AGREEMENT

CONCERNING THE ADOPTION OF UNIFORM TECHNICAL PRESCRIPTIONS FOR WHEELED VEHICLES, EQUIPMENT AND PARTS WHICH CAN BE FITTED AND/OR BE USED ON WHEELED VEHICLES AND THE CONDITIONS FOR RECIPROCAL RECOGNITION OF APPROVALS GRANTED ON THE BASIS OF THESE PRESCRIPTIONS */

(Revision 2, including the amendments which entered into force on 16 October 1995)

Addendum 110: Regulation No. 111

Amendment 1

Supplement 1 - Date of entry into force: 4 April 2005

UNIFORM PROVISIONS CONCERNING THE APPROVAL OF TANK VEHICLES OF CATEGORIES N AND O WITH REGARD TO ROLLOVER STABILITY

UNITED NATIONS

*/ Former title of the Agreement:

Insert new paragraphs 2.7. and 2.7.1., to read:

"2.7. "Rollover threshold" means the instant when all the wheels of one side of a vehicle have lost contact with the supporting surface (tilt table platform).

2.7.1. The inclination angle of the tilt table surface is represented by the symbol "β".

Paragraph 5.3.1.1., amend to read:

".....a tilt table angle of $\beta_c = 23^\circ$ has been reached ....." 

Annex 1.

Item 3.2., amend to read:

"3.2. tank; make, model, effective volume: ....................................................." 

Item 6.2., amend to read:

"6.2. mass of vehicle in running order: .............................................................." 

Insert a new item 8.1., to read:

"8.1. Centre of gravity height of the vehicle in running order: ........................." 

Insert a new item 11.5., to read:

"11.5. Stability enhancement engaged: ........ yes/not/not applicable 2/"

Annex 3.

Paragraph 7., amend to read:

"7 TEST PROCEDURE

7.1. This procedure consists ........ 

........ of stick-slip and hysteresis."

Insert new paragraphs 7.2. to 7.4., to read:

"7.2. Without prejudice to paragraph 5., if the vehicle fails to achieve the minimum tilt table angle specified in paragraph 5.3.1.1. when tested with a partially filled tank in the maximum mass condition then, subject to the agreement of the type approval authority and appropriate safety considerations being taken into account, the
manufacturer or applicant may request that a further test be undertaken with alternative loading conditions as described in paragraphs 7.2.1. and 7.2.2. Where the vehicle manufacturer or applicant chooses not to test in accordance with the alternative loading conditions in paragraphs 7.2.1. and 7.2.2., the first test result will constitute the final result.

7.2.1. The first alternative condition is the vehicle loaded to its maximum mass and with the tank fully or partially filled with a fluid for which the tank is designed to carry in normal use.

7.2.2. The second alternative condition is the vehicle loaded in excess of its normal maximum mass and with the tank fully filled with a substitute fluid.

7.2.3. If the tank vehicle manufacturer does not agree with overloading required for additional test, the vehicle is considered as not having passed the test.

7.3. In the case where the vehicle is tested in the fully filled condition, the recorded values of the test tilt table inclination angle $\beta_f$ shall be corrected using the following formulae:

$$\tan \beta_p = \tan \beta_f \cdot \frac{A_f \cdot H_f}{A_f \cdot H_g} + \frac{T_T}{2H_g} \left(1 - \frac{A_f}{A_f}\right)$$

The value of $\beta_p$ shall be higher than, or equal to, the minimum rollover threshold inclination angle required by this Regulation ($\beta_c$).

In the formulae:

- $A_T = \text{vehicle mass in case of loading by normal fluid}$;
- $A_f = \text{vehicle mass in case of loading by a substitute fluid}$;
- $A_f = A_f + V_i \cdot (\rho_f - \rho_t)$;
- $H_g, H_f = \text{height of the vehicle centre of gravity in case of loading with normal fluid and a substitute fluid, respectively}$;
- $T_T = \text{theoretical wheel track at the vehicle cross section at the centre-of-gravity point}$;
\[ \beta_p = \text{corrected tilt table inclination angle for the fluid which the vehicle is intended to carry;} \]
\[ \beta_f = \text{the recorded tilt table inclination angle achieved using the substitute fluid;} \]
\[ V_t = \text{effective tank volume;} \]
\[ C_{ST} = \frac{A_g}{H_g - H_l} \]
\[ C_{ST} = \text{vertical stiffness of suspension at the centre of gravity point;} \]
\[ A_g = \text{mass of payload;} \]
\[ \rho_T = \text{density of normal fluid;} \]
\[ \rho_f = \text{density of the substitute fluid;} \]
\[ H_l = \text{height of the centre of gravity of the vehicle in running order.} \]

7.4. If, in the case of filling a tank with a substitute fluid, the total vehicle mass is less than the maximum permissible mass of a vehicle and the vehicle is intended to carry a fluid having a higher density than that of the test fluid, the recorded value of the rollover threshold inclination angle shall be corrected using the formula given in paragraph 7.2. of this annex. Alternatively, the manufacturer may arrange to provide facilities for the vehicle to be tested using the fluid which it is intended to carry, taking into account any incurred safety risks.

Annex 4.

Paragraph 7.2., amend to read:

"7.2. In case of semi-trailers separated from tractors, kingpin effects are calculated by using the following formula:

\[ T_K = \frac{\sum_{i=1}^{n} T_i}{n} \]

The kingpin roll stiffness, which is the roll stiffness of the tractor at the longitudinal position of the fifth wheel/kingpin, will be calculated by using a reference load dependent roll stiffness factor of 4 kN-m/rad:

\[ C_{DRESK} = A_K \cdot 4" \]