

**Information on the  
Flexible Pedestrian Legform Impactor  
GT Alpha (Flex-GT<sub>a</sub>)**

Atsuhiko Konosu  
Flex-TEG Chairperson /Japan

# Background

- At the 2<sup>nd</sup> Flex-TEG meeting, a request is made to increase the knee bending angle limit of Flexible Pedestrian Legform Impactor G (Flex-G).
- Japan addressed the issue, and developed the Flexible Pedestrian Legform Impactor GT Alpha (Flex-GT $\alpha$ ) in March 2006.
- The Flex-GT $\alpha$  is obtained a modified knee bending angle limit, and is also obtained modified specifications to improve injury assessment ability.
- This presentation explains the Flex-GT $\alpha$  specifications.
- Then the other presentation introduces the evaluation methodologies and results concerning the injury assessment ability of Flex-GT $\alpha$ .

**General**

# Basic Structure

Flex-G

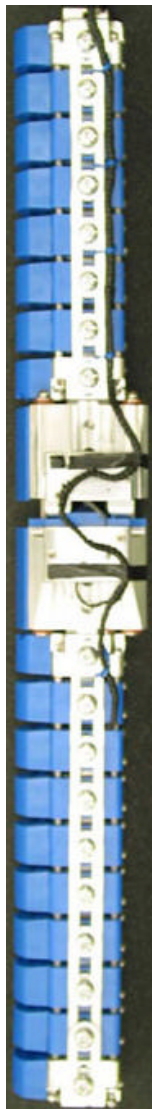


Thigh flexible bending

Knee flexible bending with ligament restraint system

Leg flexible bending

Flex-GT $\alpha$



Thigh flexible bending

Knee flexible bending with ligament restraint system

Leg flexible bending

Basic structure is the same.

# Length, C.G. Location, and Mass

## Thigh and Leg

Length, C.G. Location, and Mass	50th percentile of American Males*	Flex-GT $\alpha$ ***	Flex-G
a) Thigh length (mm)	428	433	433
b) Leg length (mm)	493	495	495
c) C.G. location of thigh (mm) **	218	189	213
d) C.G. location of leg (mm) **	233	197	225
e) Total legform impactor mass (kg)	13.4	12.4	13.9
f) Thigh mass (kg)	8.6	6.7	8.6
g) Leg mass (kg)	4.8	5.7	5.3

\* Robbins, D.H. ' Anthropometry of Motor Vehicle Occupants, Volume 2' NHTSA Contract DTNH22-80-C-07502 Pub. 1985.

\*\* From the knee joint center

\*\*\* Prototype (estimated values)

Flex-GT $\alpha$  differs slightly from the 50th percentile American male in thigh/leg lengths, C.G. locations and mass.

→These differences give Flex-GT $\alpha$  a better injury assessment ability than that of Flex-G.

# Long Bones

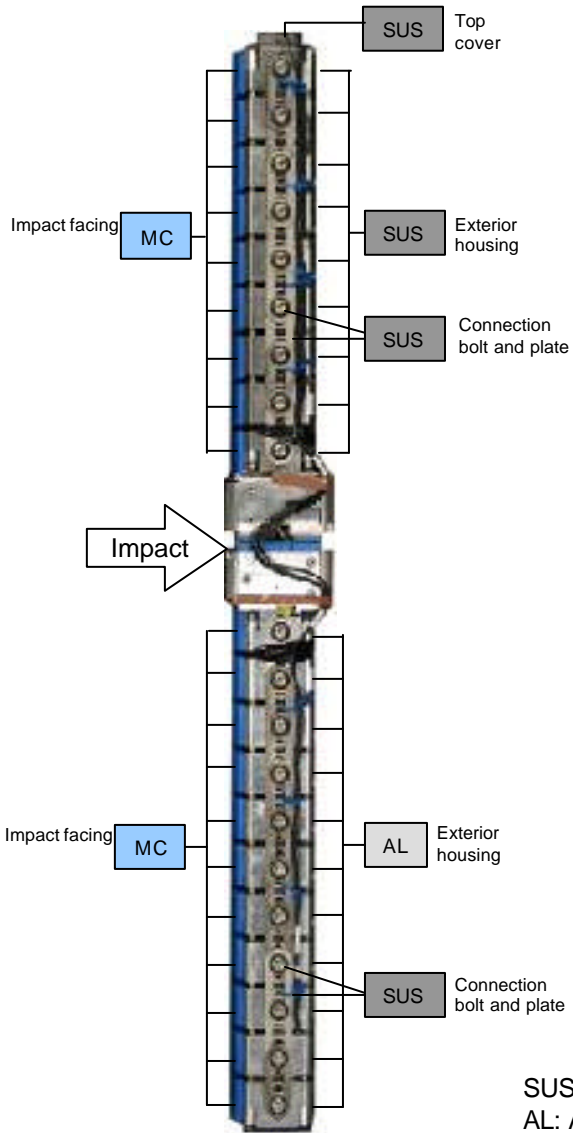
# Long Bones

## Materials

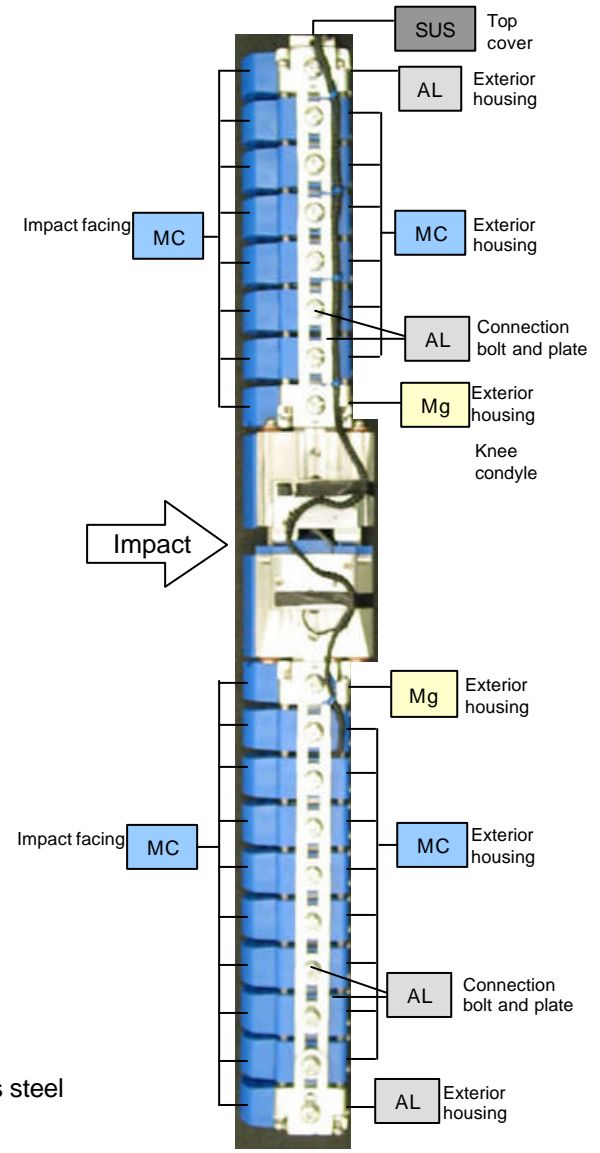
Flex-GT $\alpha$  uses different material for long bones as compared with that of Flex-G.

→To make the long bones lighter

### Flex-G



### Flex-GT $\alpha$



SUS: Stainless steel  
AL: Aluminum  
MC: MC-nylon

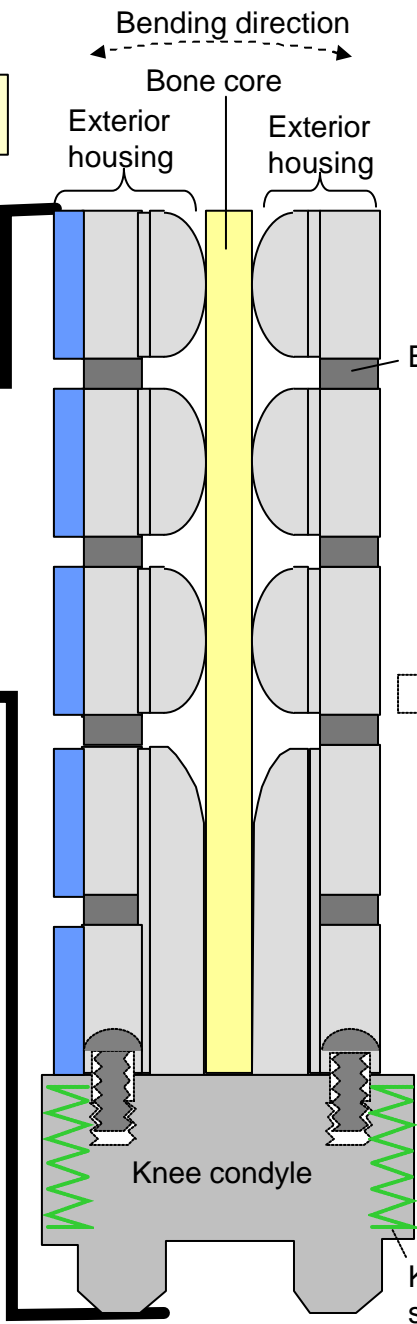
# Long Bones

Bone and knee condyle connection

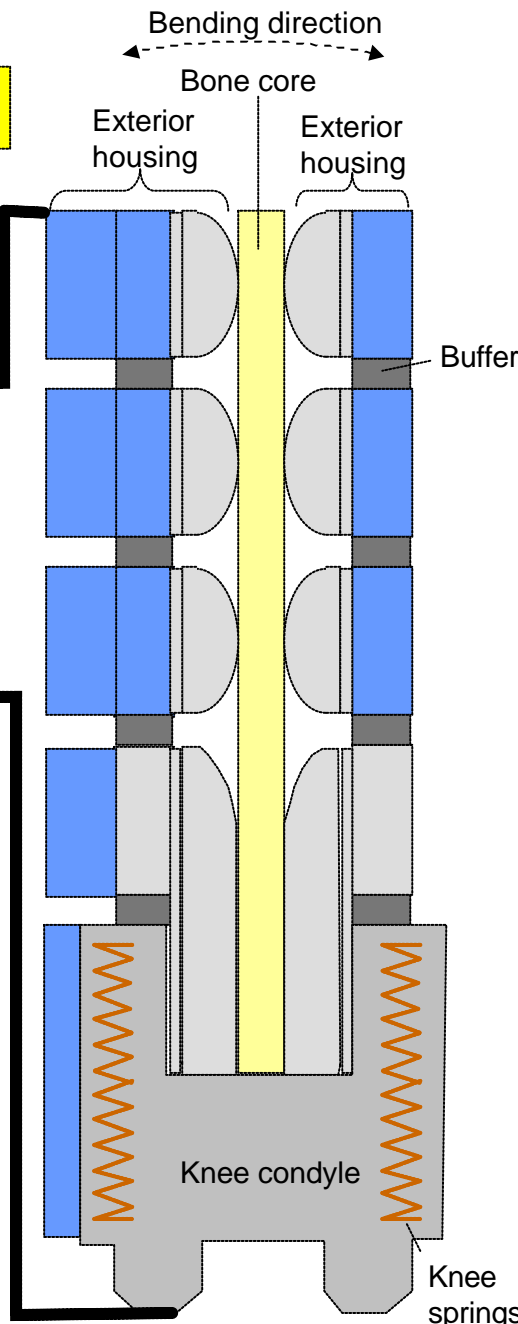
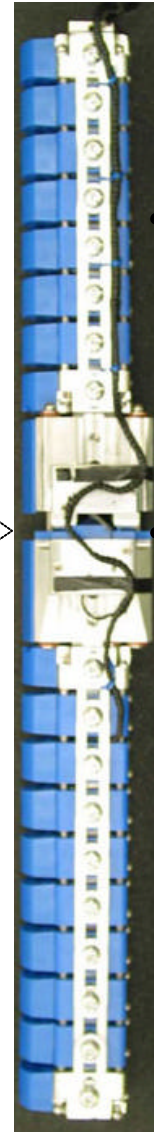
Flex-GT $\alpha$  connects the long bone and the knee condyle differently from the connection in Flex-G.

→To install longer knee springs at the knee condyle

Flex-G



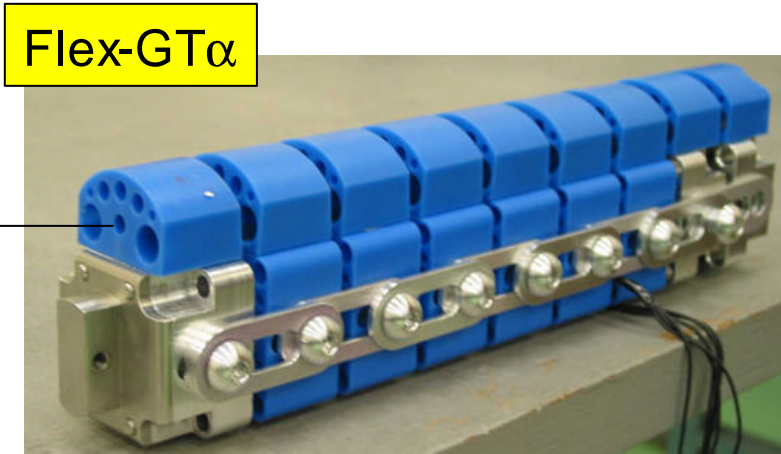
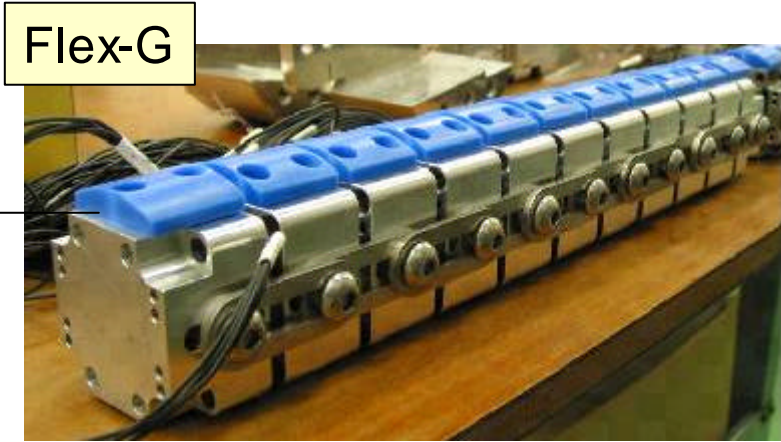
Flex-GT $\alpha$





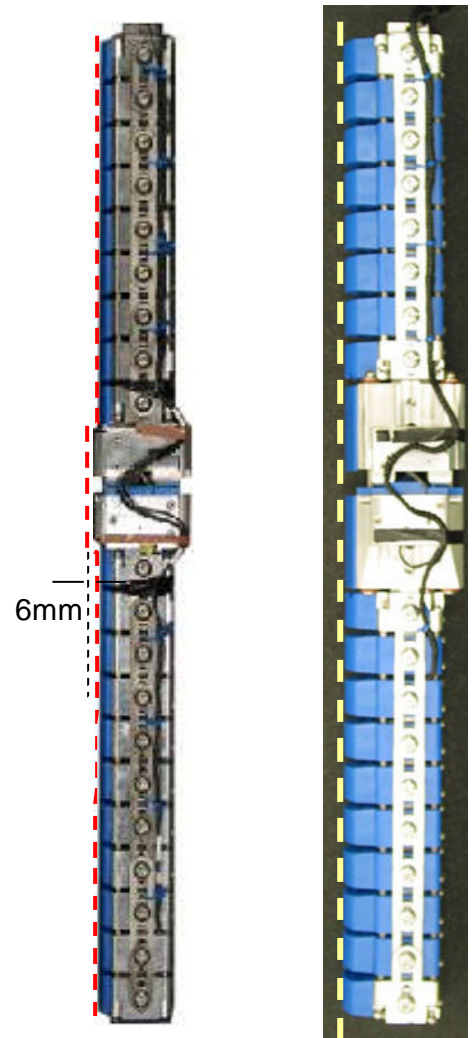
# Long Bones

Impact facing



Flex-G

Flex-GTα



Flex-GTα has a thicker impact facing as compared with that of Flex-G.

