

# **HDH: HV – HILS**

Hybrid vehicles

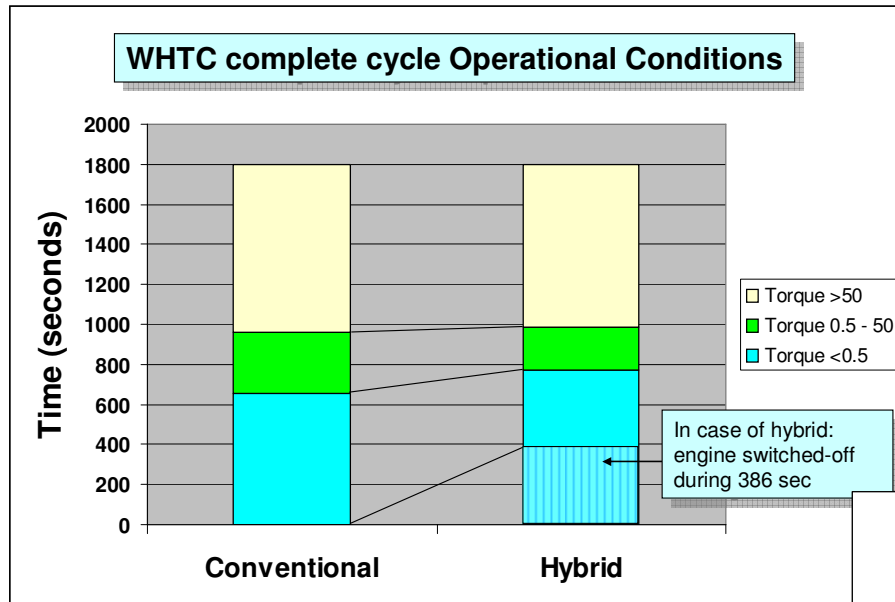
Hardware in the loop simulation

HDH Meeting 19.May 2010 Brussels

# Baseline, operational conditions

- Combustion engines in hybrid powertrains operate in different load/speed areas than in conventional powertrains
- Some (large) areas of the engine map may never be used in real world HV mode
- WHTC – WHSC engine cycles will not be representative
- Combustion engines is only operational in case of 'power-demand'

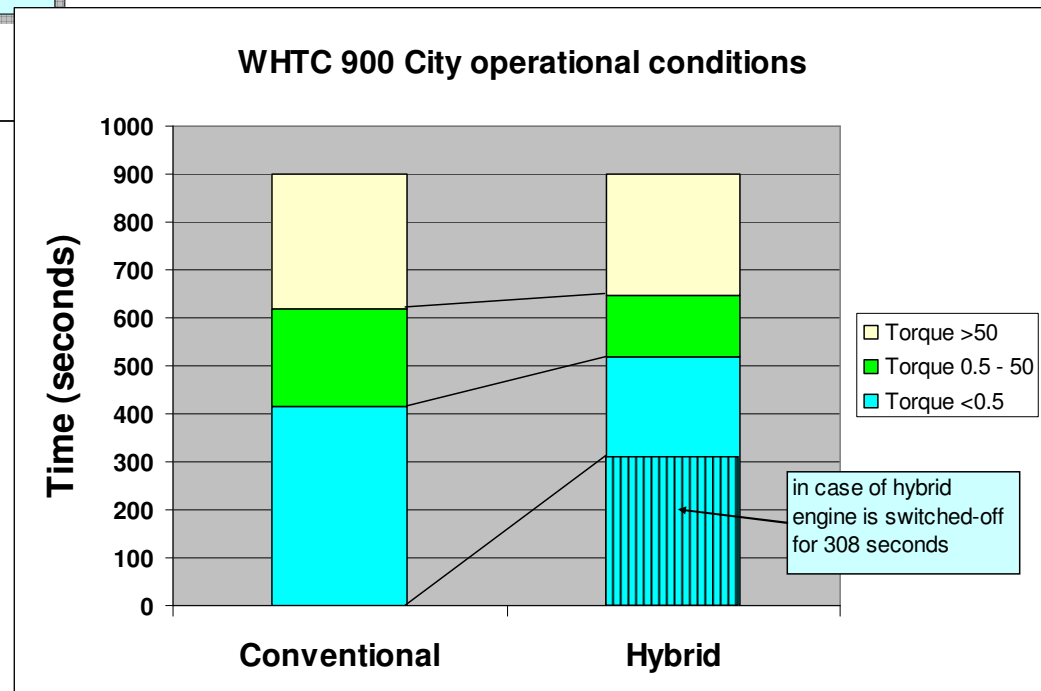
# Parallel hybrid



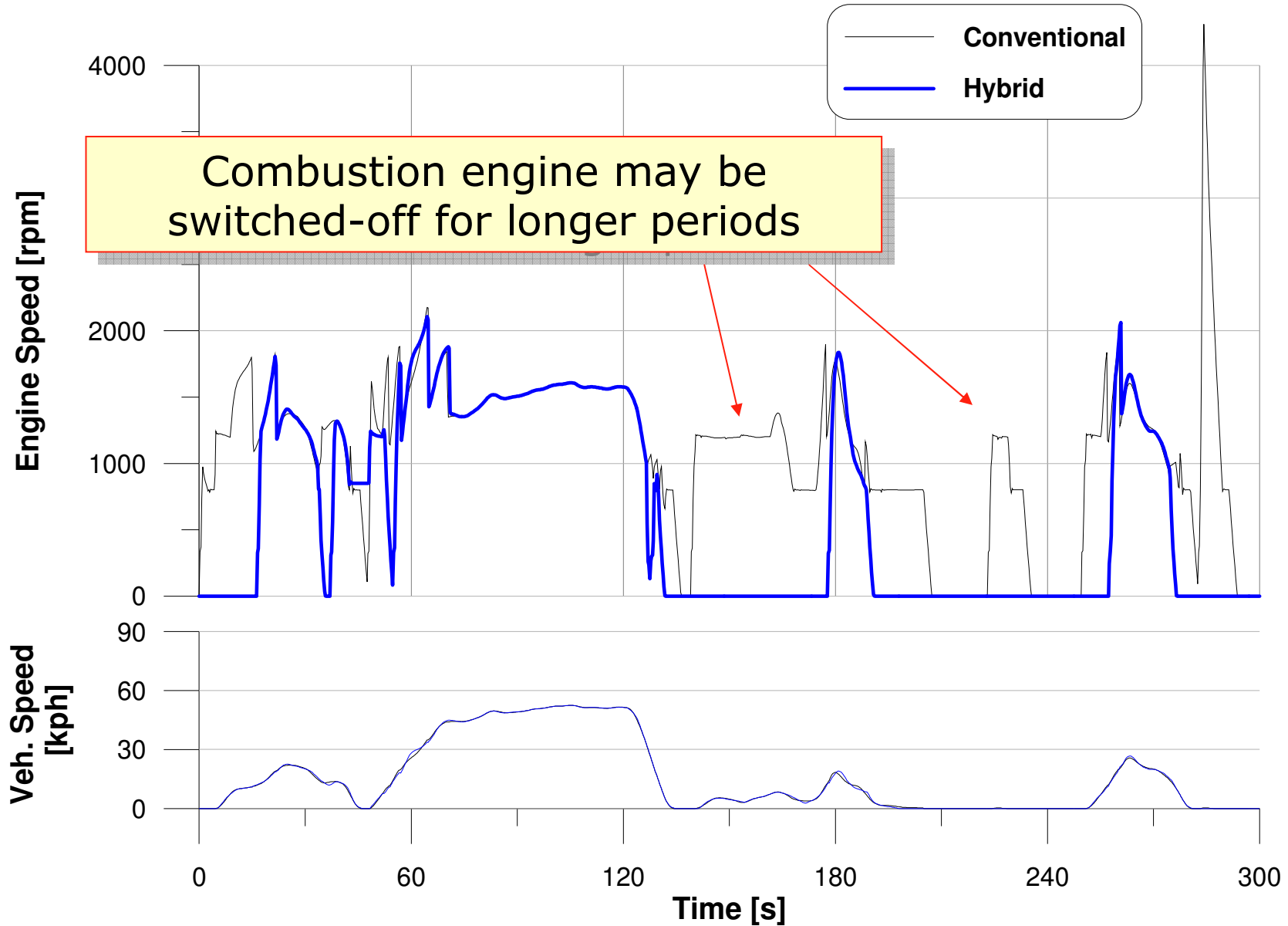
Engine load pattern shifting to higher loads in case of hybrid

