

Can we merge
France/German and
Japanese proposals ?

France

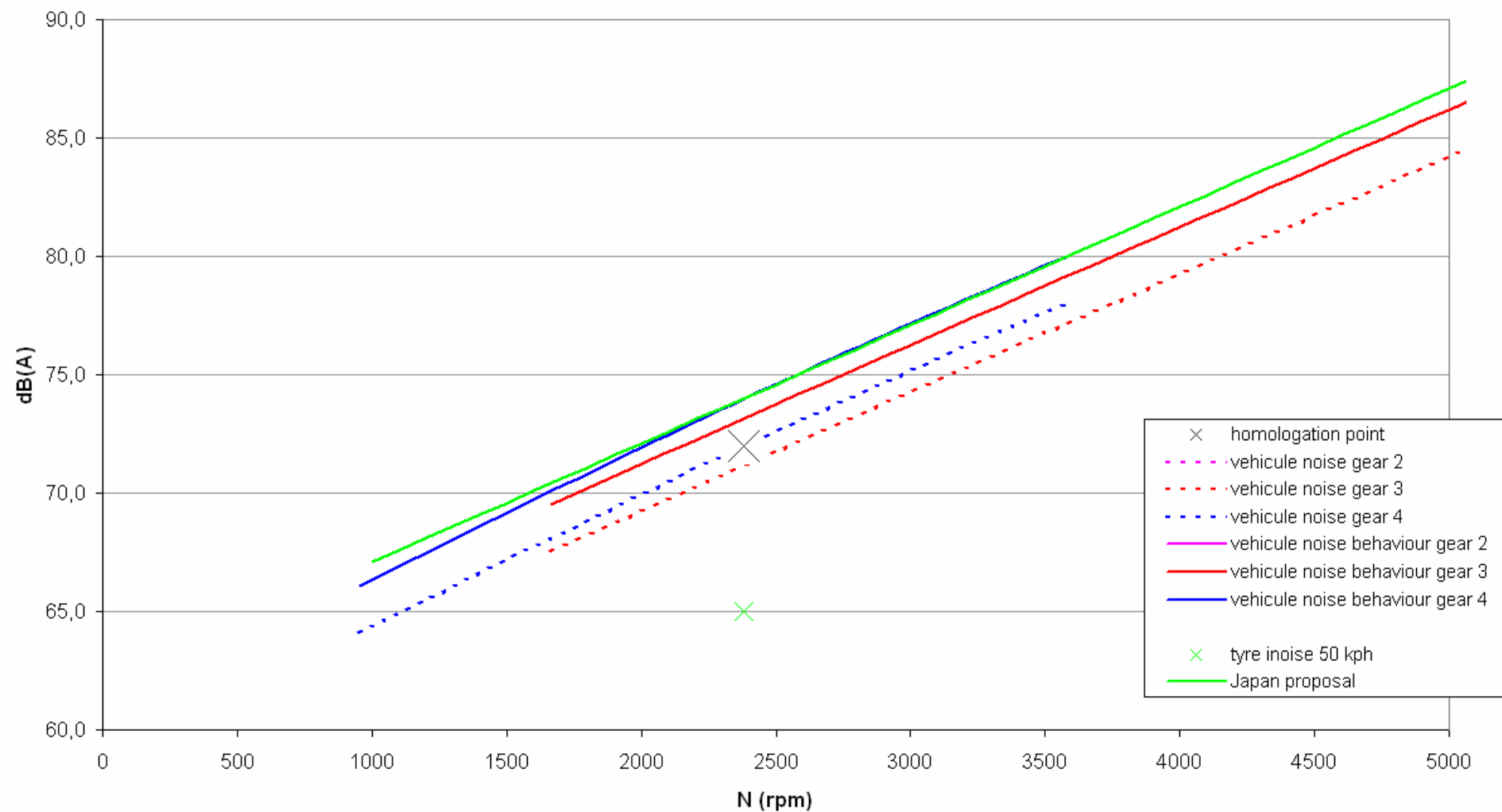
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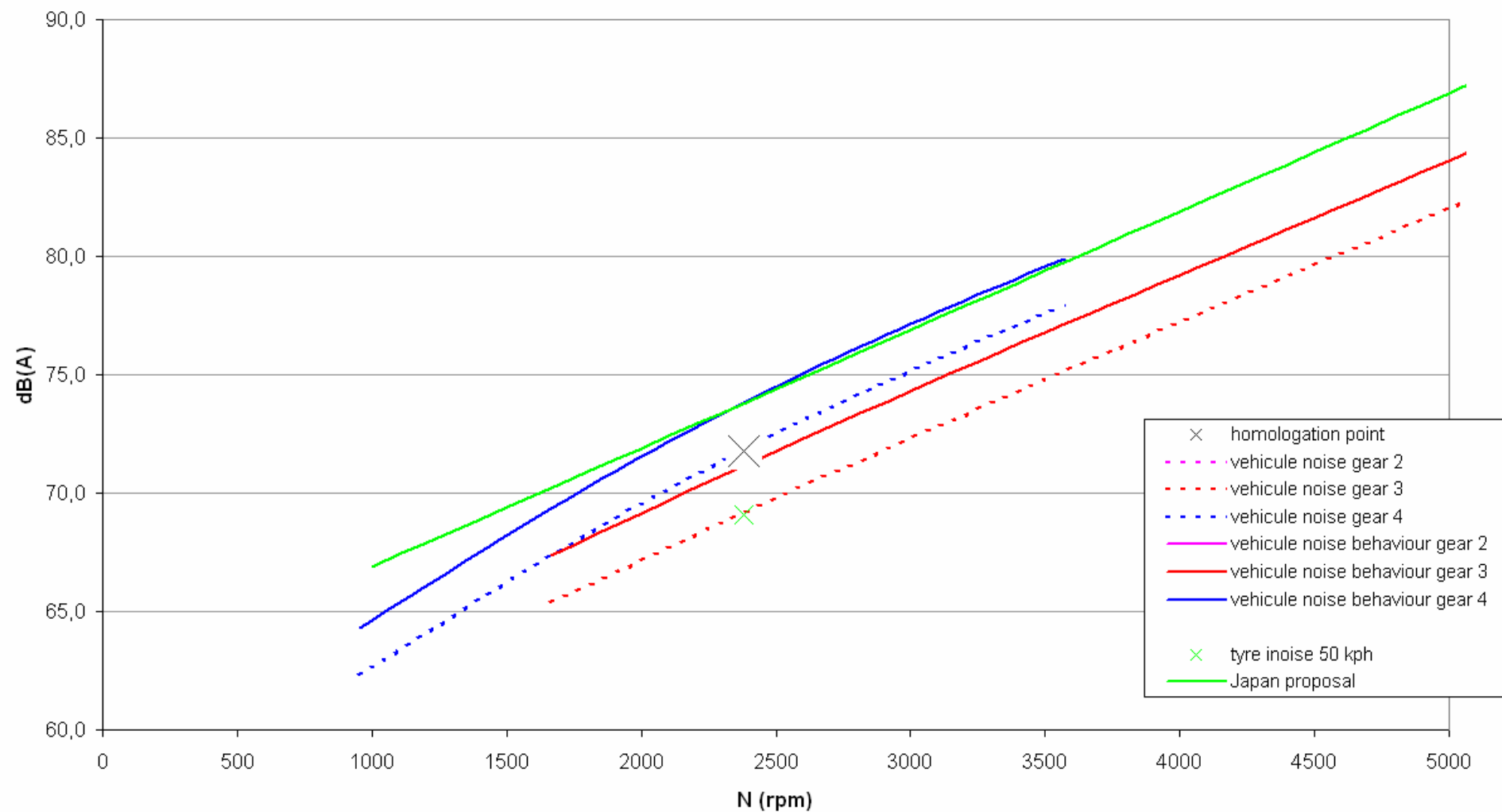
French/German proposal and Japan proposal - Noise behaviour on rpm axis



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- Converge to Japan proposal with France/German method for high engine noise compare to tyre noise.
- How to take into account the gap between vehicle noise gear i and vehicle noise gear $i-1$?

French/German proposal and Japan proposal - Noise behaviour on rpm axis



Can we converge France/German method and Japan proposal ?

- Converge L_{pmax} vs. rpm axis,
- Converge Japan proposal with France/German method for high engine noise compare to tyre noise.
- How to take into account the gap between vehicle noise gear i and vehicle noise gear $i-1$ on Japan proposal ?
- Choice of the method regarding the precision needed for detecting non linearity.

Thank you for your attention