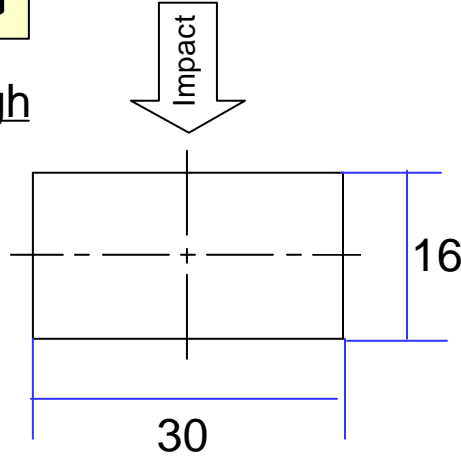
→ To align the impact facing with the knee

# Long Bones

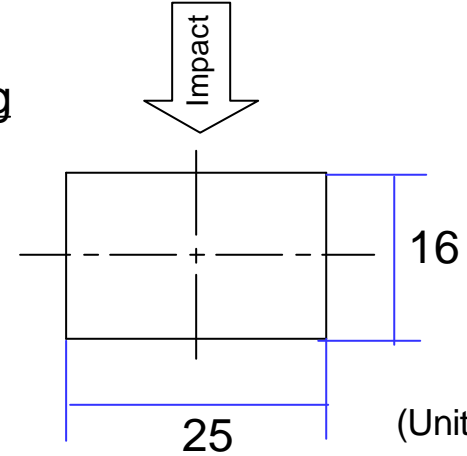
Sectional dimensions of bone core

Flex-G

Thigh



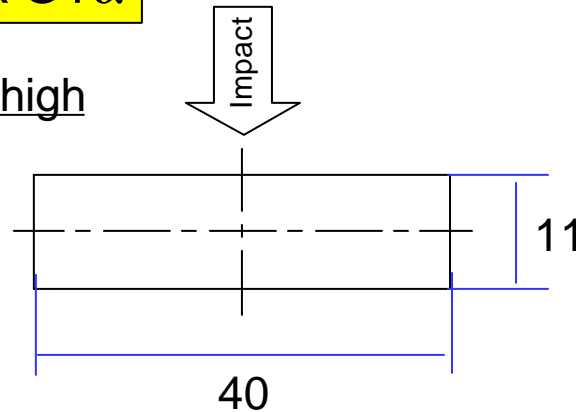
Leg



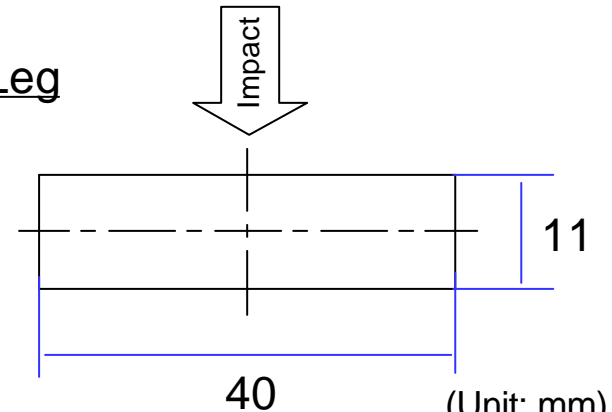
(Unit: mm)  
Sectional image

Flex-GT $\alpha$

Thigh



Leg



(Unit: mm)  
Sectional image

Flex-GT $\alpha$  has a thinner and wider bone core as compared with that of Flex-G. (Long bones of Flex-GT $\alpha$  has smaller bending stiffness as compared with that of Flex-G).

→ The difference gives Flex-GT $\alpha$  a better injury assessment ability than that of Flex-G.

# Long Bones

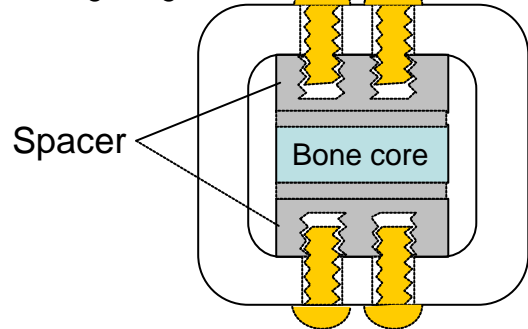
Bone core binding method

**Flex-G**

Spacer method



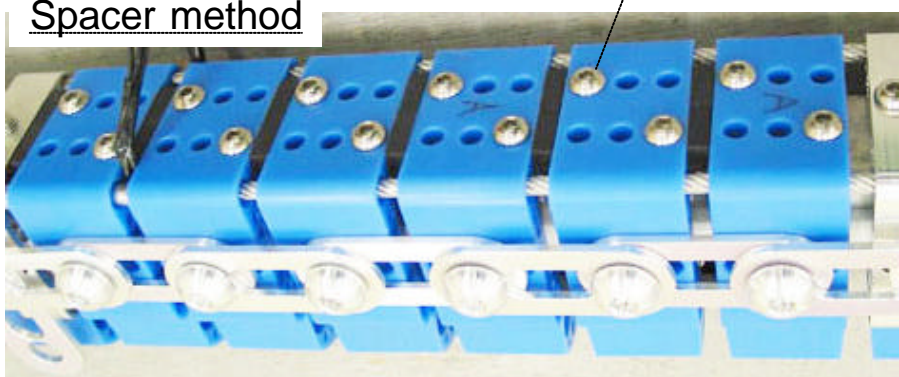
Binding image



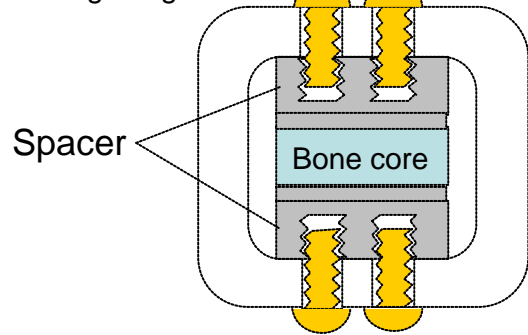
No bone core binding by screw.  
(Just keep the spacers in position.)

**Flex-GT $\alpha$**

Spacer method



Binding image



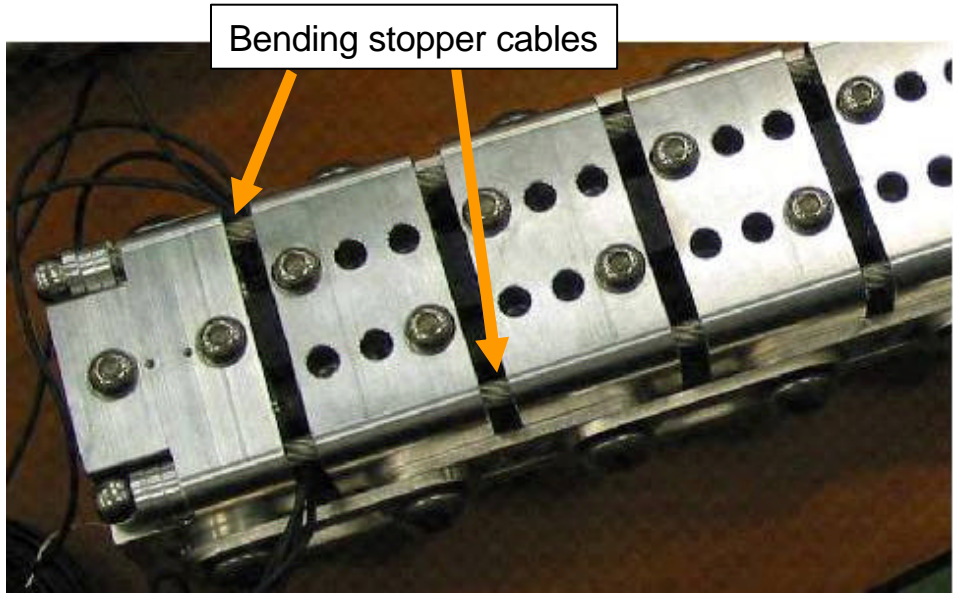
No bone core binding by screw.  
(Just keep the spacers in position.)

**Flex-GT $\alpha$  uses the same bone core binding method as Flex-G.**

# Long Bones

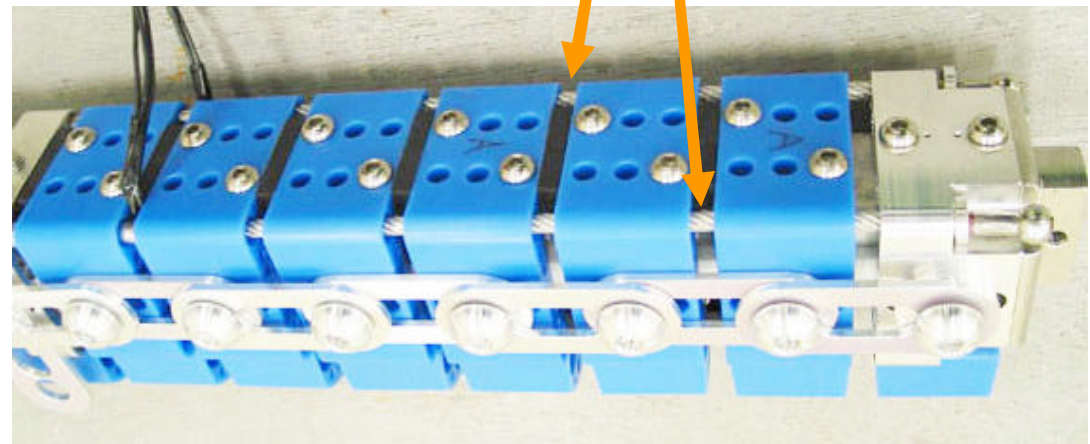
Bending  
stopper cables

Flex-G



Flex-GT $\alpha$

Bending stopper cables



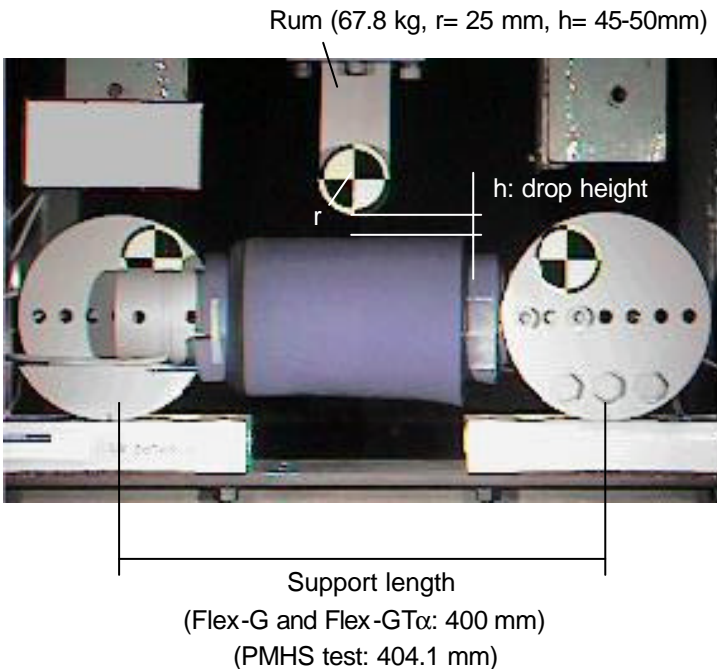
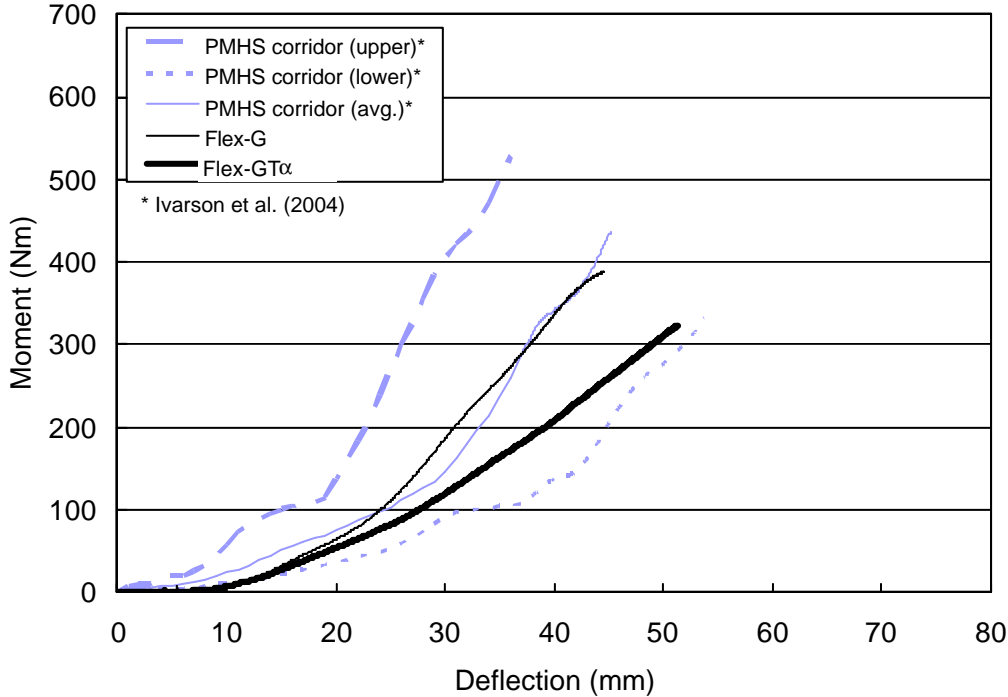
Flex-GT $\alpha$  has the same bending stopper cables as those of Flex-G.



# Long Bones

## Bending characteristics (Thigh)

### Flex-G and Flex-GT $\alpha$



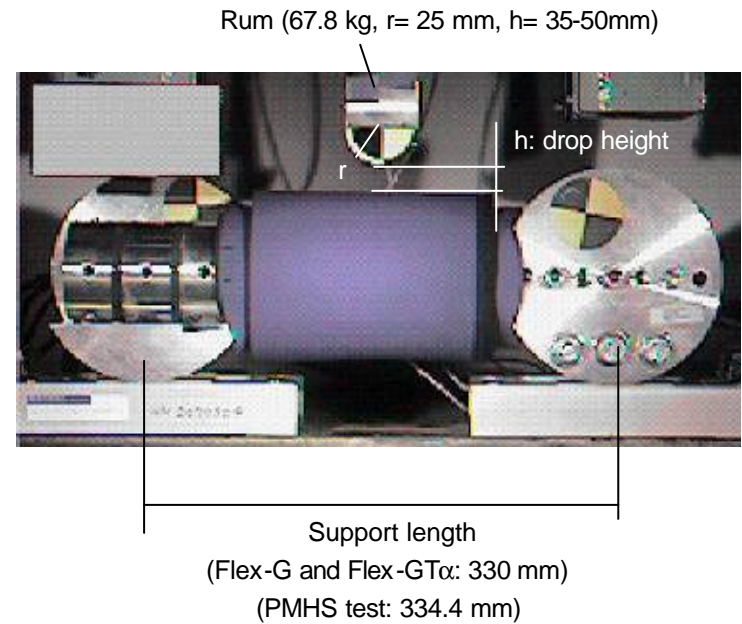
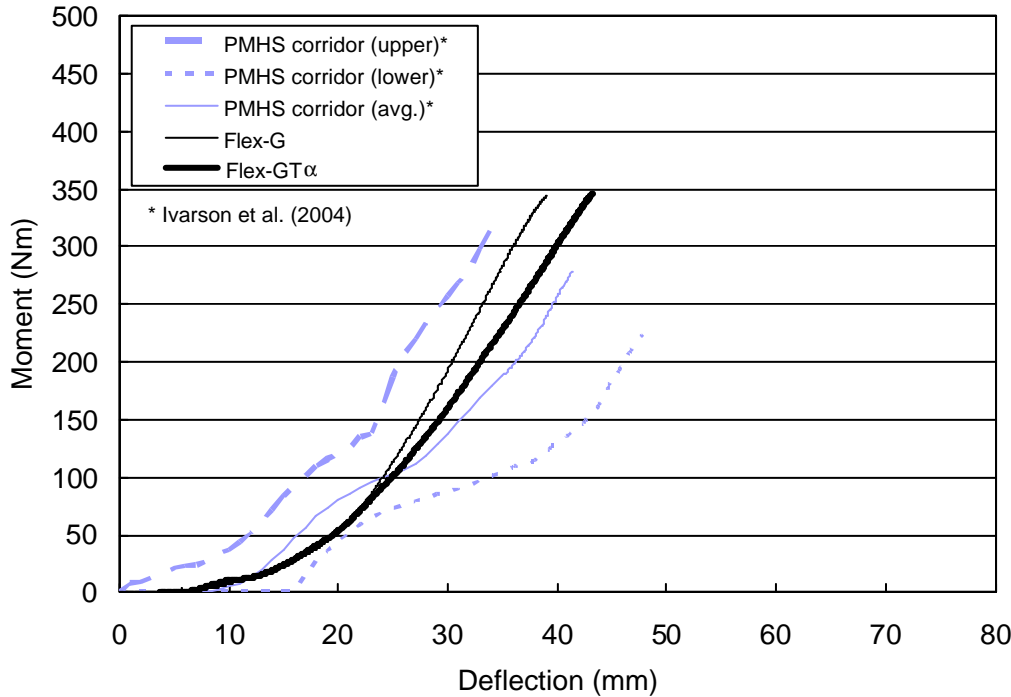
Flex-GT $\alpha$  (Thigh) has slightly smaller bending stiffness than that of Flex-G.

→ The difference gives Flex-GT $\alpha$  a better injury assessment ability than that of Flex-G.

# Long Bones

## Bending characteristics (Leg)

### Flex-G and Flex-GT $\alpha$



Flex-GT $\alpha$  (Leg) has slightly smaller bending stiffness than that of Flex-G.

→ The difference gives Flex-GT $\alpha$  a better injury assessment ability than that of Flex-G.