Example

3.5 ton truck with parallel hybrid

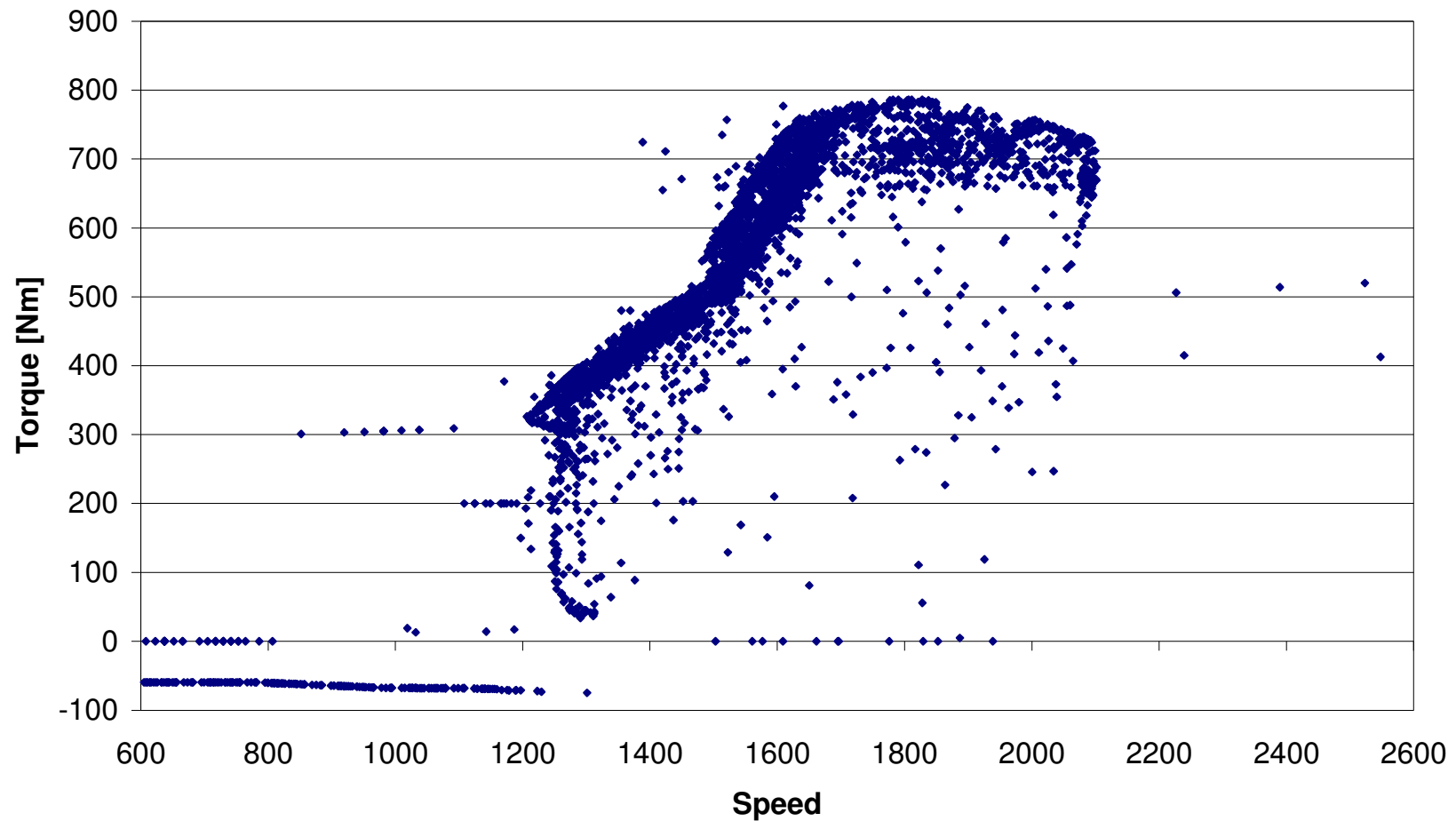


# Parallel hybrid (2)



# Serial hybrid

Serial Hybrid Full WHTC Cycle



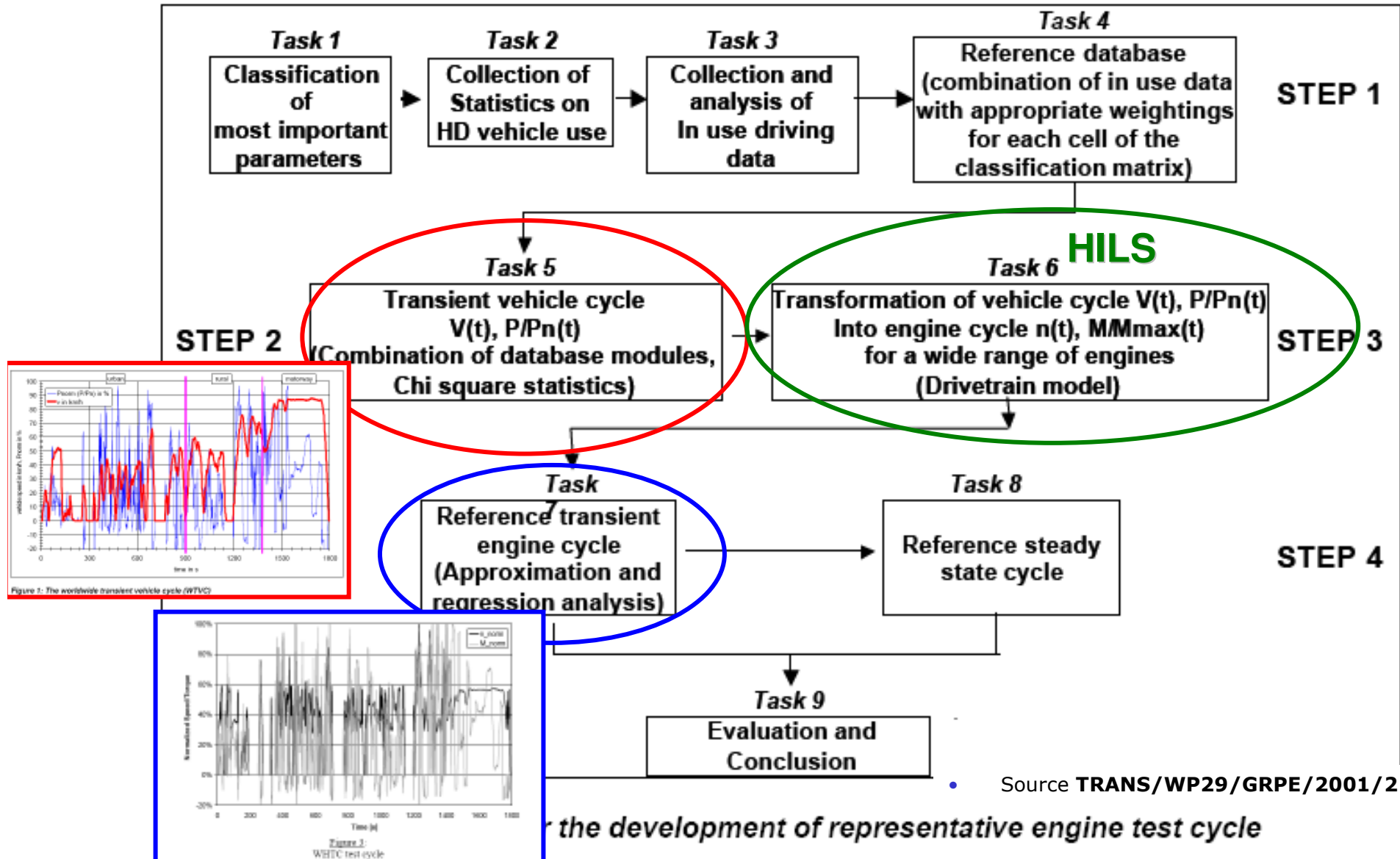
# Scope

- Emissions (NO<sub>x</sub>, HC, CO, PM) of HV's must remain – in real world application – at same level as conventional vehicles
- HV powertrain is optimised to obtain lowest energy consumption /CO<sub>2</sub>
- SOC (state of charge) must remain neutral over emission testing cycle (no external energy)
- To achieve best cost-efficiency of powertrain system

