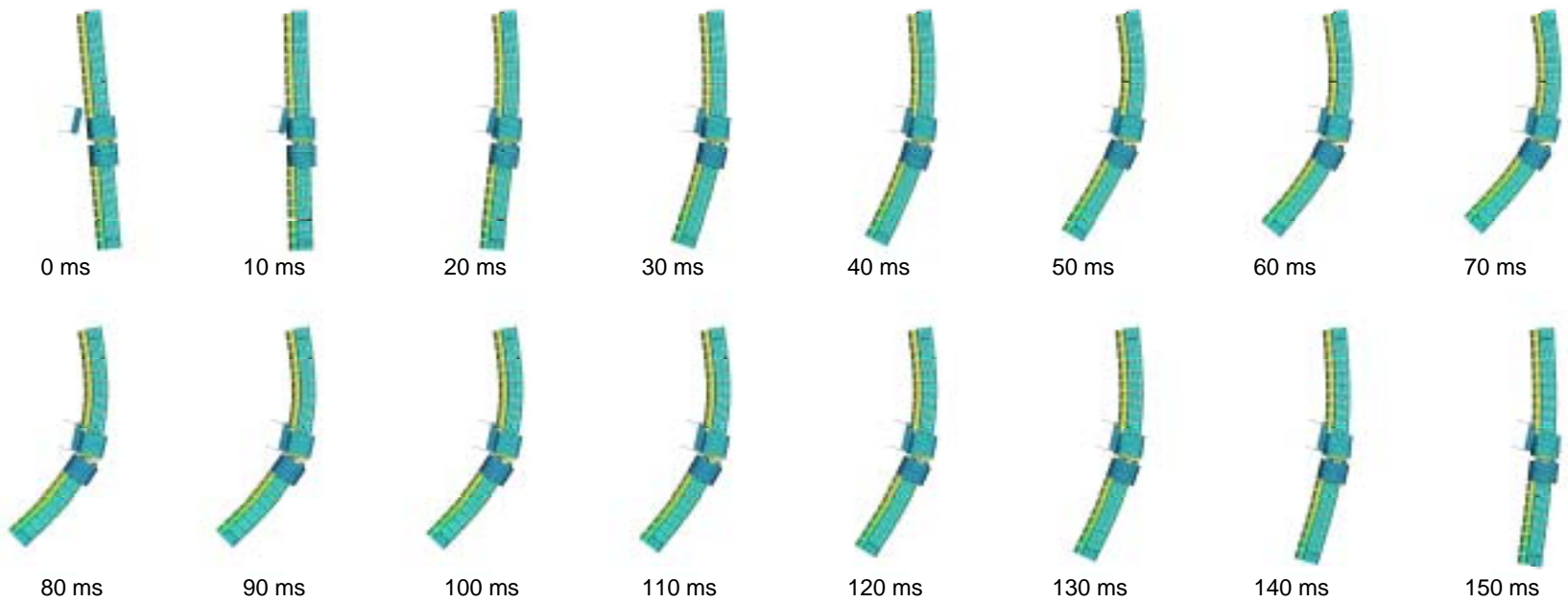
No Contact
Femur side of Knee



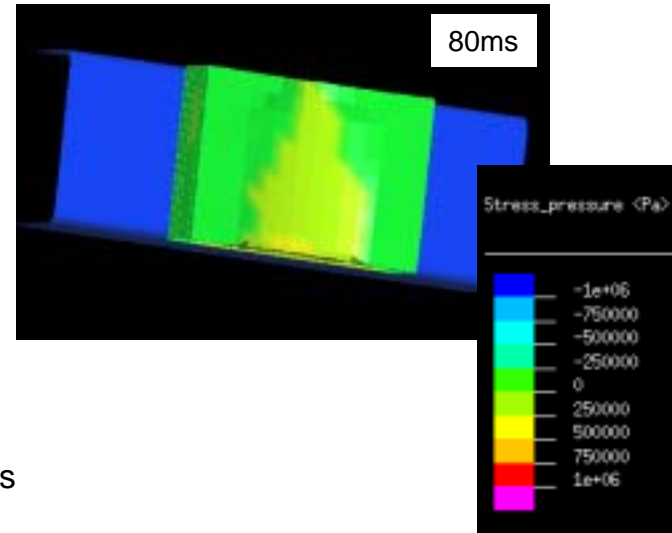
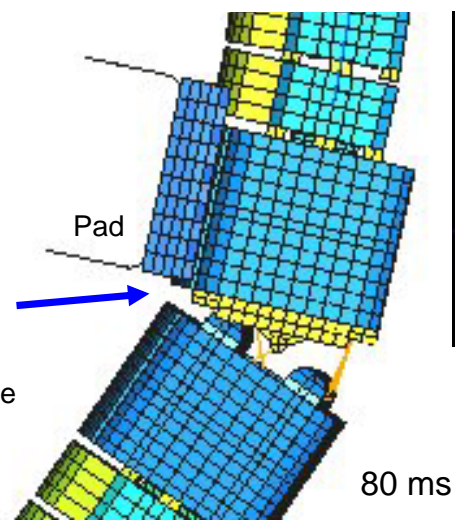
Type A-2-PAD5-8 (12 deg.)