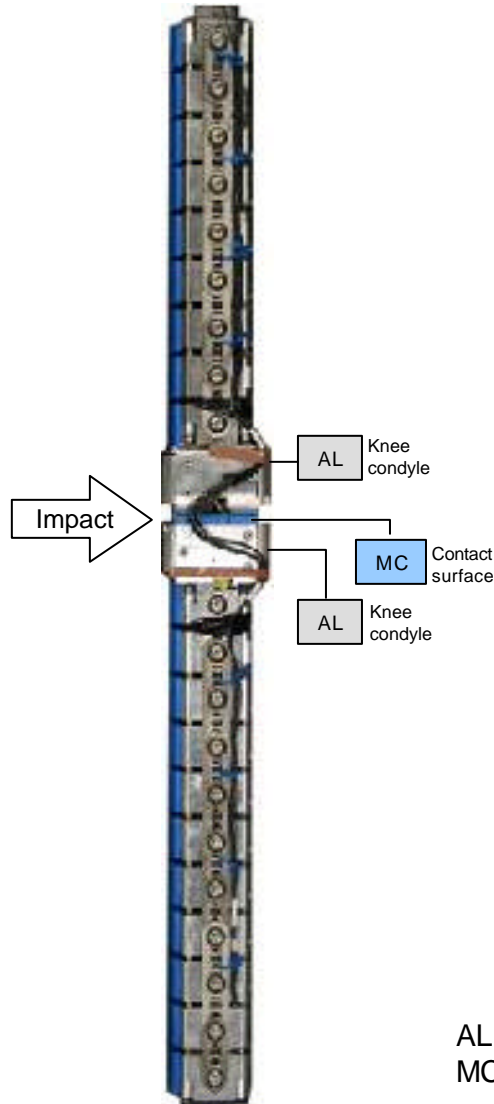
**Knee**

# Knee

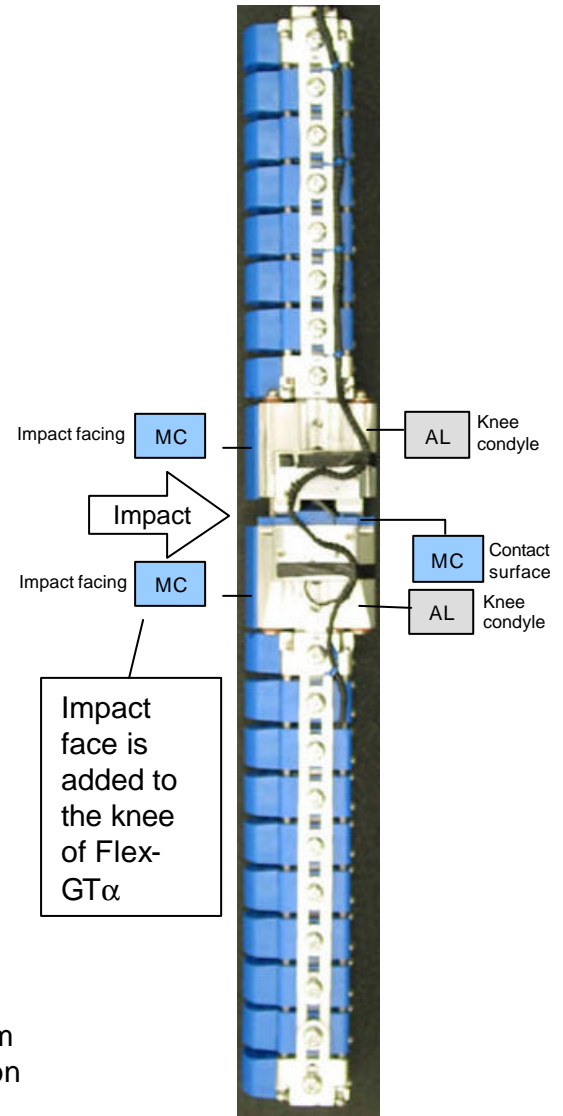
## Materials

Flex-GT $\alpha$  basically uses the same knee material as that of Flex-G.

Flex-G



Flex-GT $\alpha$



AL: Aluminum  
MC: MC-nylon

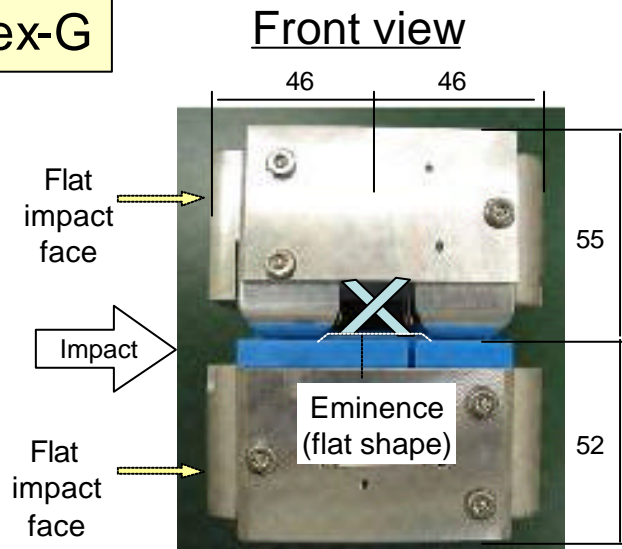


# Knee

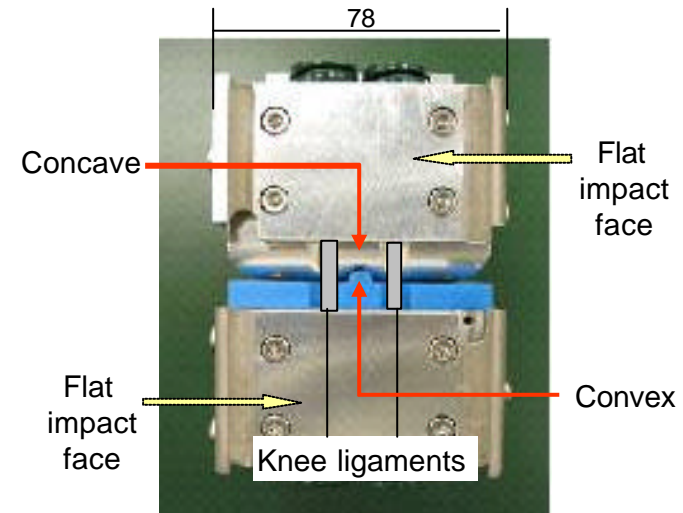
## Size and design

Flex-GT $\alpha$  has different knee size and different designs as compared with those of Flex-G.

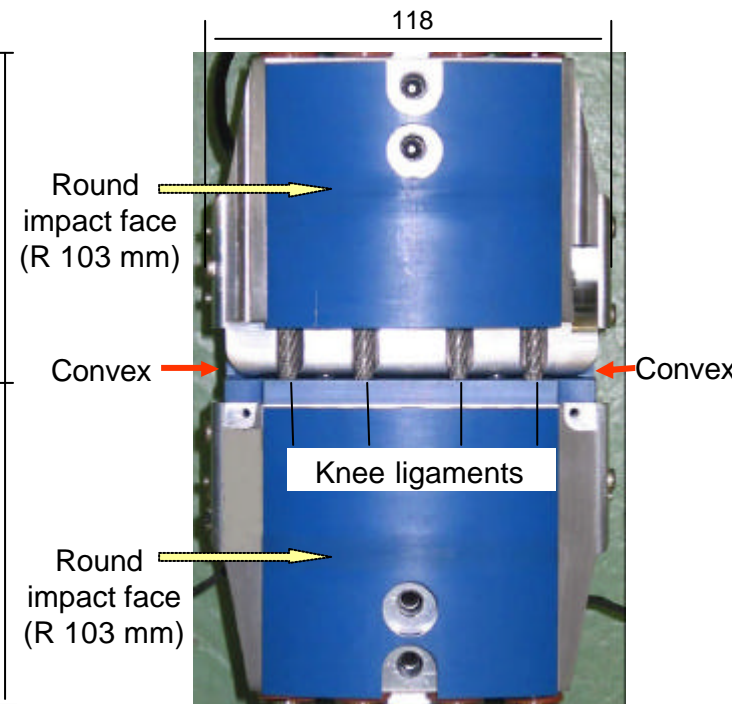
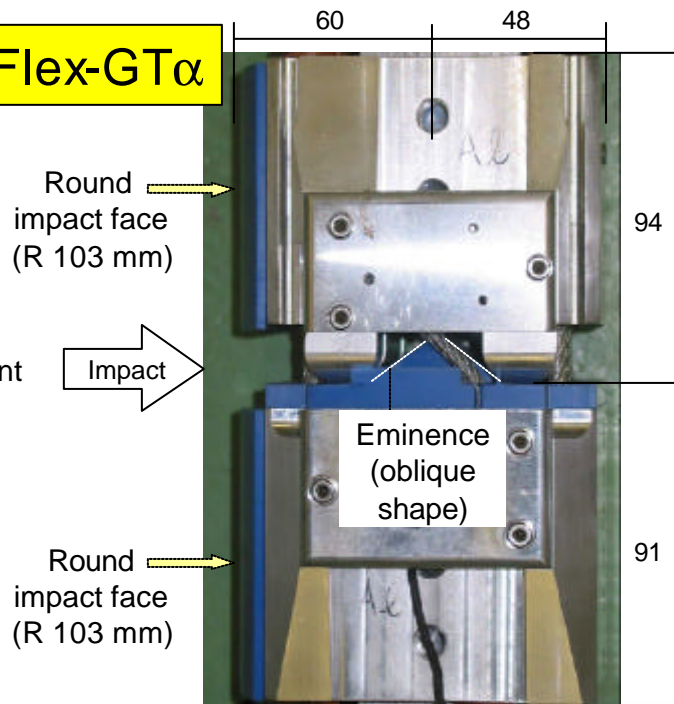
### Flex-G



### Side view



### Flex-GT $\alpha$



Size

→ To install longer springs

Round impact face

→ Smooth impact with car

Eminence (oblique shape)

→ Smooth condyle movement

Convex position

→ Changed its positions

# Knee

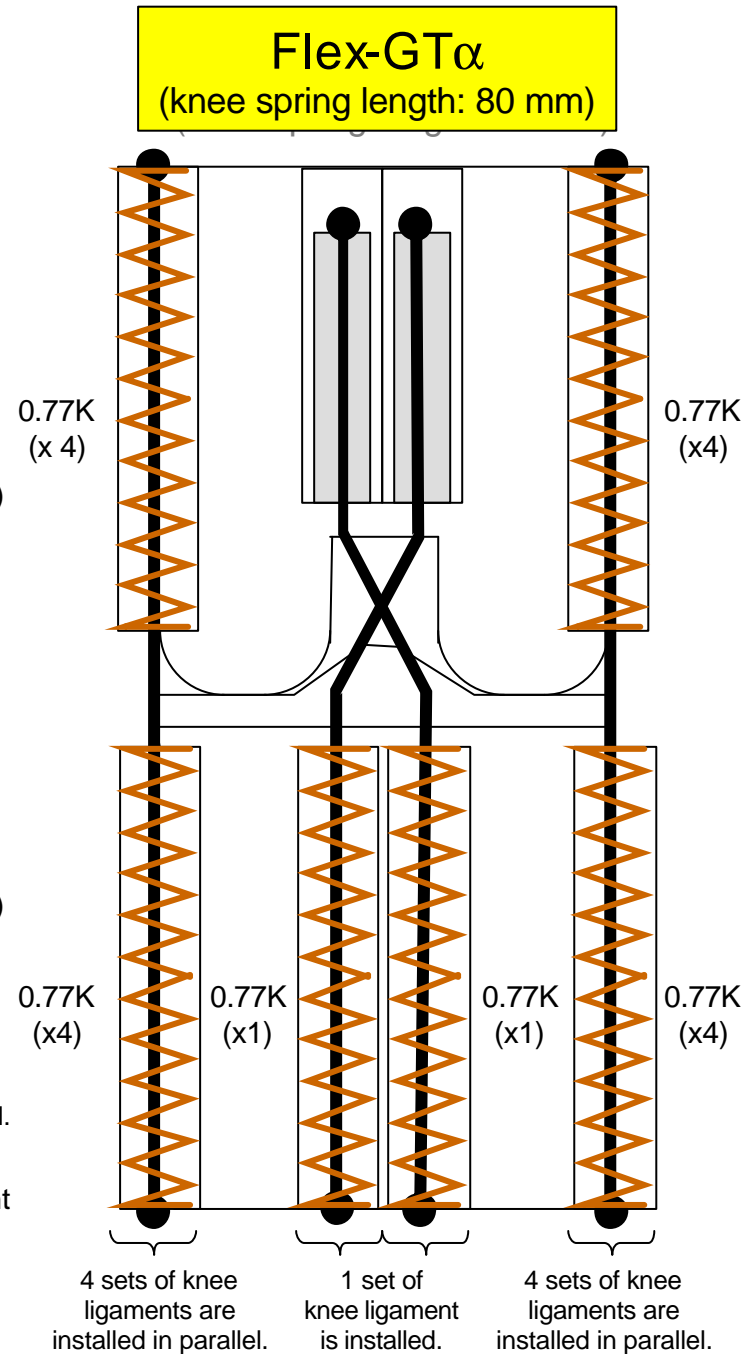
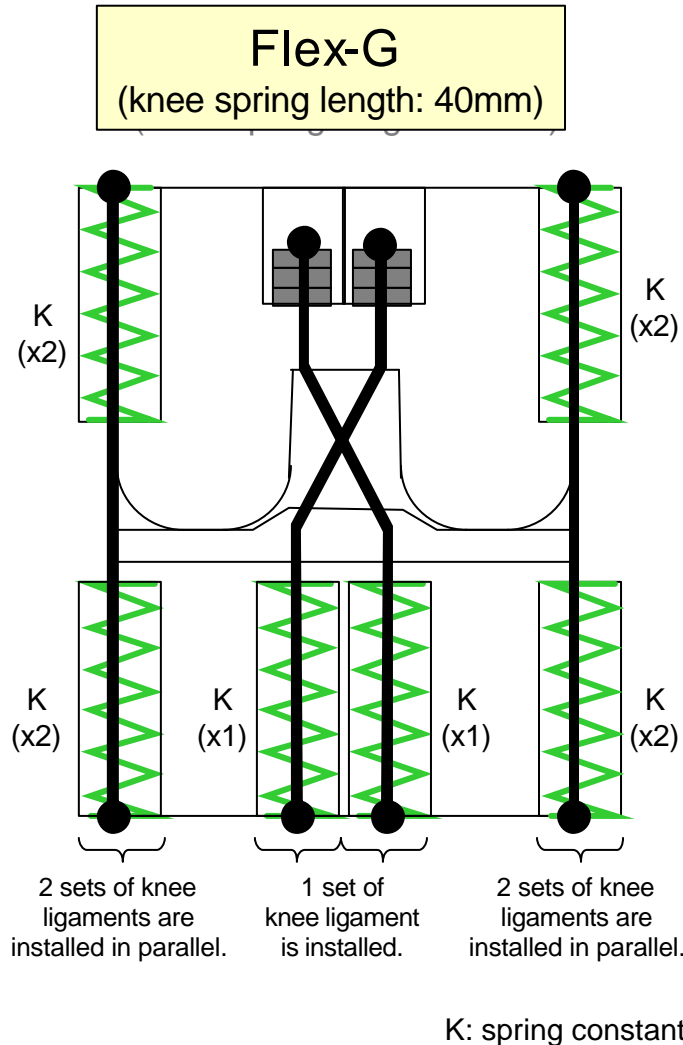
## Knee ligaments

Flex-GT $\alpha$  has different knee ligaments as compare with those of Flex-G

Longer springs  
→ To increase the maximum knee bending angle

Spring constant  
→ Longer springs tend to have small number of spring constant

Number of knee ligaments  
→ To do not weaken Flex-GT $\alpha$  knee bending stiffness