# Options to certify engines for HV's

Engine certified as today (ETC, WHTC, US-FTP)	No change to existing regulations	Engine may be operated in real driving under completely different conditions
Certification of complete vehicle on vehicle dyno	Truly reflecting the real vehicle	Controlling of test conditions, read-across for different vehicle-types within family,
System bench method, complete powertrain system to be tested on test bed	Complete system to be tested	Control? Bulky installation on test bed (with transmission),
HILS	Simple testing of engine only, cost-effective	extensive work to describe HILS on a regulatory-basis, Japanese std available

# WHTC development...HILS

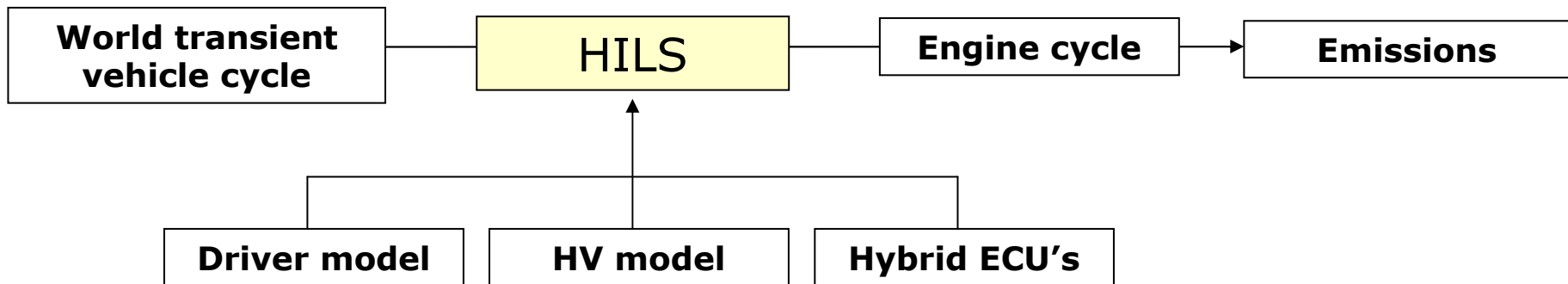
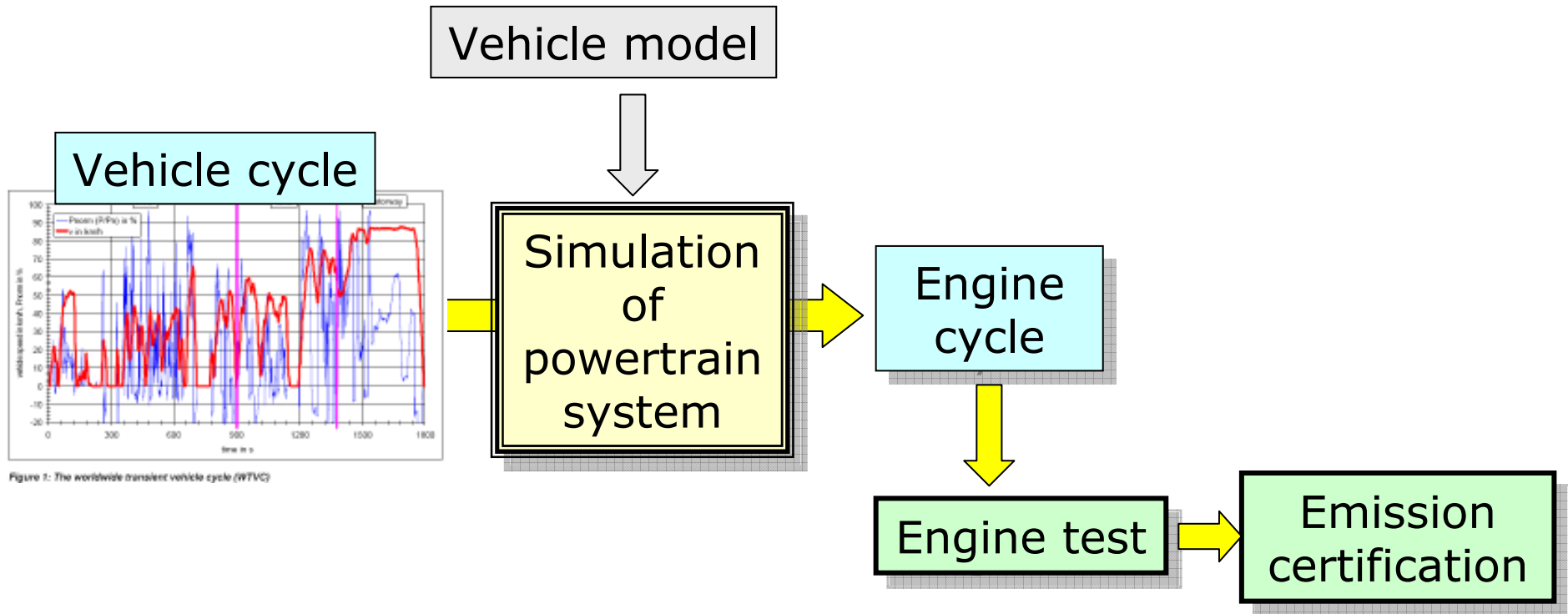