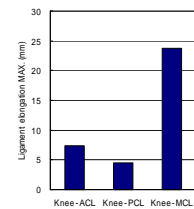
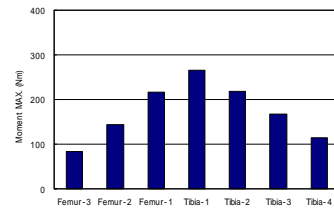
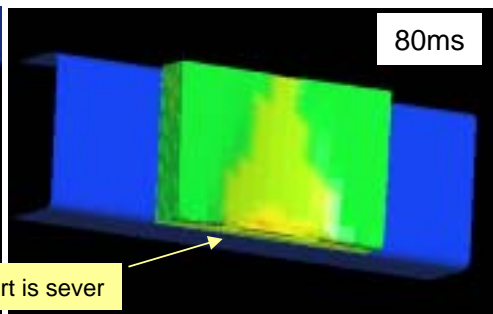
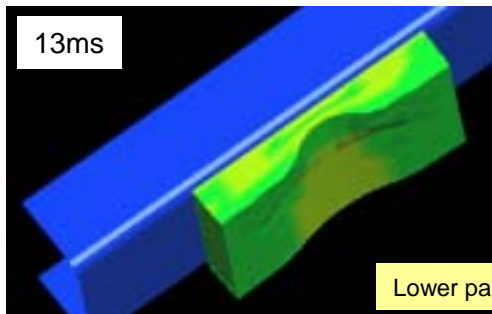
Type A-2-PAD5-8 (12 deg.)



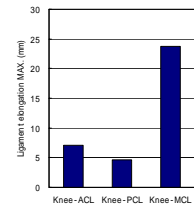
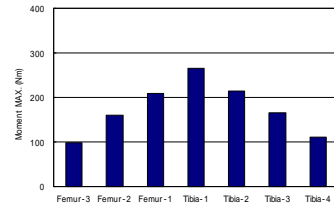
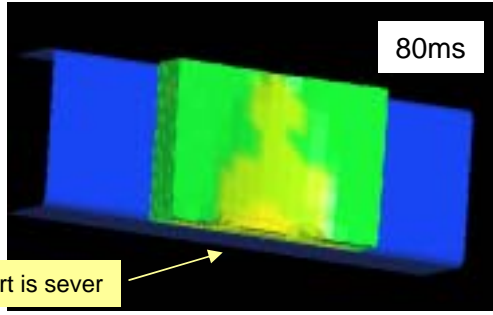
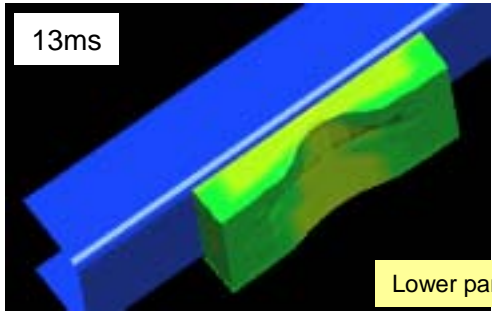
No Contact
Femur side of Knee



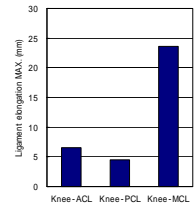
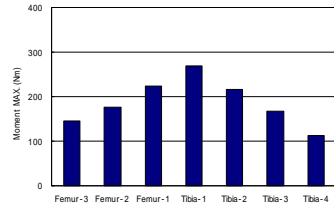
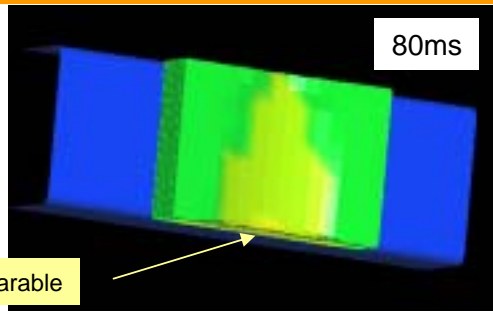
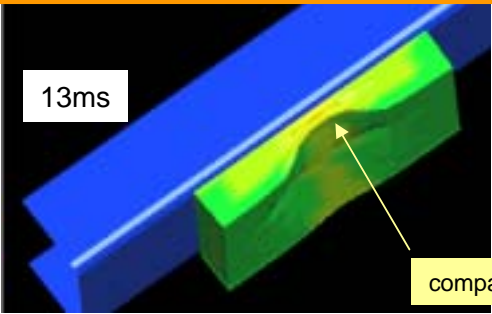
5 deg.



7 deg.



10 deg.



JAMA-JARI recommendation

12 deg.