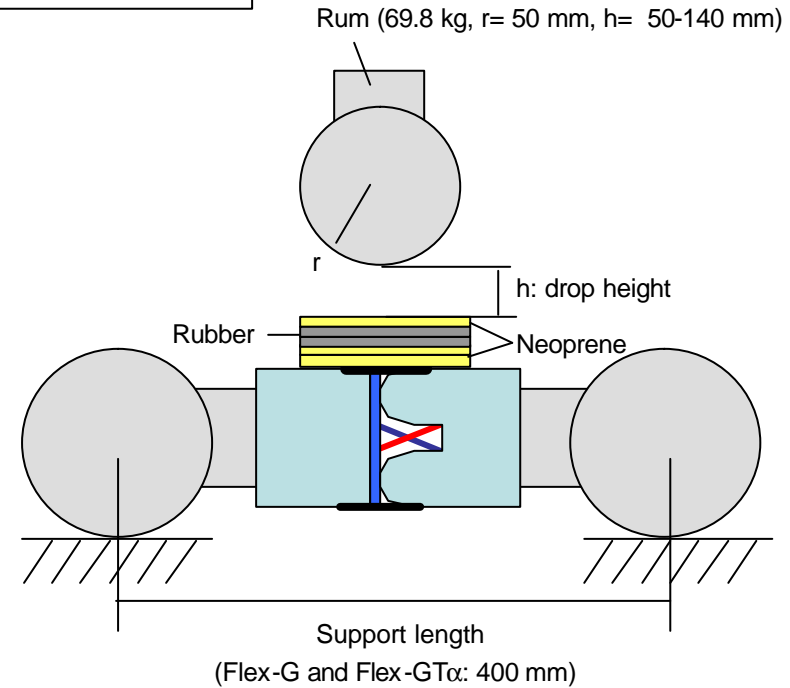
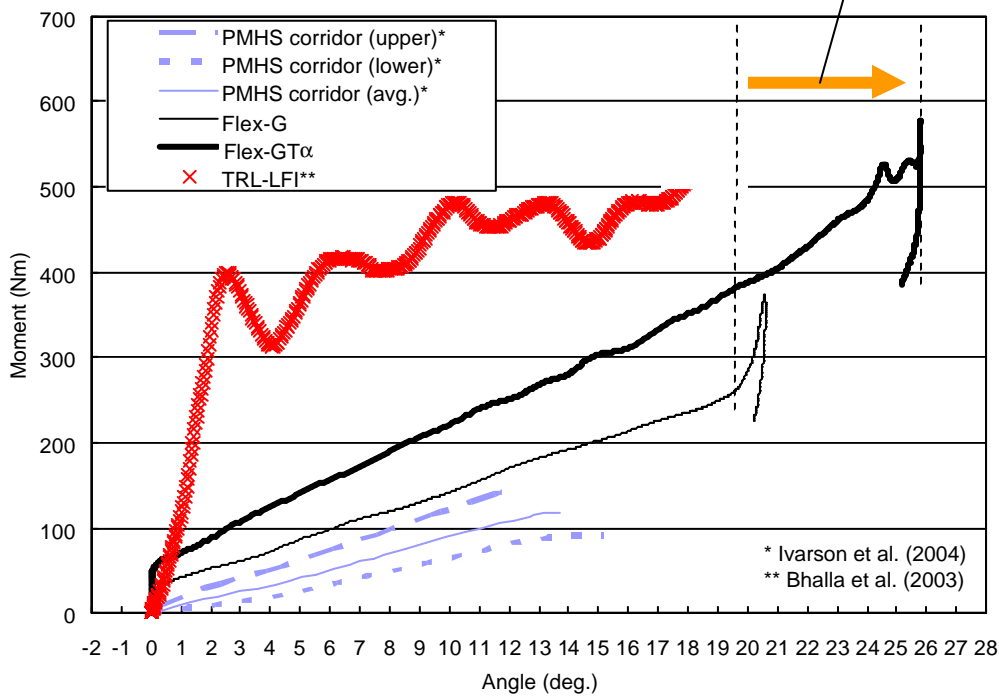


# Knee

## Bending characteristics (Knee)

Flex-G, Flex-GT $\alpha$ , and TRL-LFI

Improved knee bending limit (+30%)



Flex-GT $\alpha$  (Knee) has slightly greater bending stiffness than that of Flex-G (but not stiffer than that of TRL-LFI).

→ The difference gives Flex-GT $\alpha$  a better injury assessment ability than that of Flex-G.

**Flesh**

# Flesh

## Flex-G

### Construction

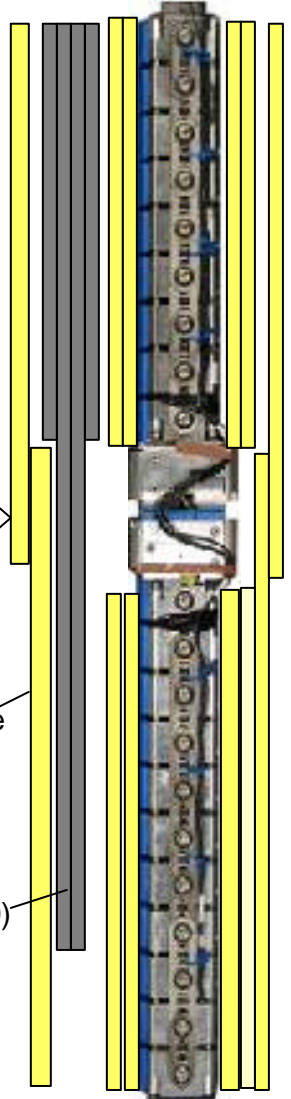
Flex-GT $\alpha$  has similar flesh construction as compared with that of Flex-G.

Impact

Neoprene

Rubber(30)

Sectional image



Outer view



## Flex-GT $\alpha$

Sectional image

Impact

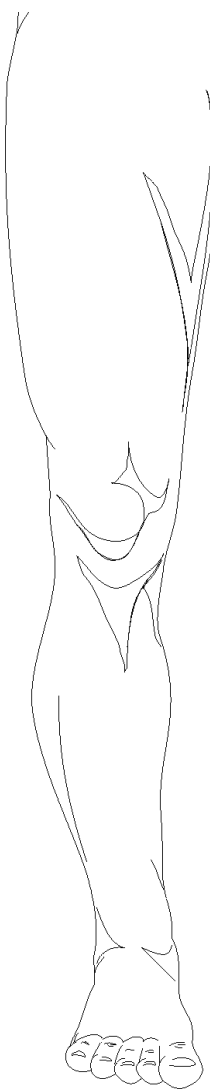
Neoprene

Rubber(30)

Outer view



Human leg illustration

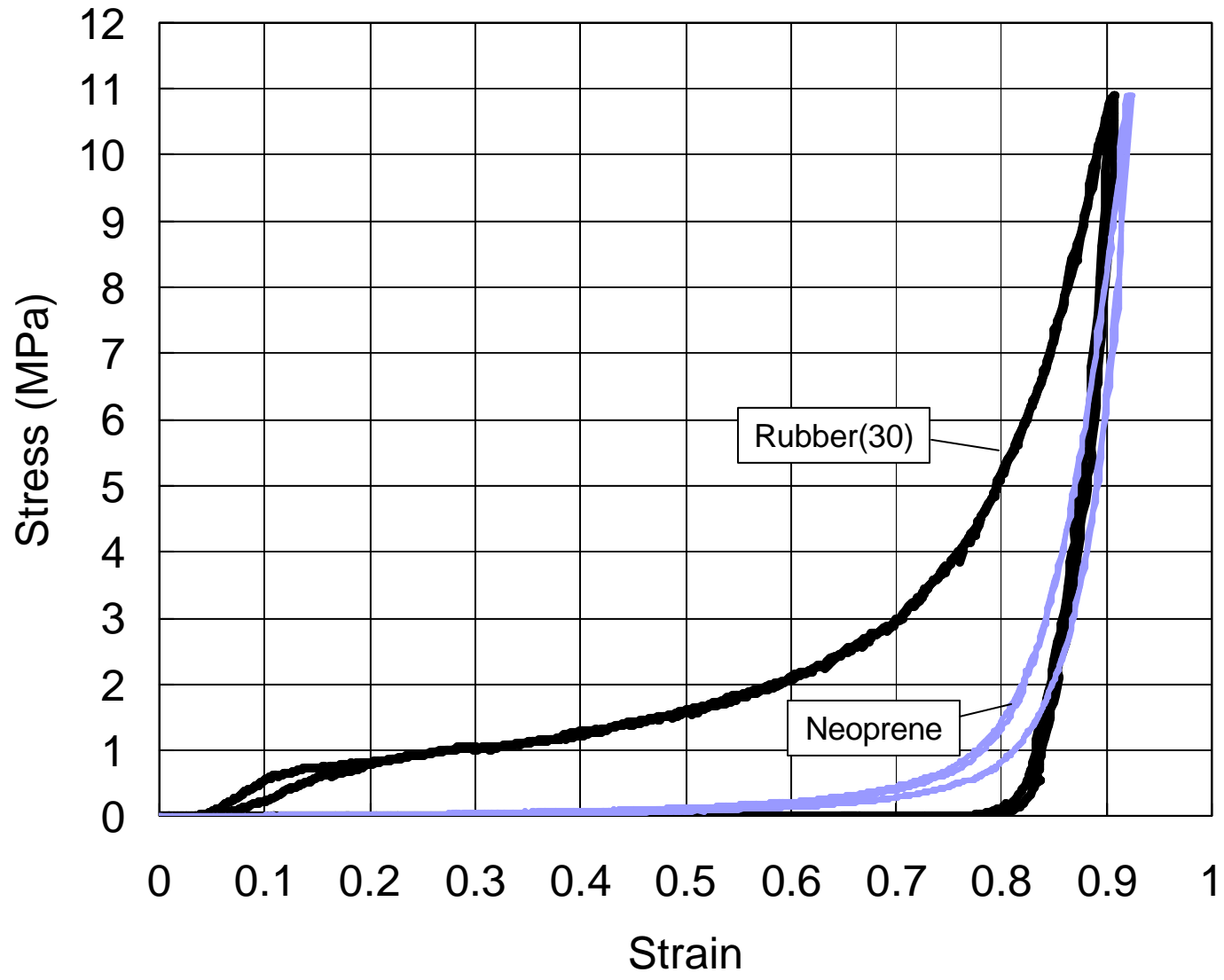


The different outer views of Flex-GT $\alpha$  and Flex-G reflect the differences in inner construction.

# Flesh

## Materials

Flex-GT $\alpha$  (Flesh) uses the same materials as those of Flex-G.



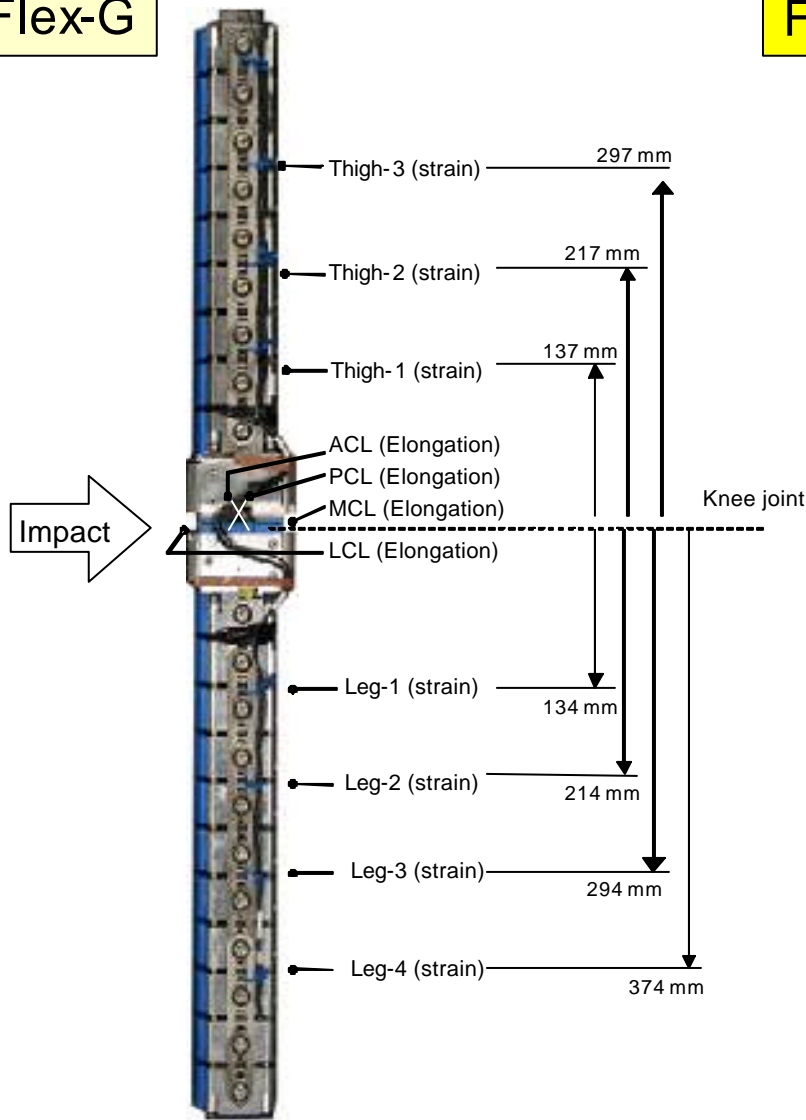
# Measurements

# Measurements

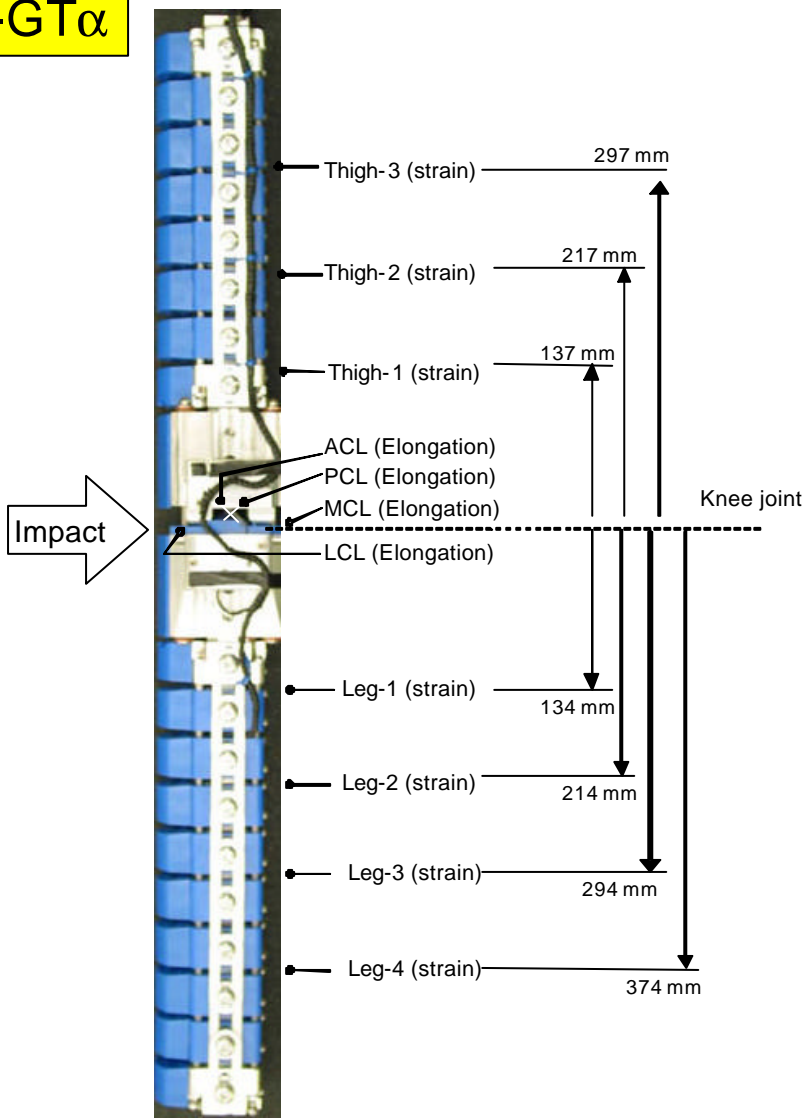
Measurement items and positions

Flex-GT $\alpha$  and Flex-G are identical in their measurement items and positions.

Flex-G



Flex-GT $\alpha$



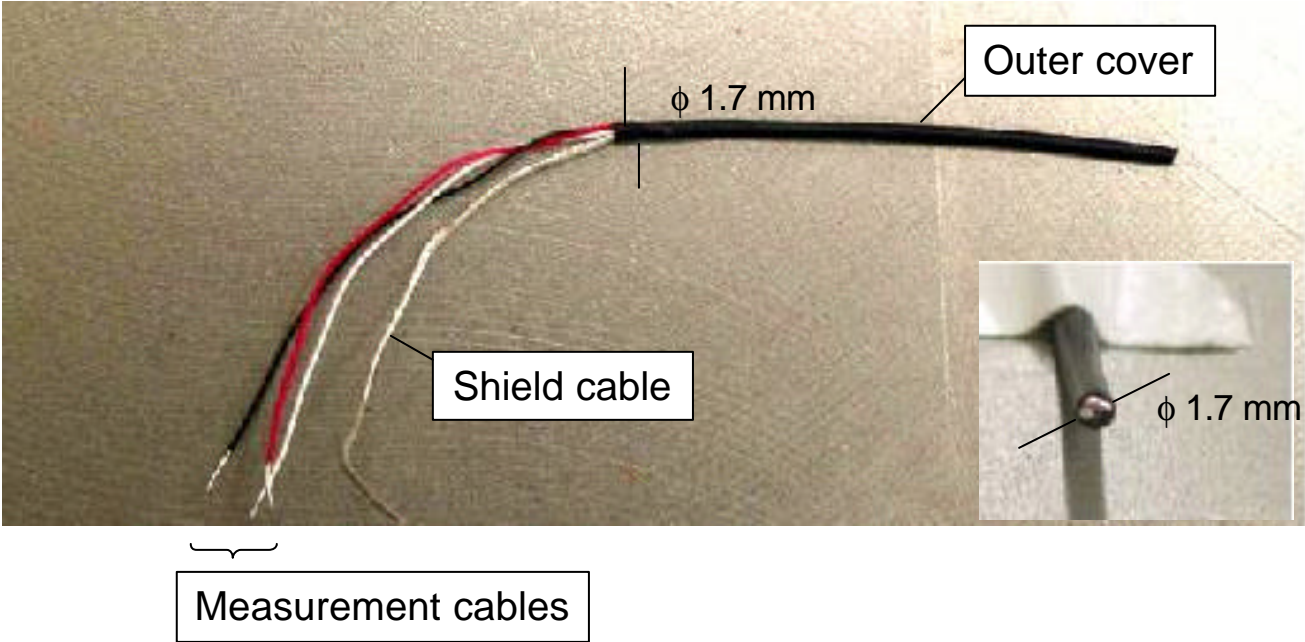


# Measurements

## Measurement cables

Flex-GT $\alpha$  uses the same measurement cables as those of Flex-G.