• Source TRANS/WP29/GRPE/2001/2

for the development of representative engine test cycle



# Basic approach



# HILS-methodology

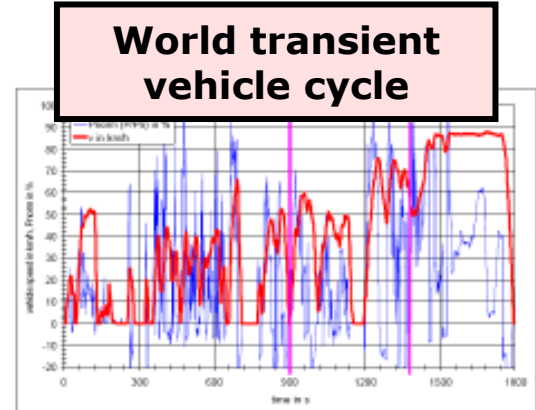
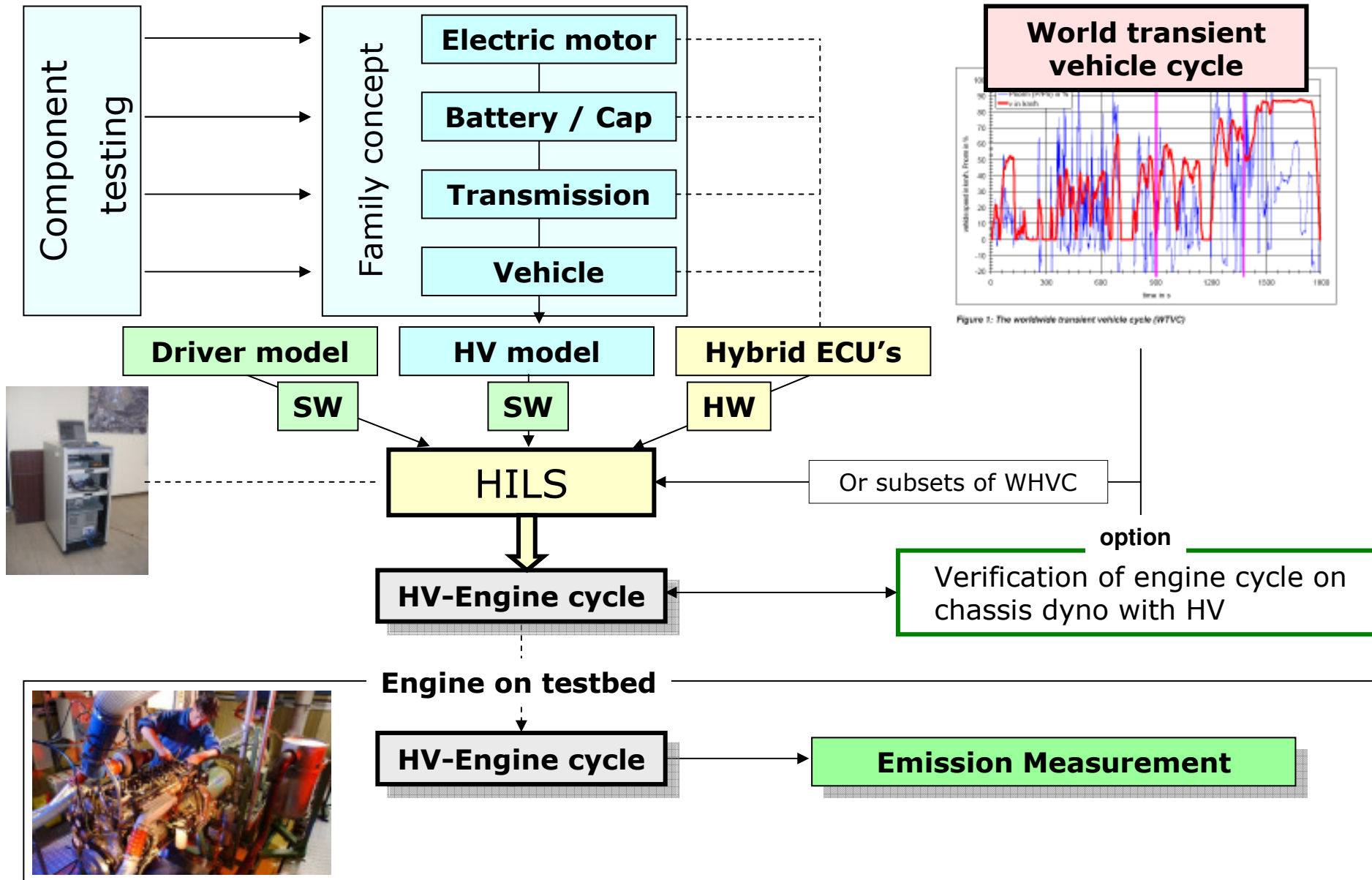
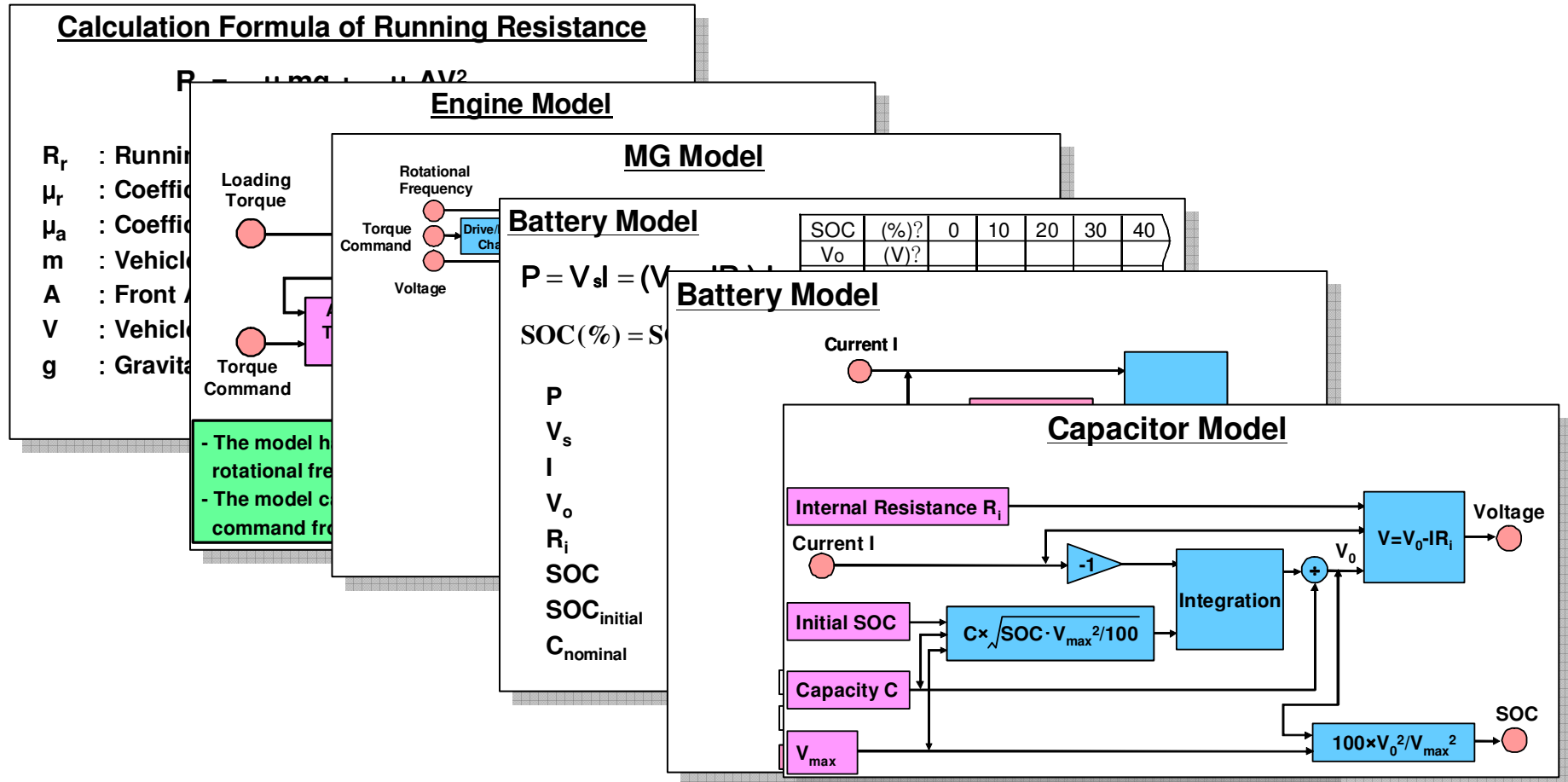
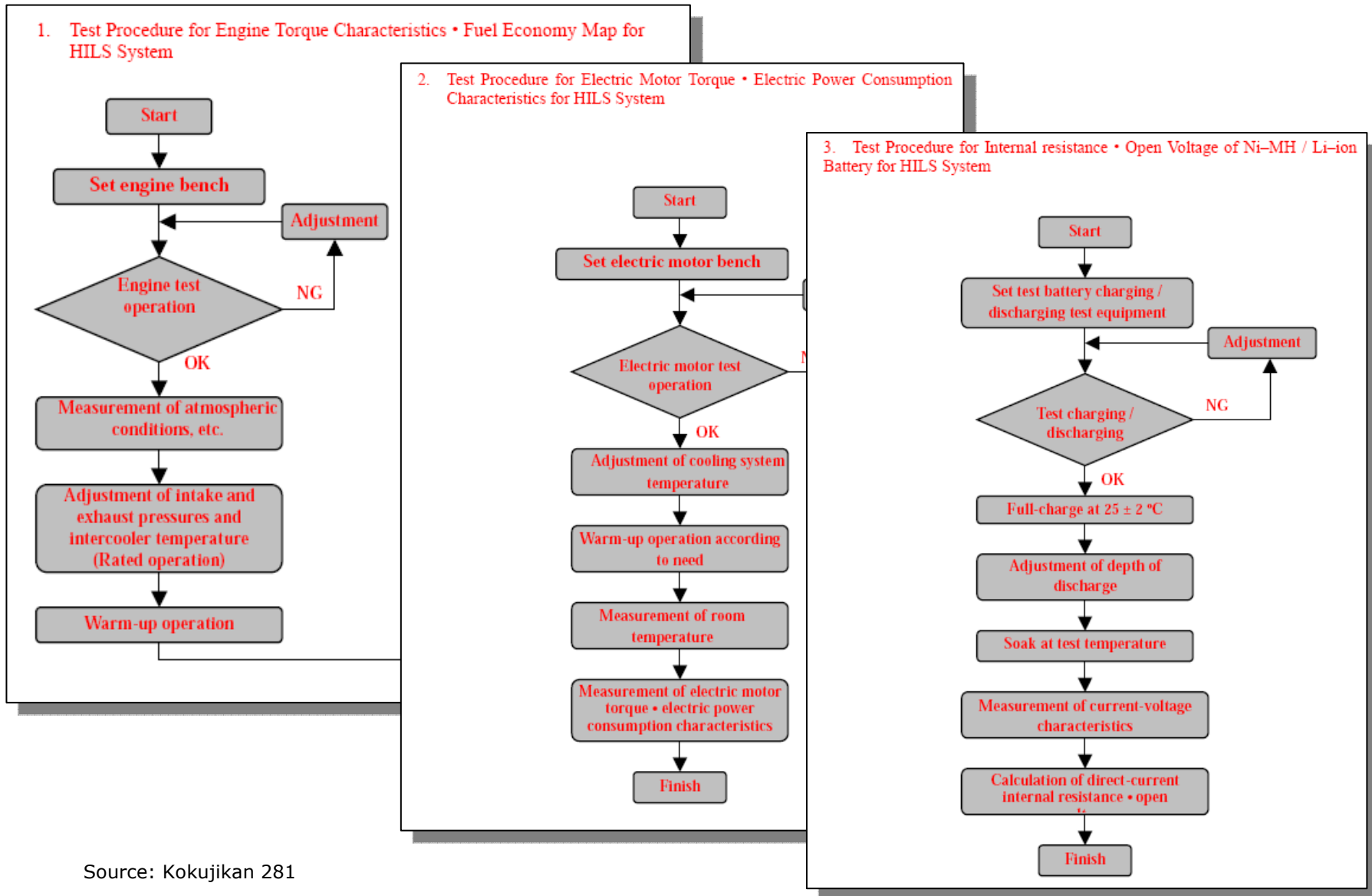