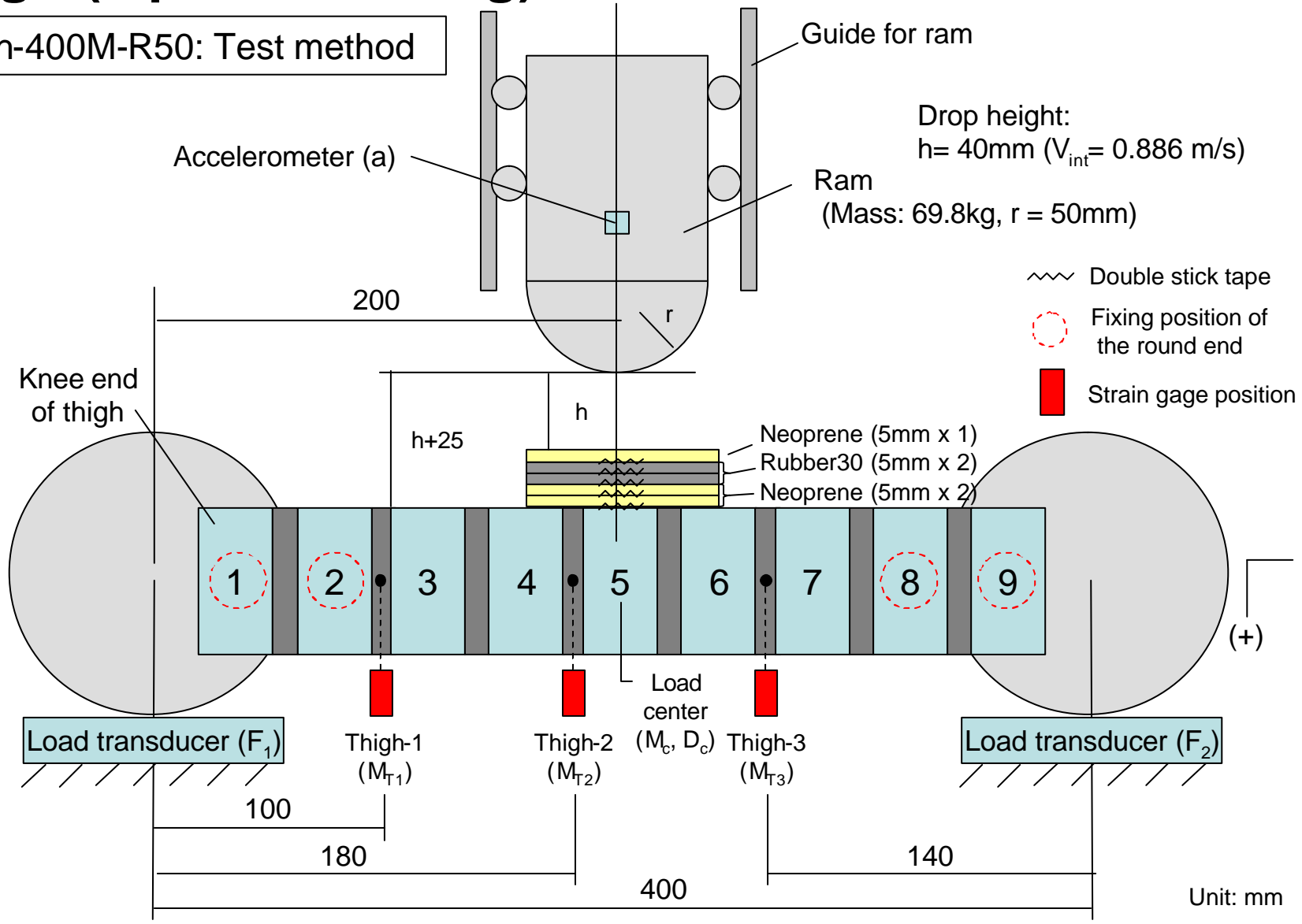
### Flex-G and Flex-GT $\alpha$



# Calibration

# Thigh (3-point bending)

Thigh-400M-R50: Test method



Flex-GT $\alpha$  (Thigh) adopts the same calibration method as that for Flex-G.

# Thigh (3-point bending)

## Thigh-400M-R50: Equations

Bending moment estimation  
(at loading center)

$$M_c(t) \cong \left| \frac{F_1(t) \times F_2(t)}{F_1(t) + F_2(t)} \times 400 \right|$$

Deflection estimation  
(at loading center)

$$D_c(t) \cong V_{init}t + \frac{1}{2}gt^2 + \iint a(t)dt$$

Bending moment estimation  
(at strain gage positions)

$$M_{T1}(t) \cong |F_1(t) \times 100|$$

$$M_{T2}(t) \cong |F_1(t) \times 180|$$

$$M_{T3}(t) \cong |F_2(t) \times 140|$$

*M* : Bending moment (Nm)

*F* : Force (kN)

*D* : Deflection (m)

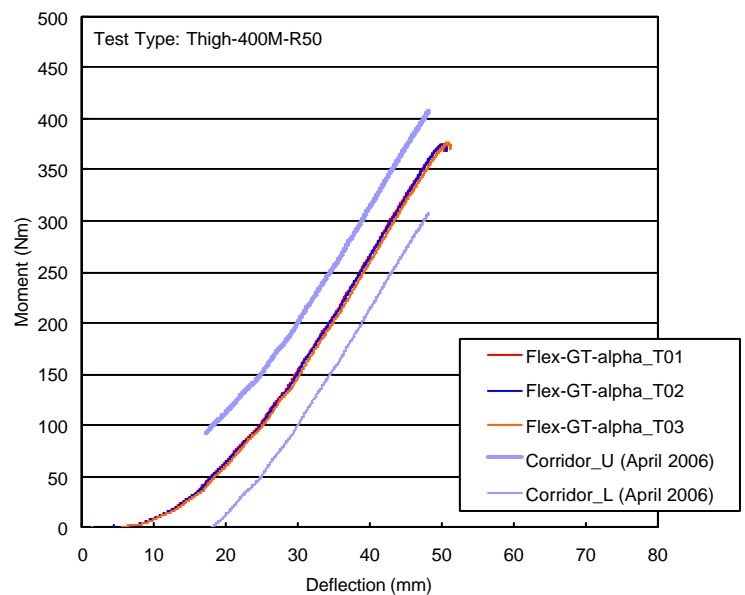
*V<sub>init</sub>* : Initial velocity (m/s)

*g* : Gravity (m/s<sup>2</sup>)

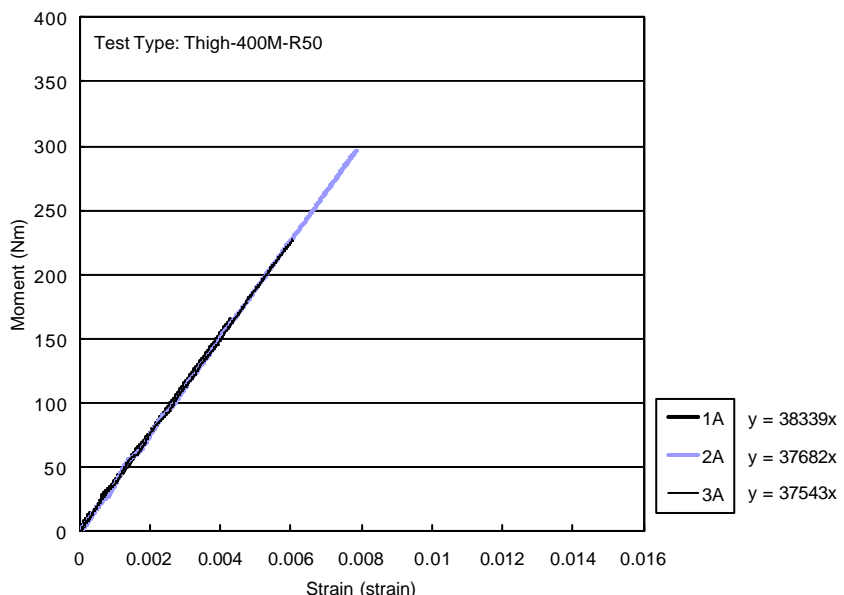
*a* : Acceleration (m/s<sup>2</sup>)

*t* : time (s)

### Evaluate: Bending characteristics



### Obtain: Strain-moment relationship





# Leg (3-point bending)

## Leg-410M-R50: Equations

Bending moment estimation  
(at loading center)

$$M_c(t) \cong \left| \frac{F_1(t) \times F_2(t)}{F_1(t) + F_2(t)} \times 410 \right|$$

Deflection estimation  
(at loading center)

$$D_c(t) \cong V_{init}t + \frac{1}{2}gt^2 + \iint a(t)dt$$

Bending moment estimation  
(at strain gage positions)

$$M_{L1}(t) \cong |F_1(t) \times 65|$$

$$M_{L2}(t) \cong |F_1(t) \times 145|$$

$$M_{L3}(t) \cong |F_2(t) \times 185|$$

$$M_{L4}(t) \cong |F_2(t) \times 105|$$

*M* : Bending moment (Nm)

*F* : Force (kN)

*D* : Deflection (m)

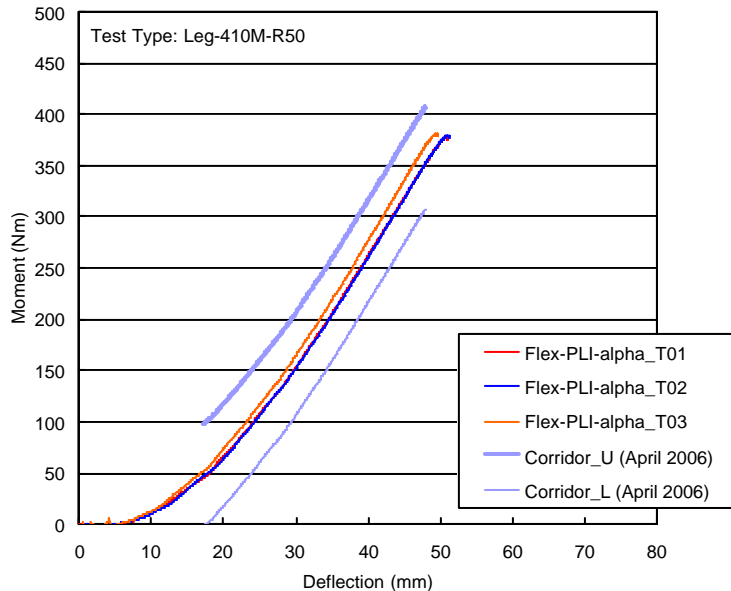
*V<sub>init</sub>* : Initial velocity (m/s)

*g* : Gravity (m/s<sup>2</sup>)

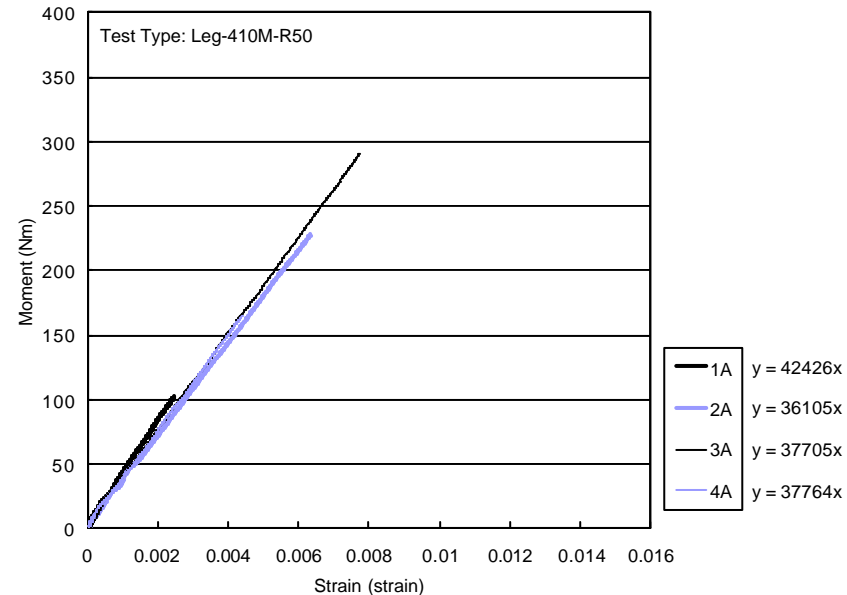
*a* : Acceleration (m/s<sup>2</sup>)

*t* : time (s)

## Evaluate: Bending characteristics

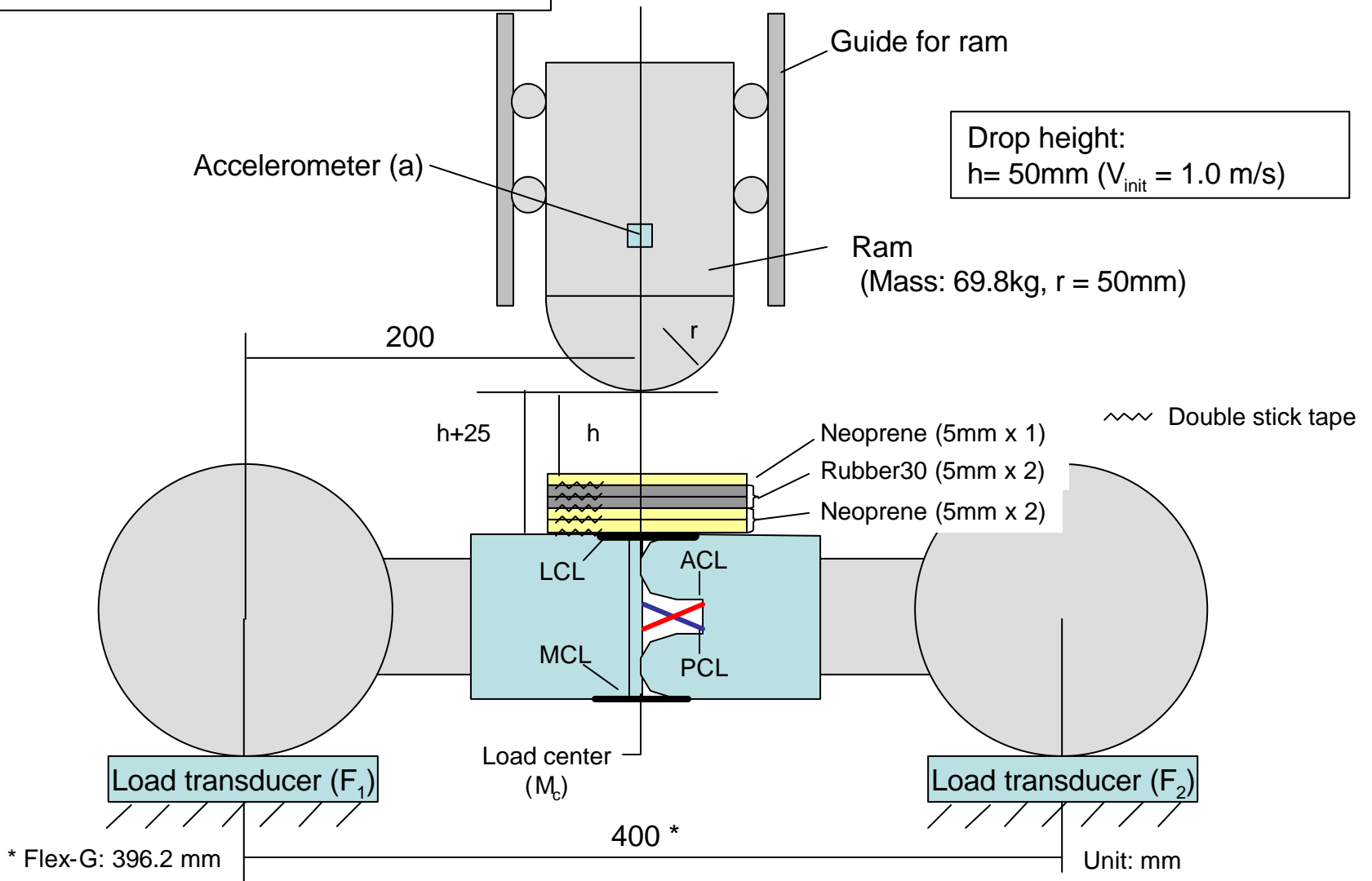


## Obtain: Strain-moment relationship



# Knee (3-point bending)

Knee-3PB-400-R50: Test method



Flex-GT $\alpha$  (Knee) adopts a calibration method similar to that for Flex-G.

# Knee (3-point bending)

Knee-3PB-400-R50: Equation

Bending moment estimation  
(at loading center)

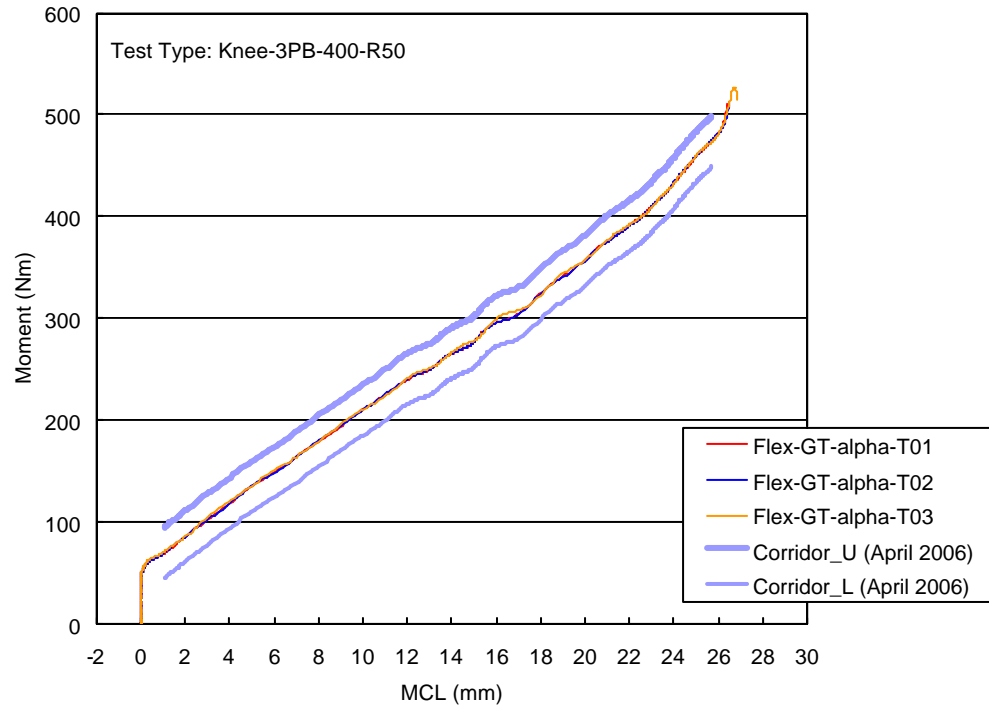
$$M_c(t) \cong |F_1(t) \times 200|$$

$M$  : Bending moment (Nm)

$F$  : Force (kN)

$t$  : time (s)

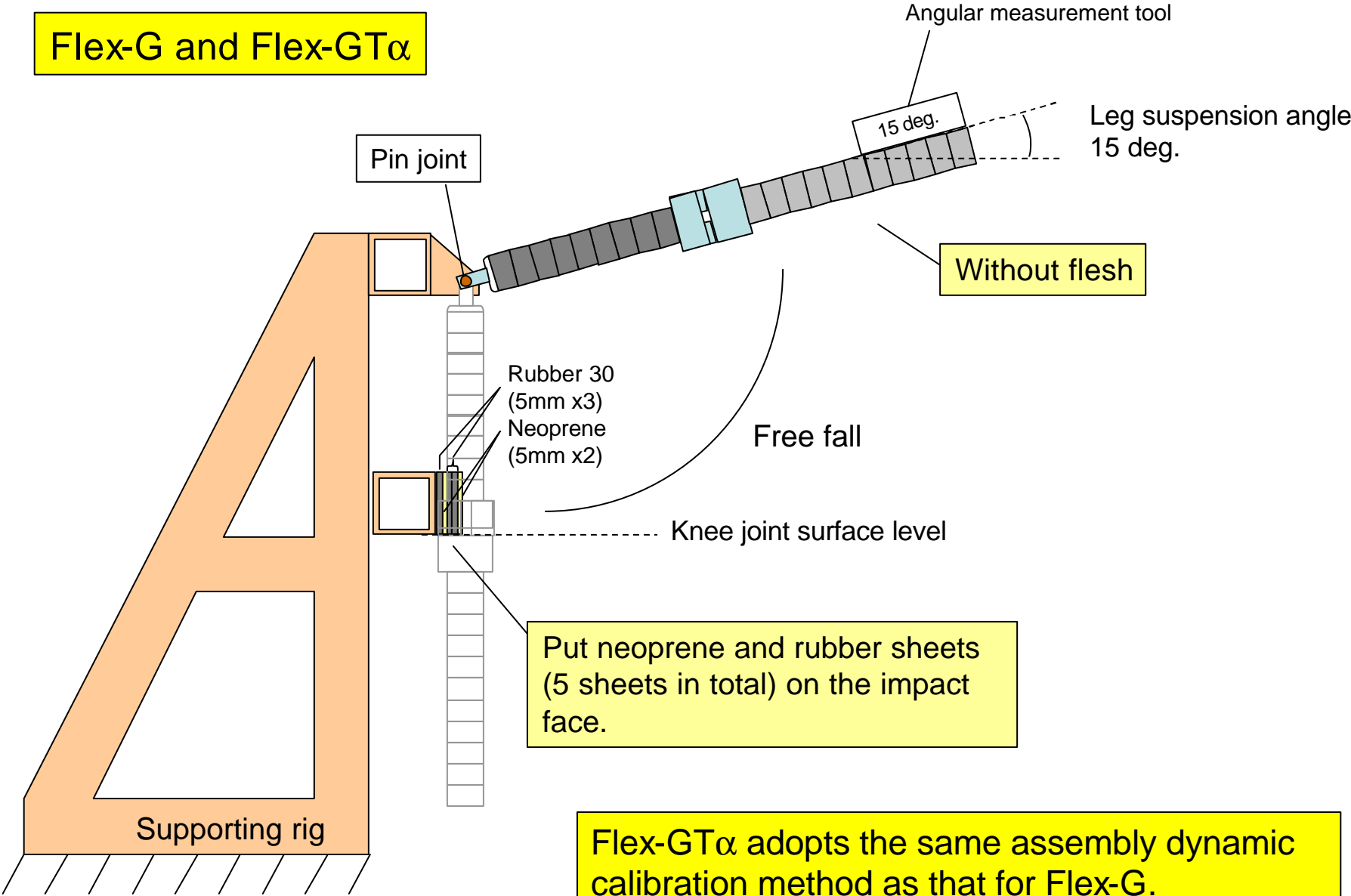
## Evaluate: Bending characteristics





# Assembly Dynamic Certification Test

Flex-G and Flex-GT $\alpha$



Angular measurement tool

15 deg.

Leg suspension angle 15 deg.

Pin joint

Without flesh

Rubber 30 (5mm x3)  
Neoprene (5mm x2)

Free fall

Knee joint surface level

Put neoprene and rubber sheets (5 sheets in total) on the impact face.

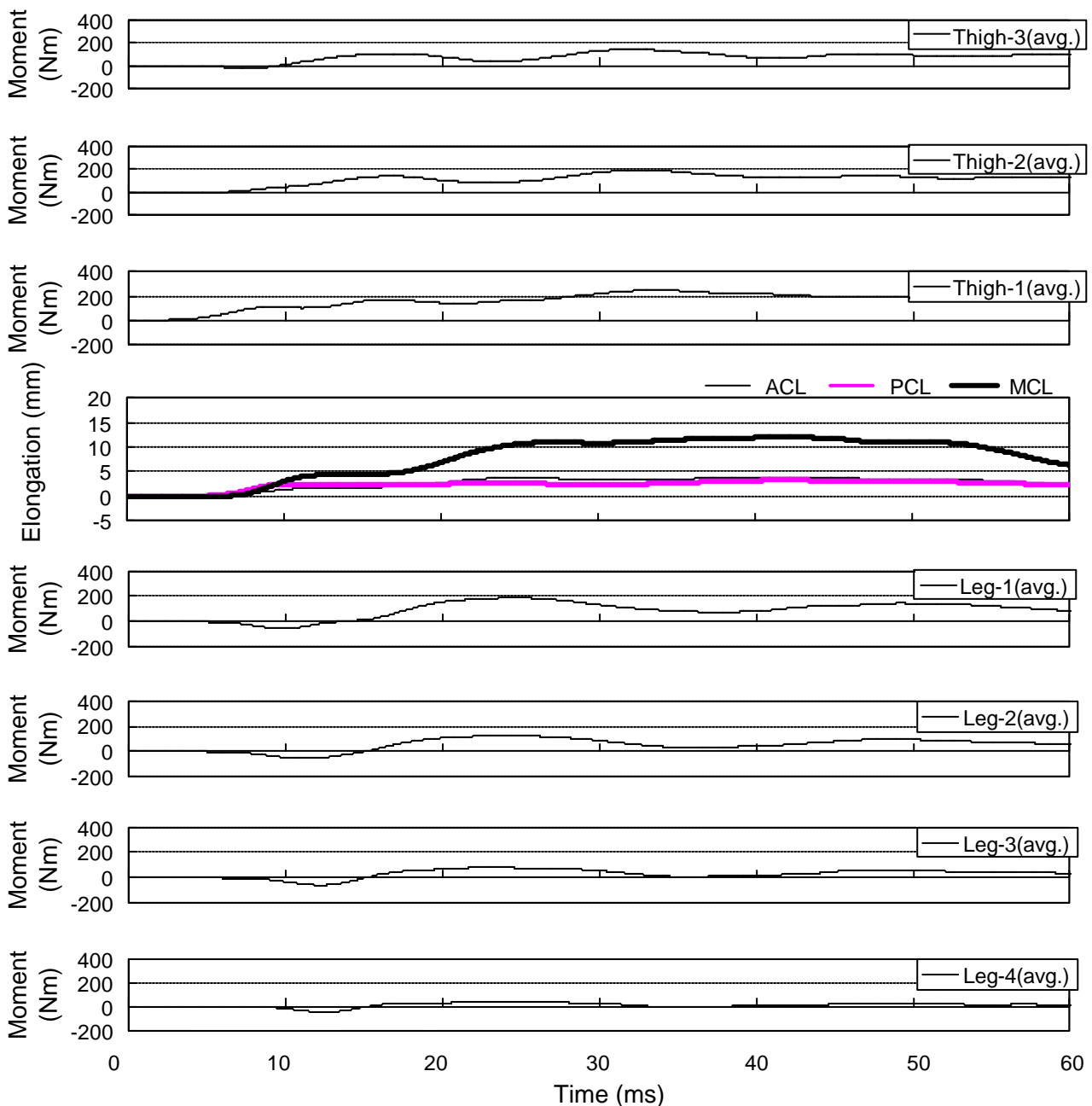
Supporting rig

Flex-GT $\alpha$  adopts the same assembly dynamic calibration method as that for Flex-G.

# Results

## Waveform

Flex-GT $\alpha$

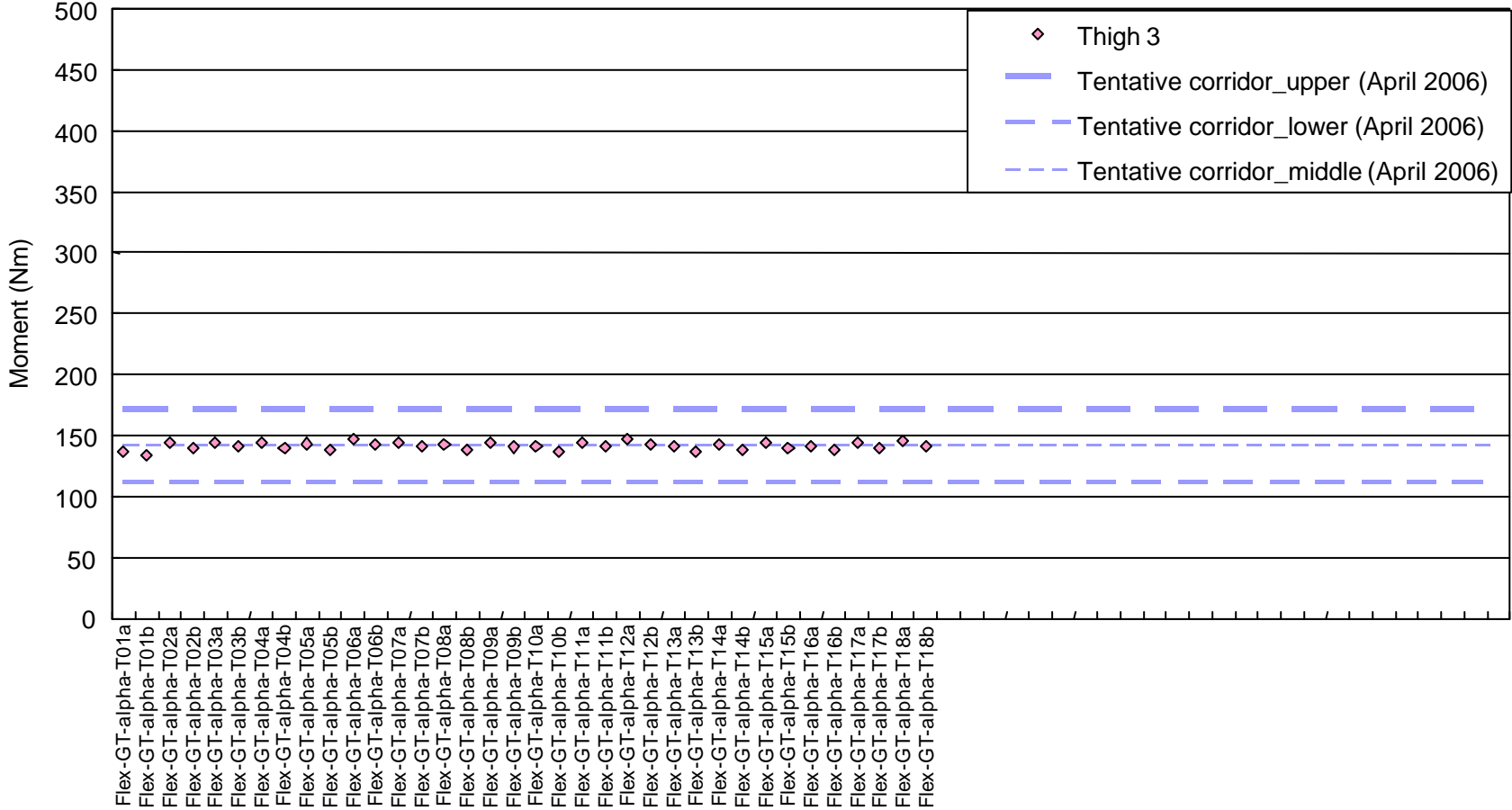


# Results

## Thigh-3 (maximum value)

Flex-GT $\alpha$

Assembly Dynamic Certification Test  
Thigh output  
(Flex-GT-Alpha)