Figure 1: The worldwide transient vehicle cycle (WTVC)

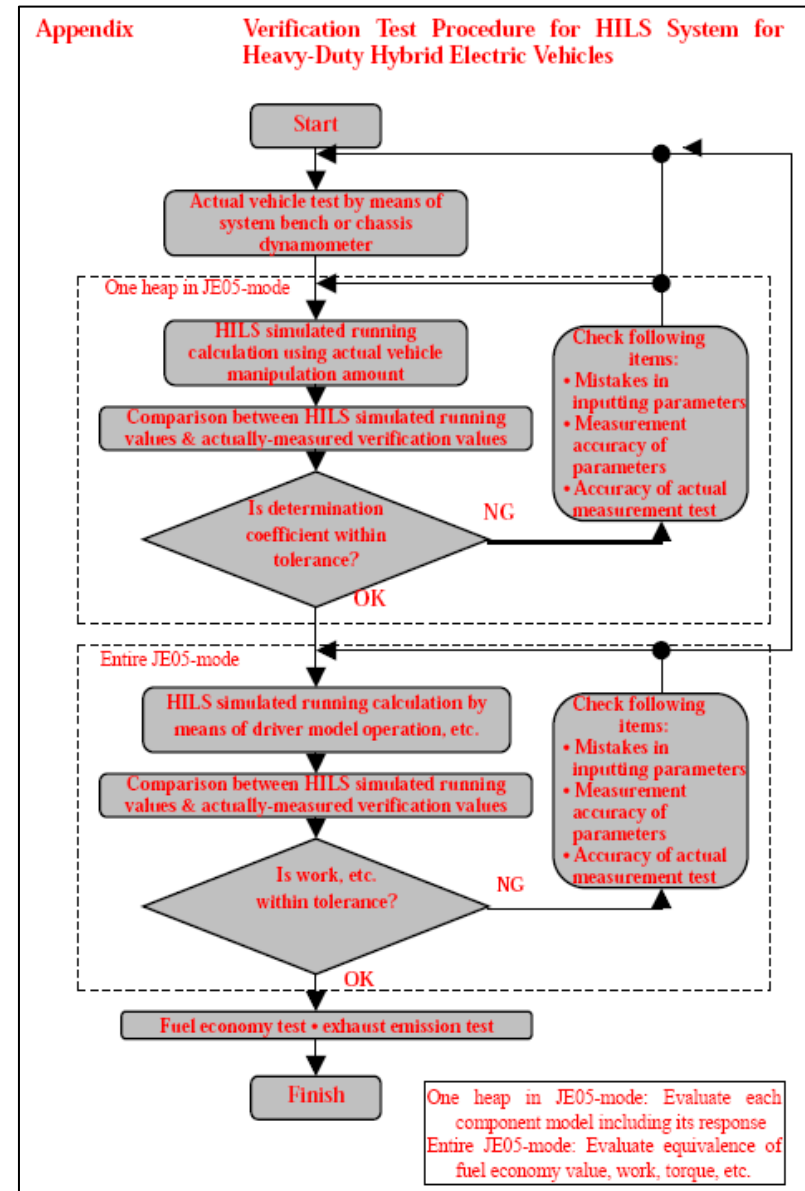
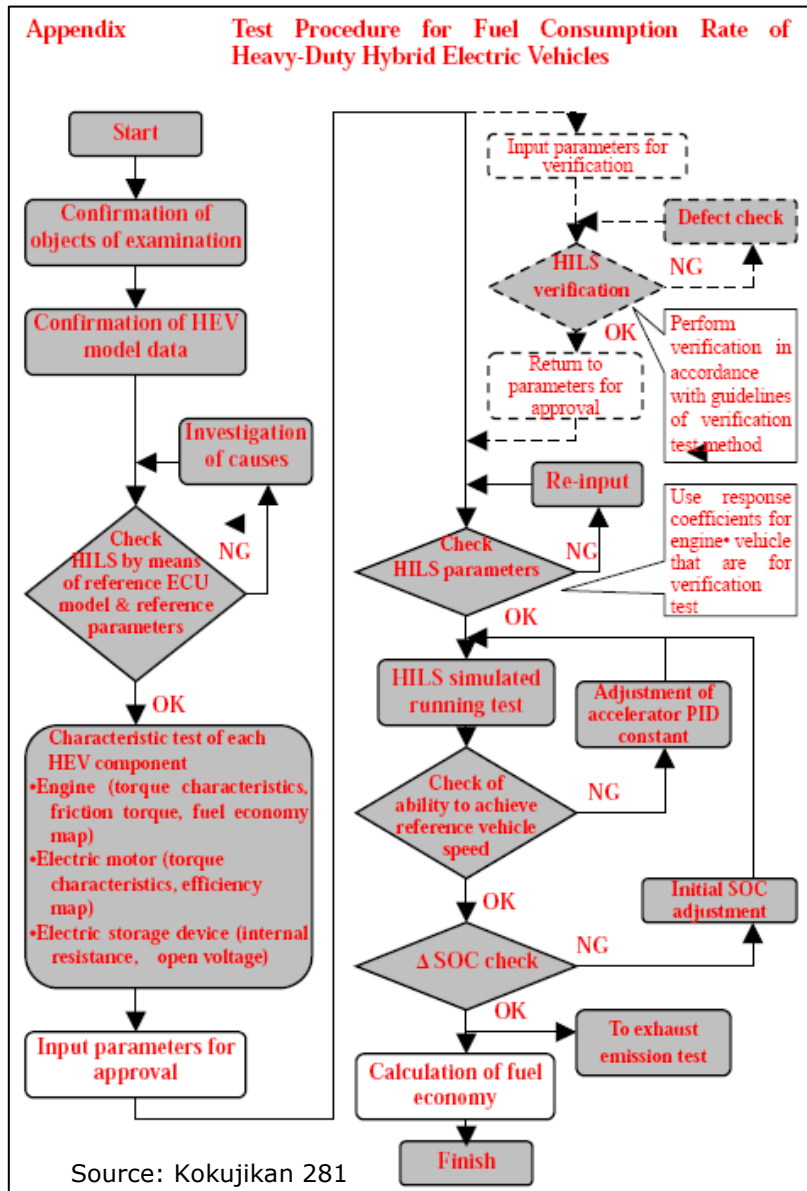
# JARI: HEV-Models