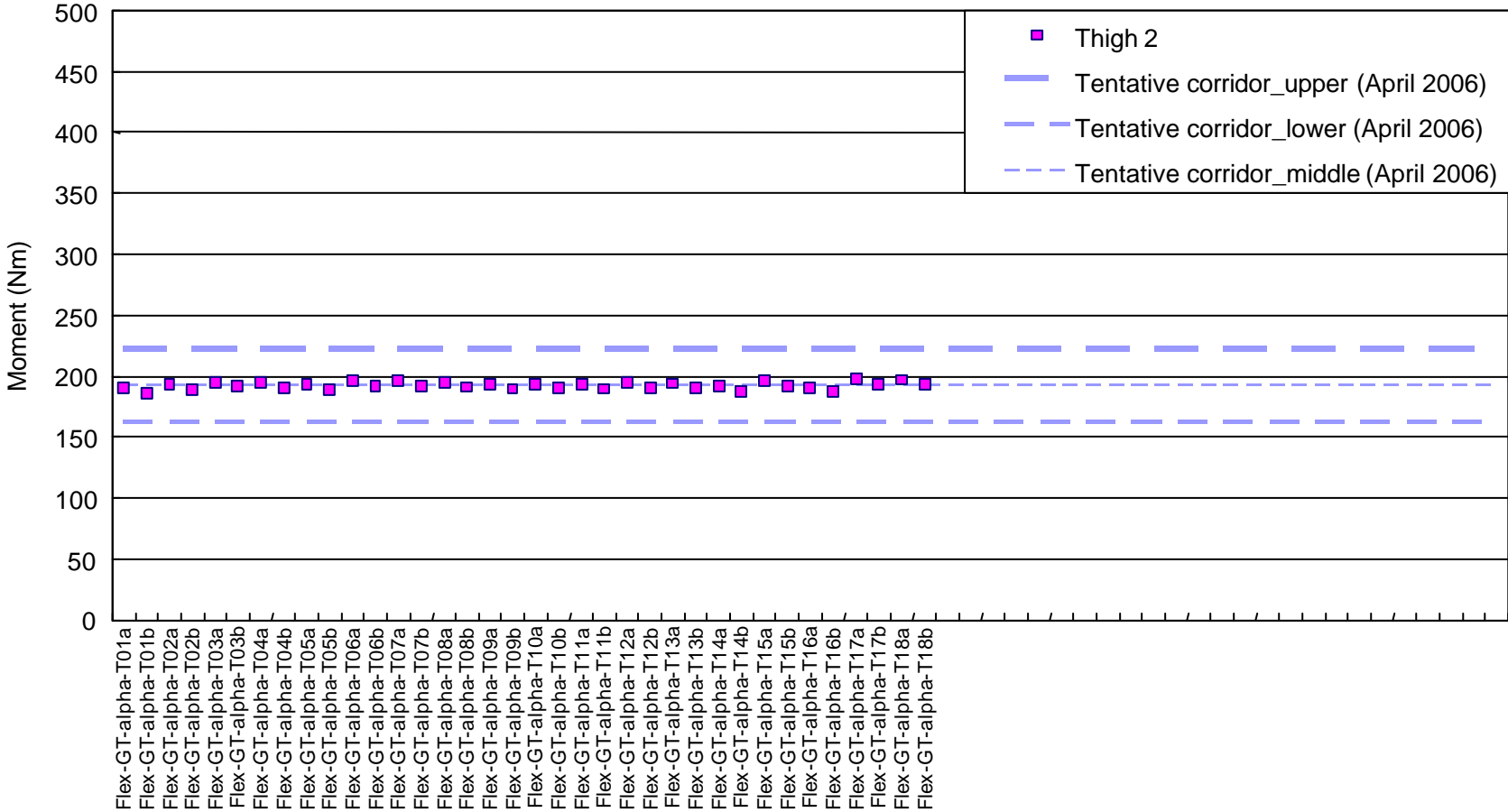


# Results

## Thigh-2 (maximum value)

Flex-GT $\alpha$

Assembly Dynamic Certification Test  
Thigh output  
(Flex-GT-Alpha)

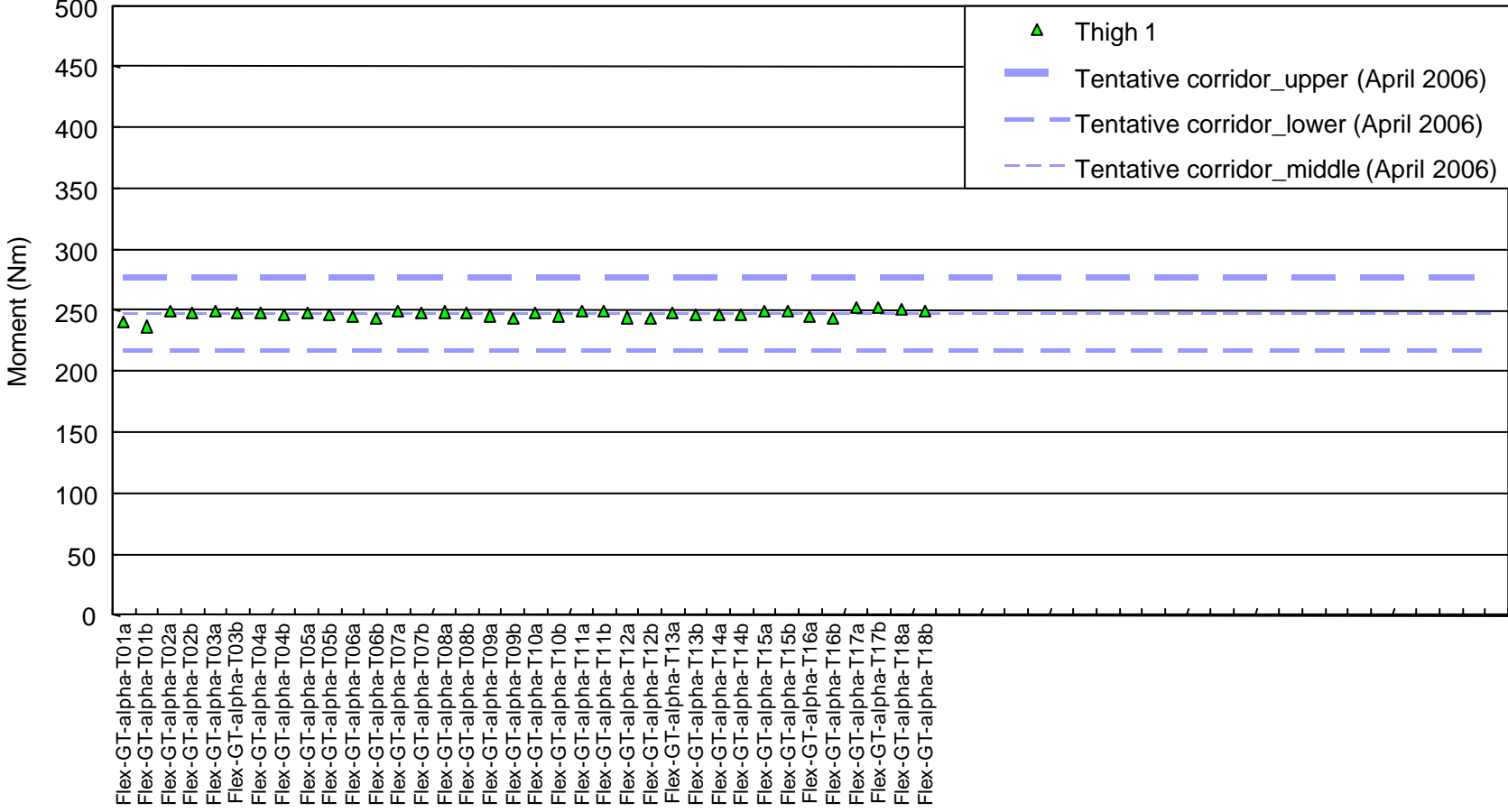


# Results

## Thigh-1 (maximum value)

Flex-GT $\alpha$

Assembly Dynamic Certification Test  
Thigh output  
(Flex-GT-Alpha)

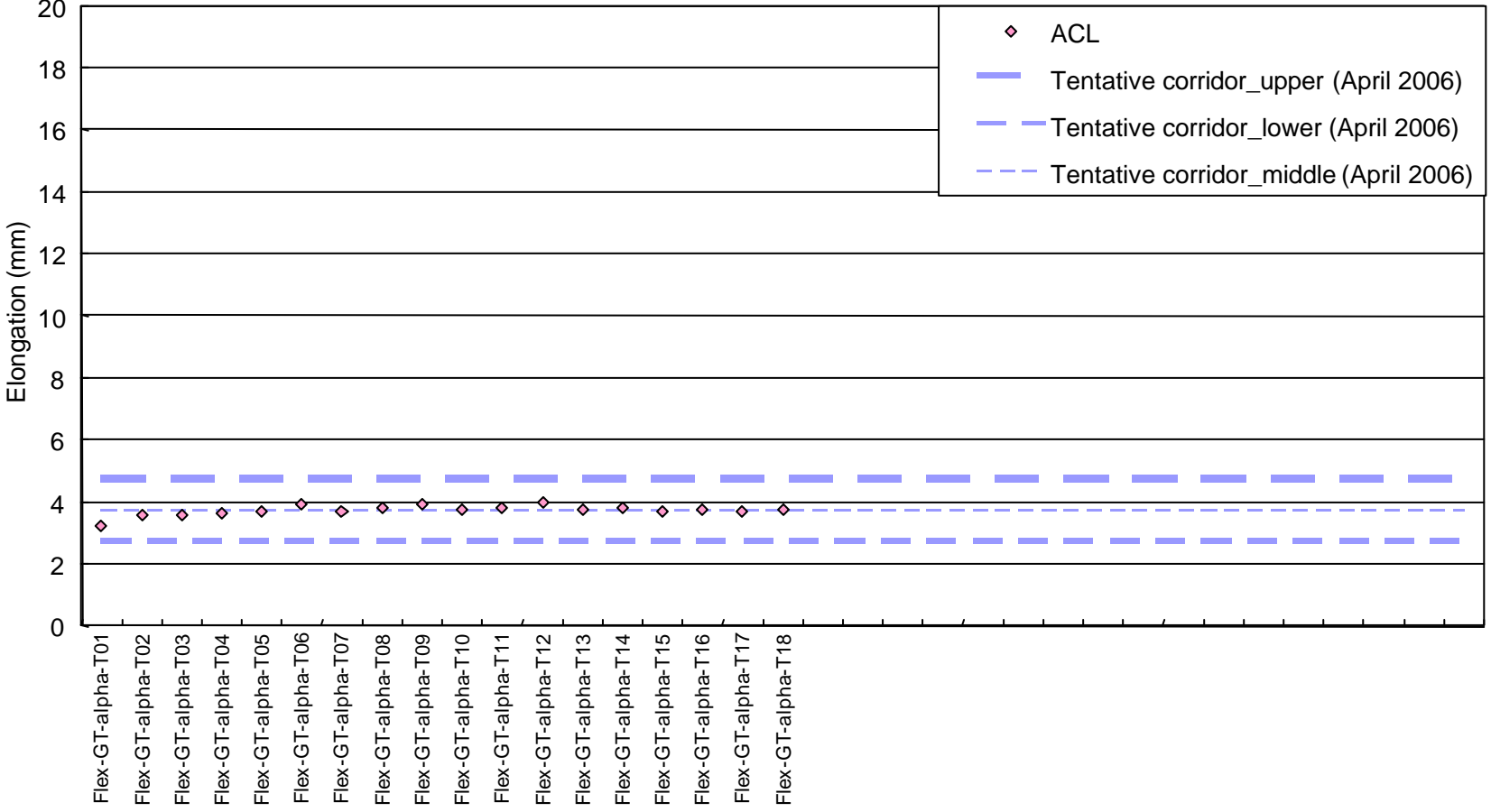


# Results

ACL (maximum value)

Flex-GT $\alpha$

Assembly Dynamic Certification Test  
Knee ligament output  
(Flex-GT-Alpha)

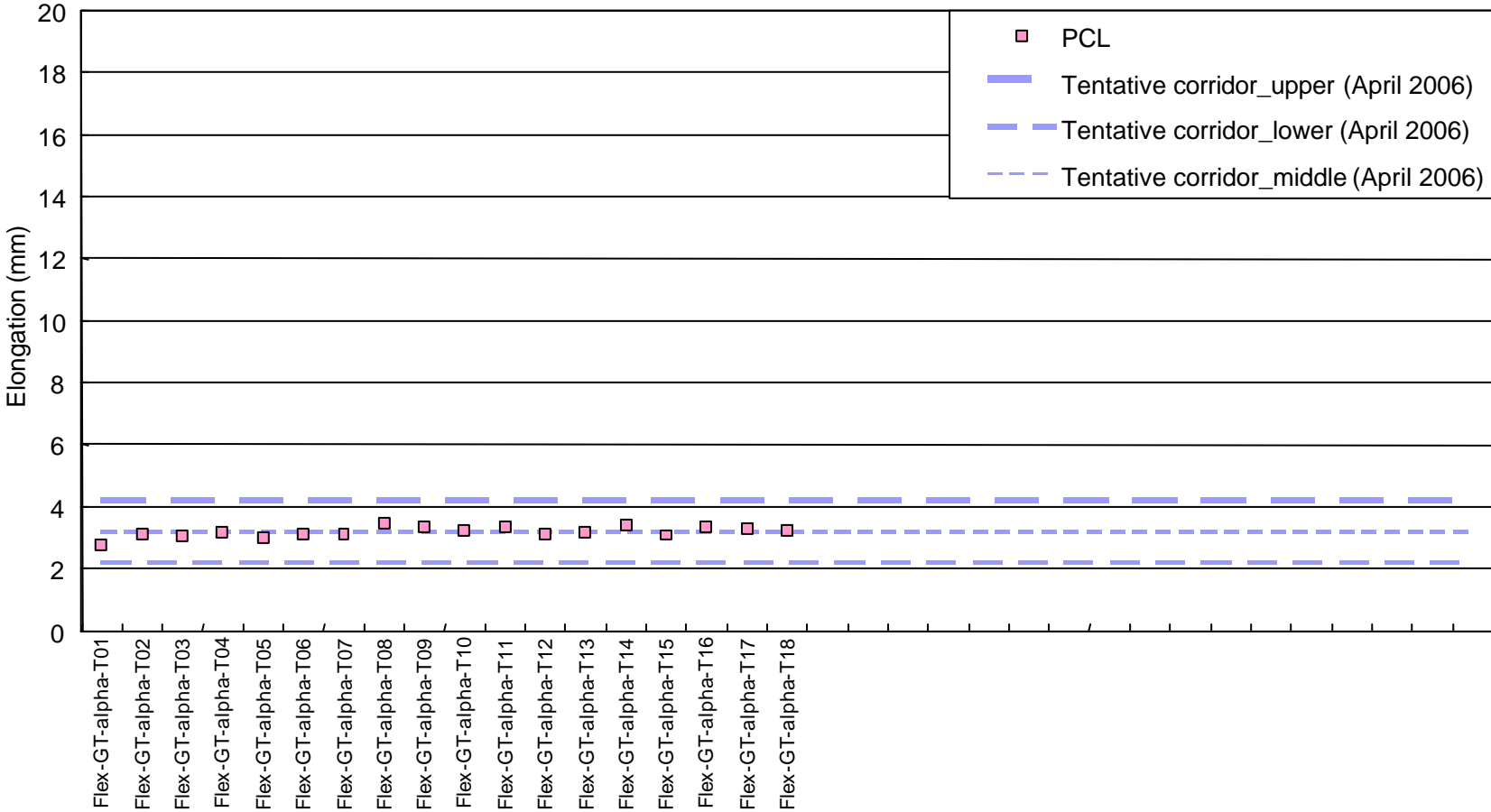


# Results

## PCL (maximum value)

**Flex-GT $\alpha$**

Assembly Dynamic Certification Test  
Knee ligament output  
(Flex-GT-Alpha)

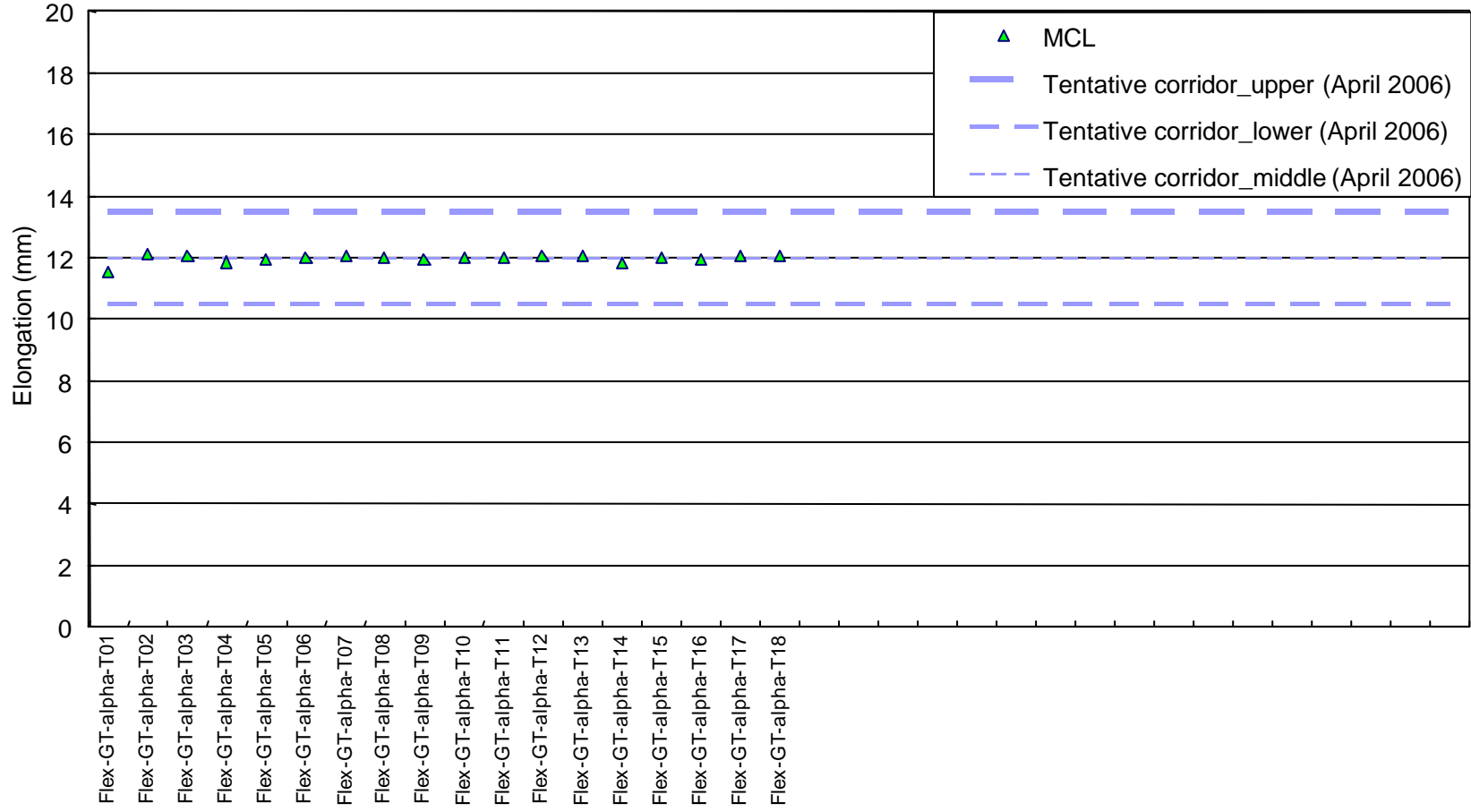


# Results

## MCL (maximum value)

**Flex-GT $\alpha$**

Assembly Dynamic Certification Test  
Knee ligament output  
(Flex-GT-Alpha)



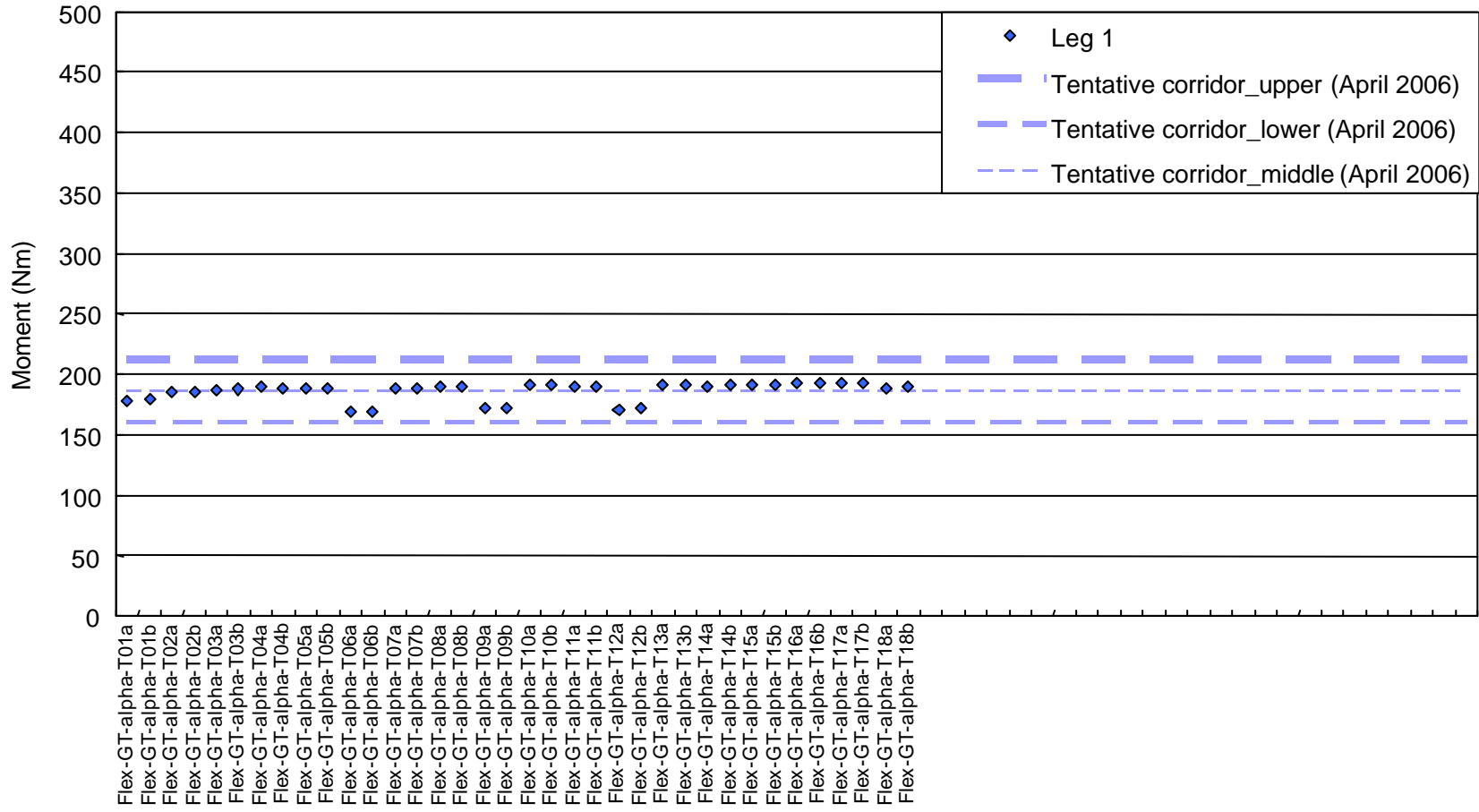


# Results

## Leg-1 (maximum value)

Flex-GT $\alpha$

Assembly Dynamic Certification Test  
Leg output  
(Flex-GT-Alpha)

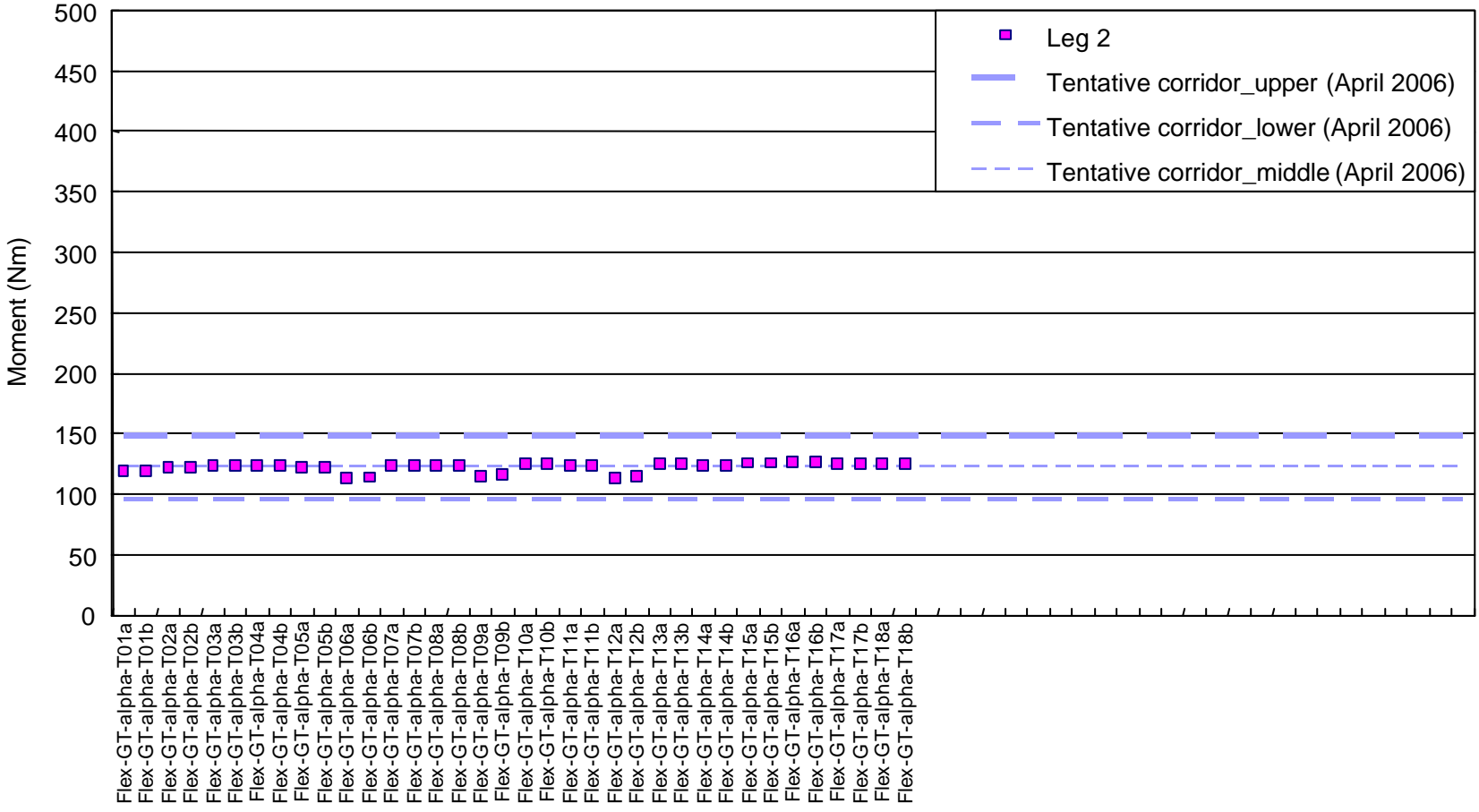


# Results

## Leg-2 (maximum value)

Flex-GT $\alpha$

Assembly Dynamic Certification Test  
Leg output  
(Flex-GT-Alpha)

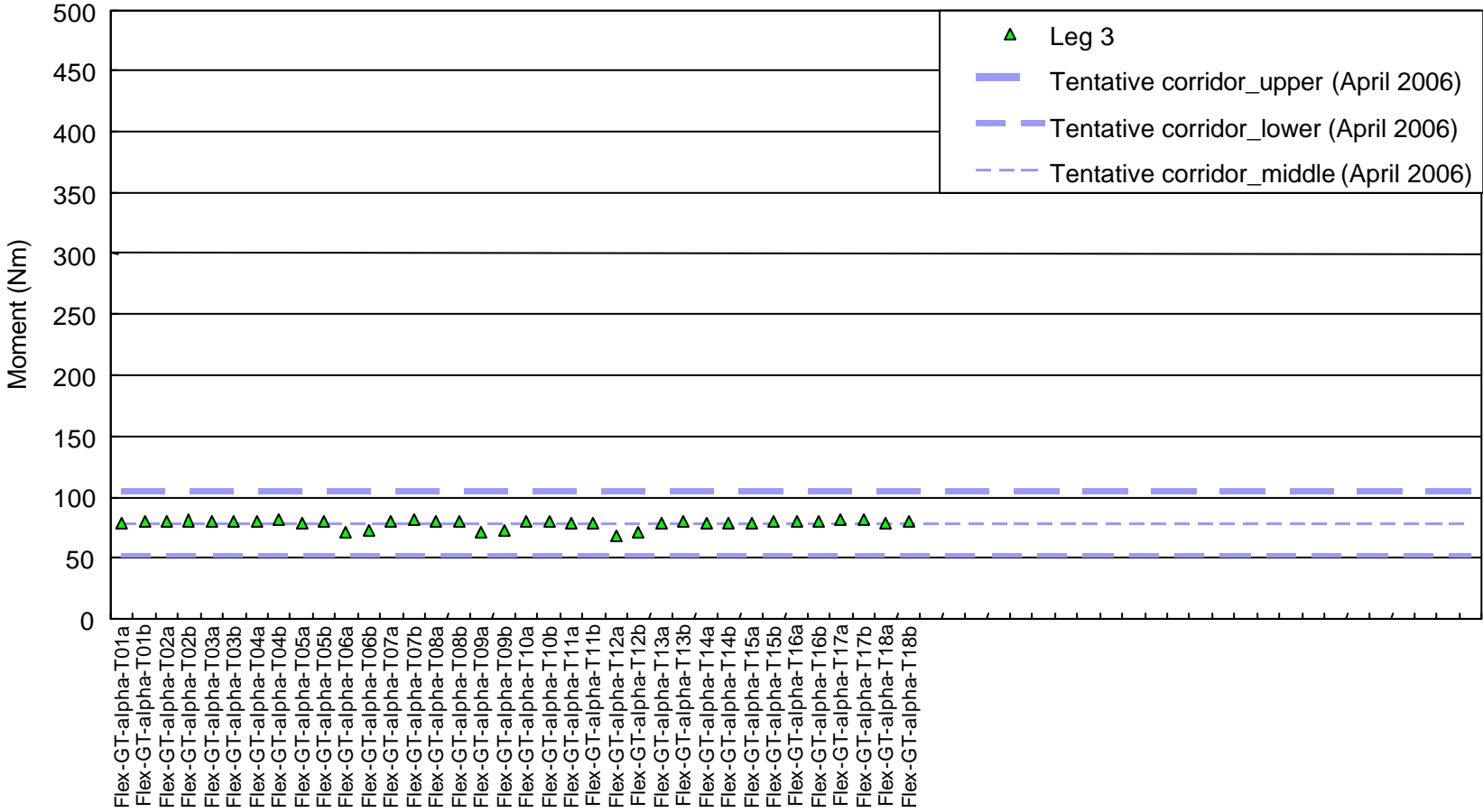


# Results

## Leg-3 (maximum value)

Flex-GT $\alpha$

Assembly Dynamic Certification Test  
Leg output  
(Flex-GT-Alpha)

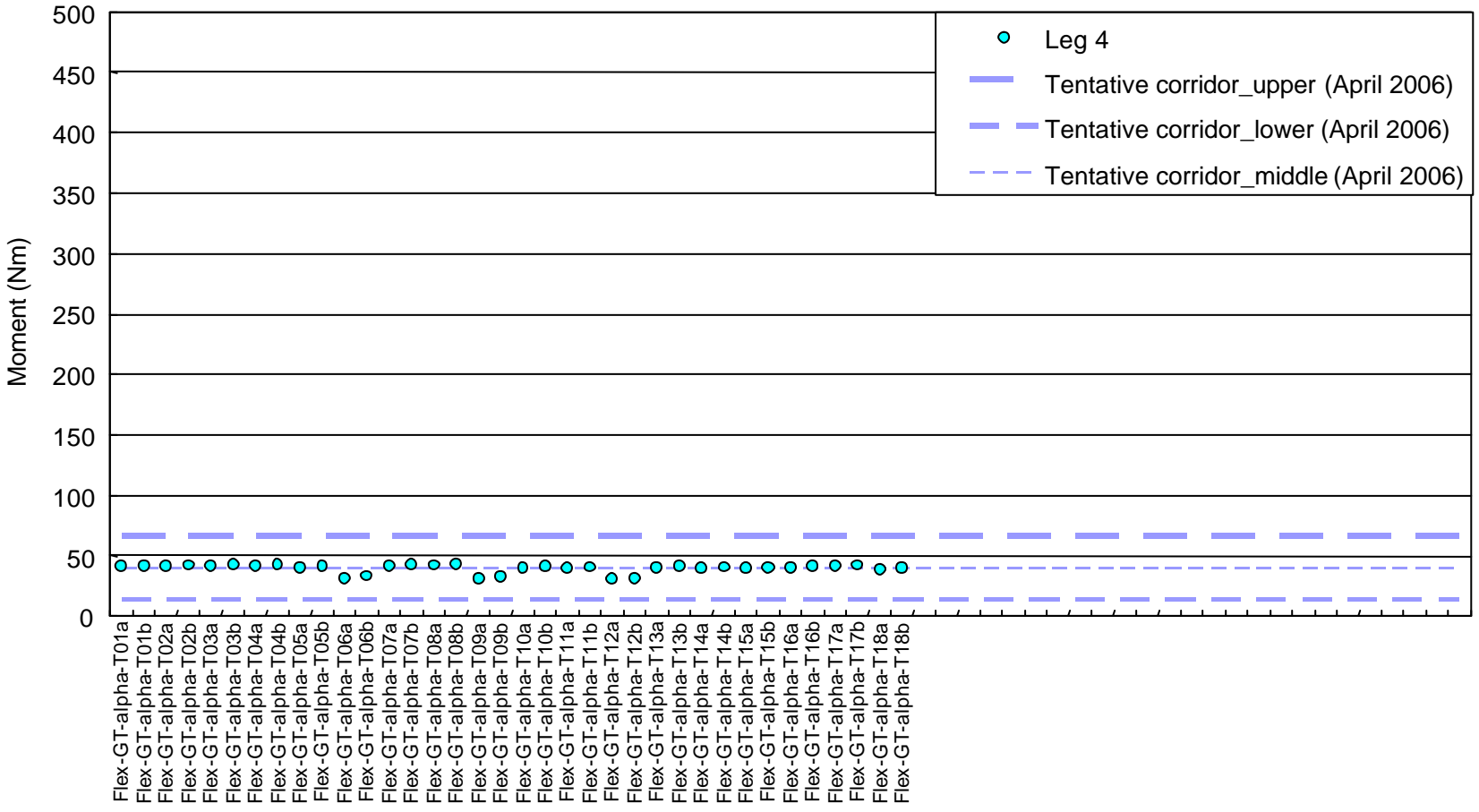


# Results

## Leg-4 (maximum value)

Flex-GT $\alpha$

Assembly Dynamic Certification Test  
Leg output  
(Flex-GT-Alpha)



# Conclusions

- The Flexible Pedestrian Legform Impactor GT Alpha (Flex-GT $\alpha$ ) was developed in March 2006.
- The Flex-GT $\alpha$  knee bending limit angle is increased by around 30% (+6 degrees).
- The other presentation will introduce the evaluation method and results concerning the injury assessment ability of Flex-GT $\alpha$ .

***Thank you for your attention!***