# Test procedures engine, motor, battery

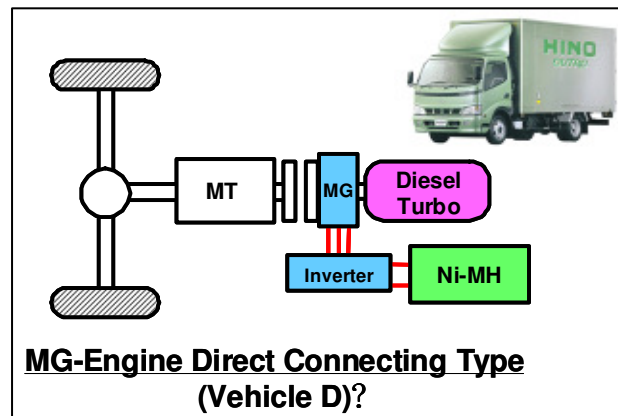
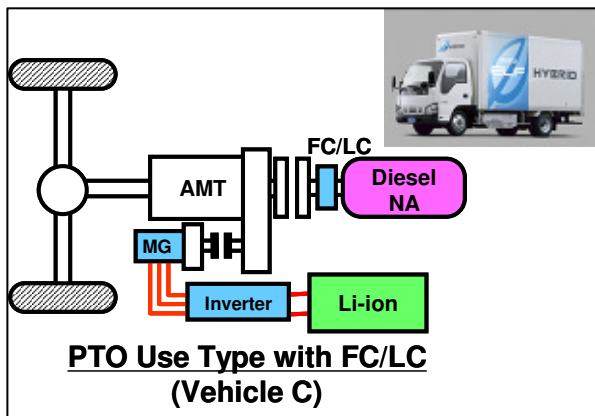
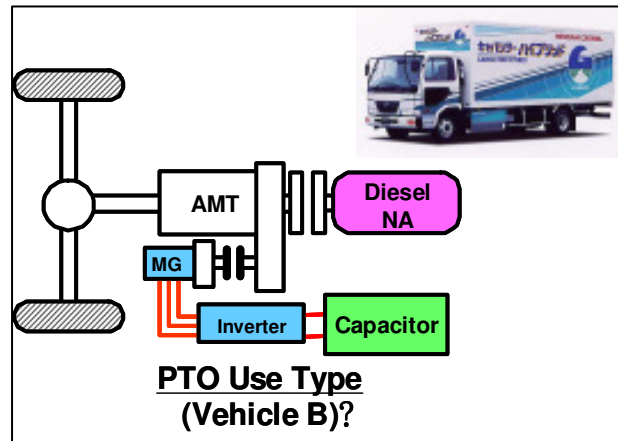
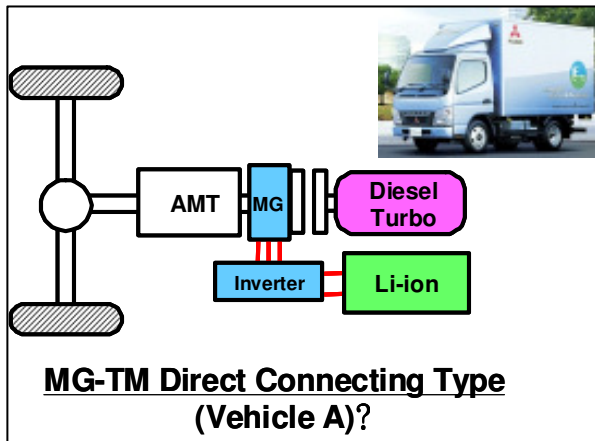


# Test procedure FC, Emissions and verification

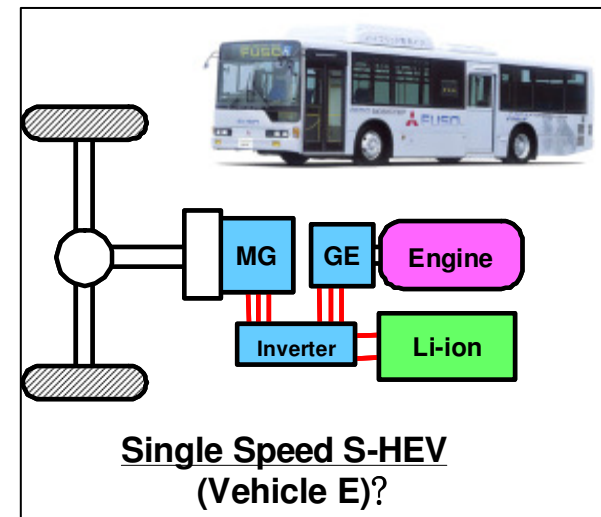


# JARI: standardised HEV - models

## Parallel Hybrid

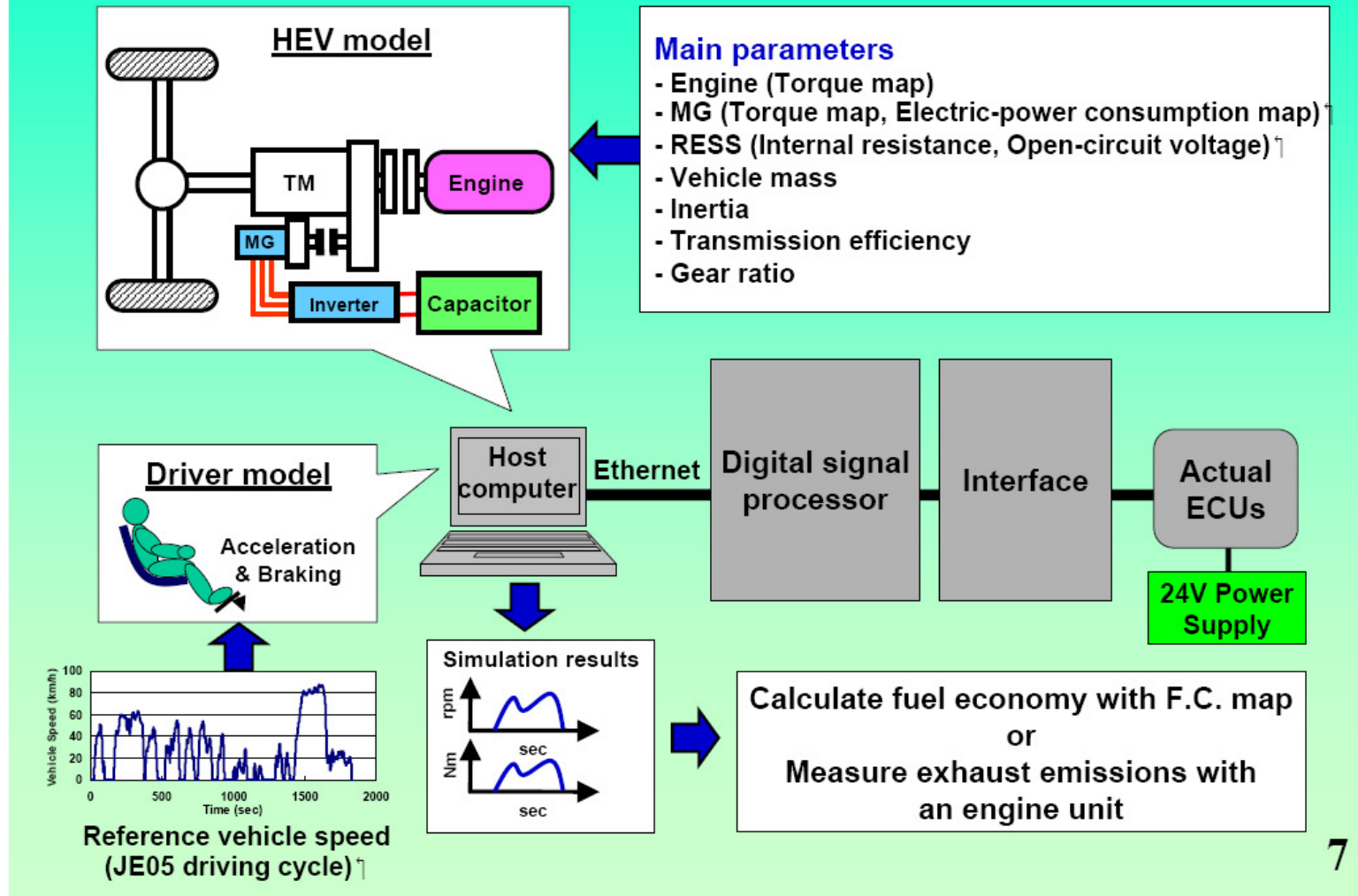


## Serial Hybrid



# Japanese HILS system approach

## HILS Method for Heavy-Duty HEVs



# JAMA / JARI HILS validation

- Evaluation of system bench test versus HILS
  - System bench test has too many limitations (types of hybrid systems) and inaccuracies
  - System bench test requires intensive resources
- With HILS method the engine can be tested in engine test-cell
  - Standard emission testing procedures
  - No additional resources for emission testing than usual
- HILS methodology verified in different steps
  - Rolling resistance air drag: coast down
  - Acceleration and braking
  - Overall evaluation with driver model
  - Over JE05 cycle ...work
  - And fuel economy testing
  - With very good results



# HILS - HW

## HILS – HW

The HILS-hardware as seen at the demonstration at JARI.  
The hardware is CRAMAS (Fujitsu Ten), the software from OnoSokki, no open source code, copyright issues  
Currently the approx price of one system is Euro 160k



# Tech. evaluation, issues

<b>Issue</b>	<b>Potential solution</b>	<b>Comment</b>
Durability, SOH	Introduction of DF's, in-use-conformity PEMS	investigation
Thermals	Electric systems only, specify and apply limitations and implement them into the models	
Auxiliaries	For emission certification not important	Details to be aligned with WHDC
Multi-ECU, distributed functionality	Install ,CAN-Bus' in HILS HW, seems to be basically possible	Key requirement
Difficulty with HW-integrated ECU / SW	SILS would be alternative but bearing other risks	Validation required, IUC-PEMS
All types of gearboxes	Introduce new models for automatic transmissions	Just work
Cold start	Test the engine as in WHTC (cold and hot soak test)	
Cycle bypass potential	Requires verification, PEMS-ISC to be applied	
HILS code	must be open-sourced	Black box model is not acceptable in a certification procedure
HILS-HW sourcing	To establish specifications	Incl. calibration
HILS models public	Public description of models	
Heat recovery (exhaust)	Fitted on engine at certification or by simulation	Possible extension of HILS

# HILS as developed by JAMA/JARI

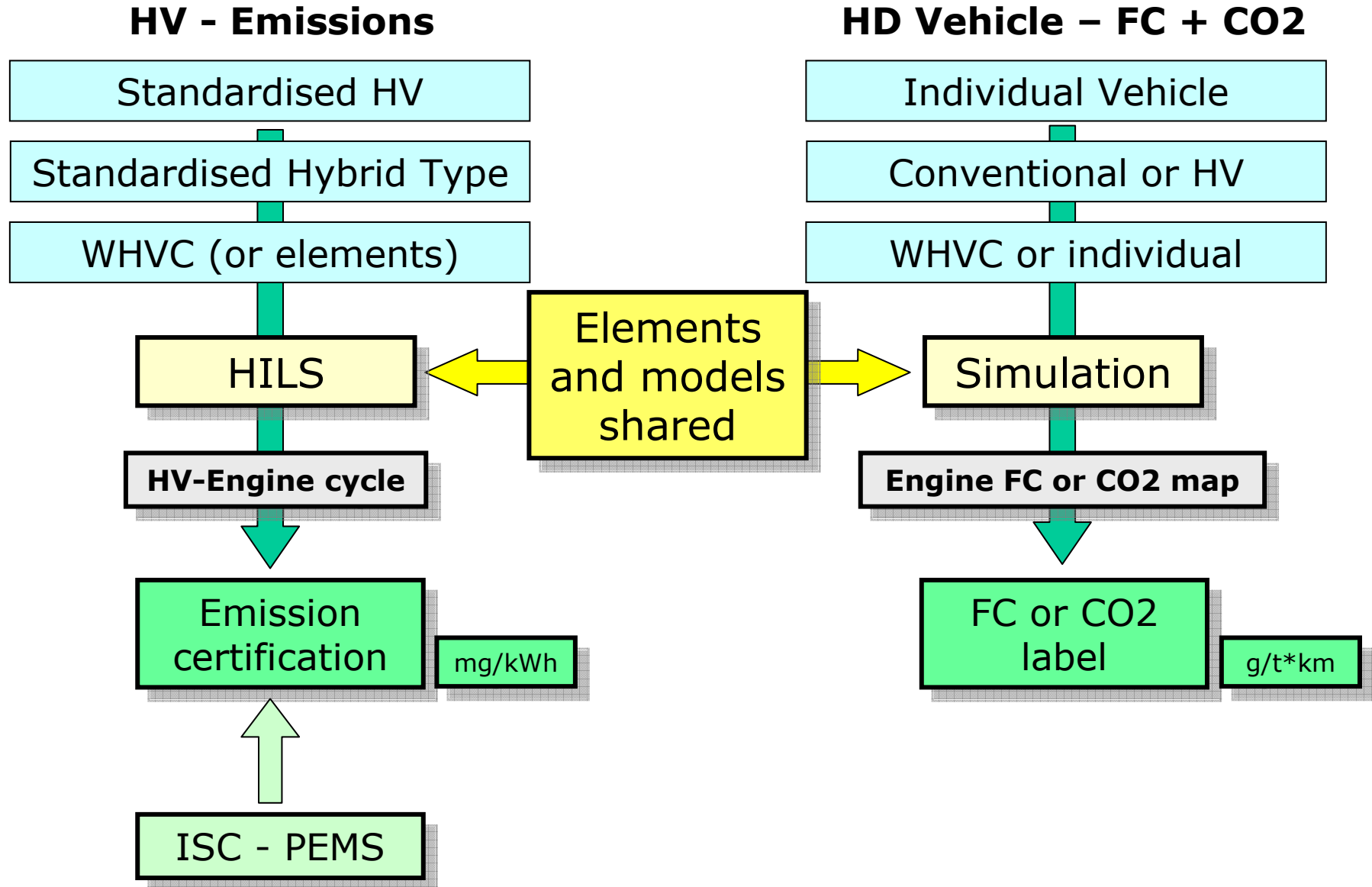
## Base documents

- SAE paper "Development of a fuel economy and emission test method with HILS for HD HEV's"  
2008-01-1318
- Kokujikan No. 281 of March 16, 2007:  
TEST PROCEDURE FOR FUEL CONSUMPTION RATE  
AND EXHAUST EMISSIONS OF HEAVY-DUTY  
HYBRID ELECTRIC VEHICLES USING  
HARDWARE-IN-THE-LOOP SIMULATOR SYSTEM
- Kokujikan No. 282 of March 16, 2007  
TEST PROCEDURE FOR HILS SYSTEM PROVISIONAL  
VERIFICATION FOR HEAVY-DUTY HYBRID ELECTRIC  
VEHICLES

# Fuel consumption / CO2

- HILS is proposed as emission certification test procedure along the same lines as WHDC → g/kWh emissions for a standardised cycle (WHVC) and standardised vehicle (family concept), all other Euro VI requirements apply
- ISC will check emission performance in real service
- HD-HV CO2 must be based on vehicle mission and load → elements of HILS in combination with individual vehicle specs, mission and load can be used for CO2 qualification

# Emissions - FC + CO2



## Other issues, challenges

- OCE, NTE to be adapted
- Emission test cycles with engine standstill periods (testbed and PEMS) → test equipment and control, protocols may need updating

# Summary

HIL-Simulation is the most cost-effective approach for emission certification of dedicated engines for HD-HV

# WHVC

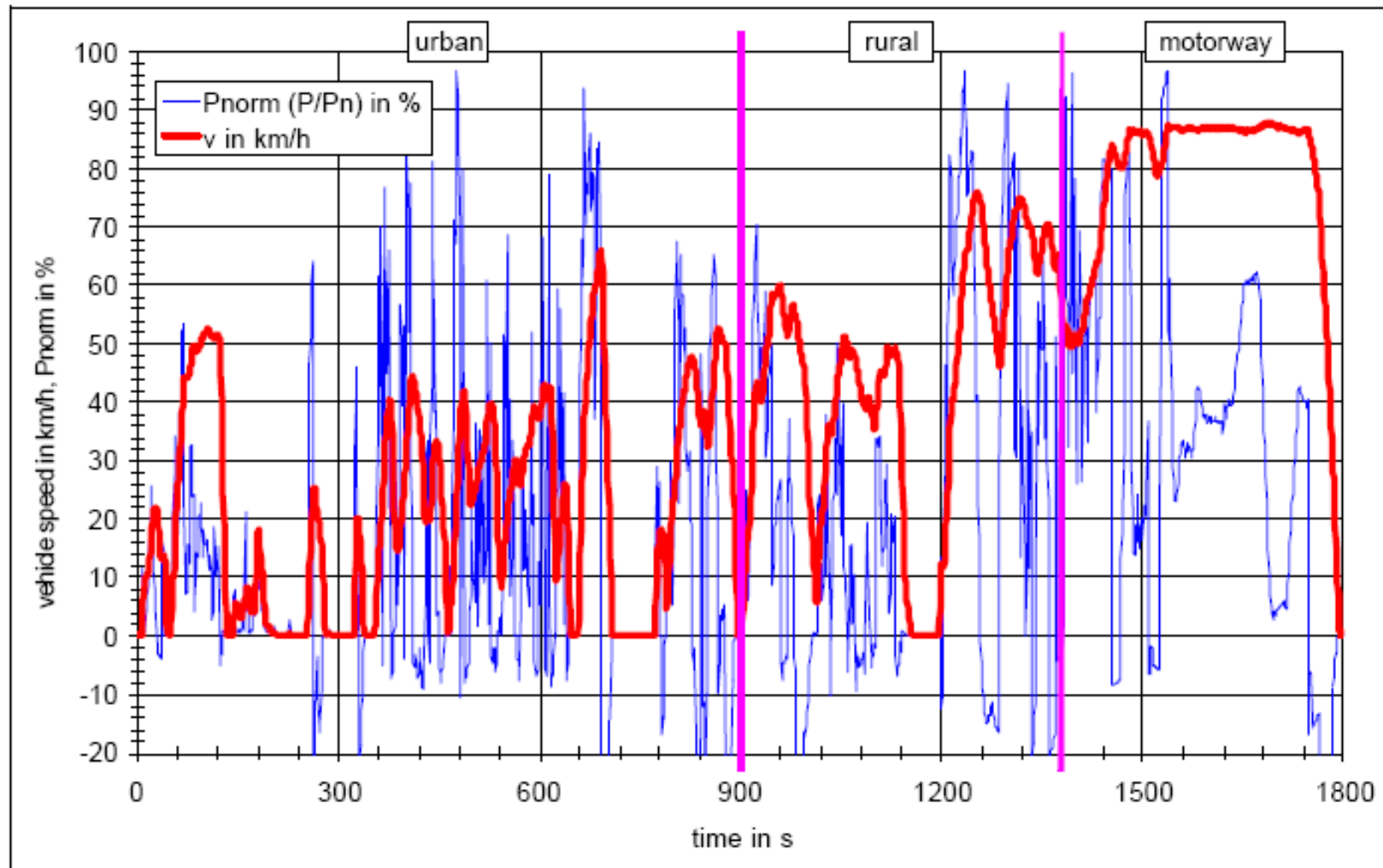
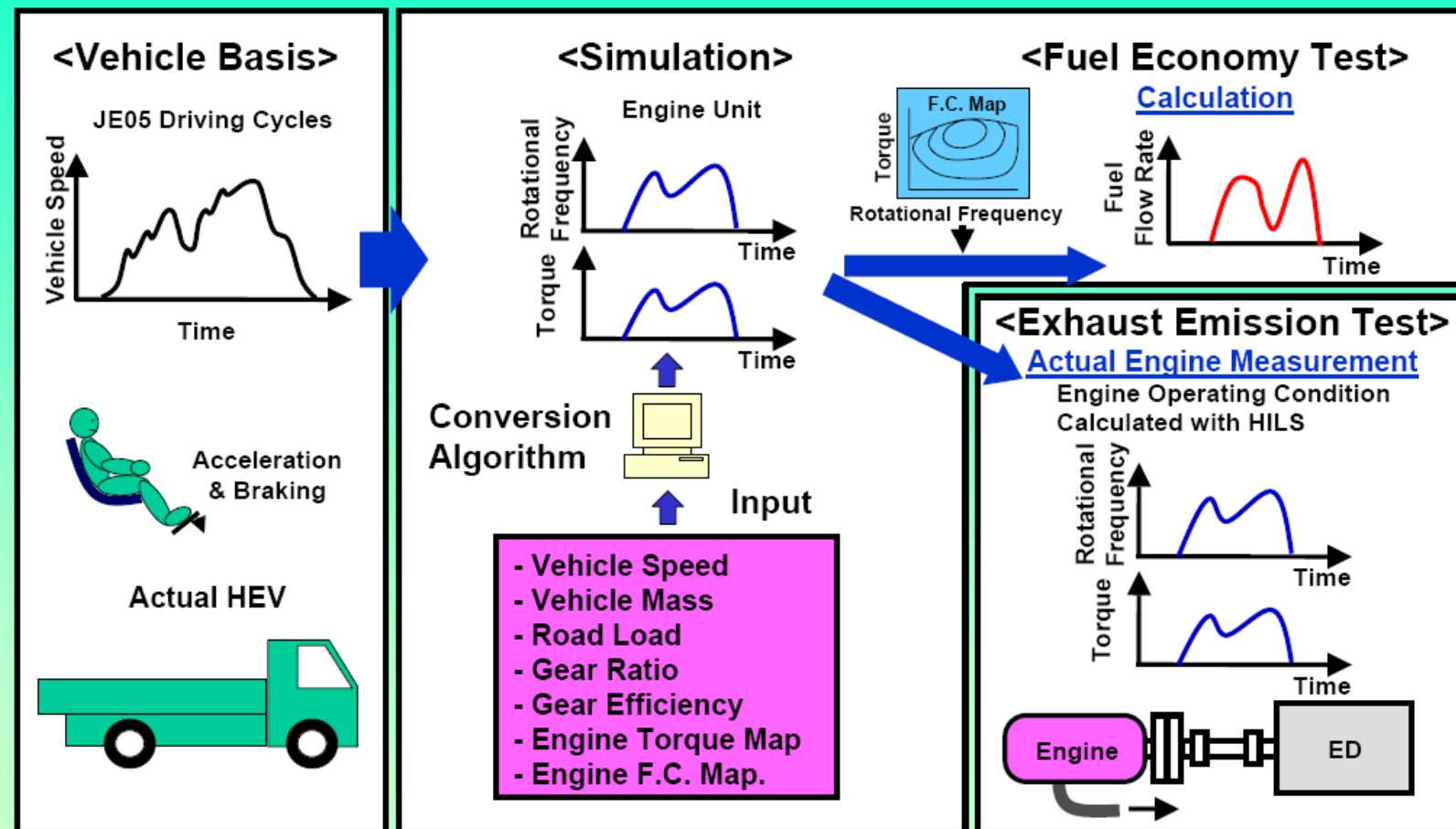


Figure 1: The worldwide transient vehicle cycle (WTVC)



# Conventional HD trucks – fuel economy / emissions Japan

## Simulation Method for HD Conventional Vehicles



In Japan, Simulation method is used for HD-CVs, because there are many vehicle types such as different gear ratios and different bodies.

# Japan Standard Vehicle Specification

standard vehicle specification by MLIT for exhaust/ gas

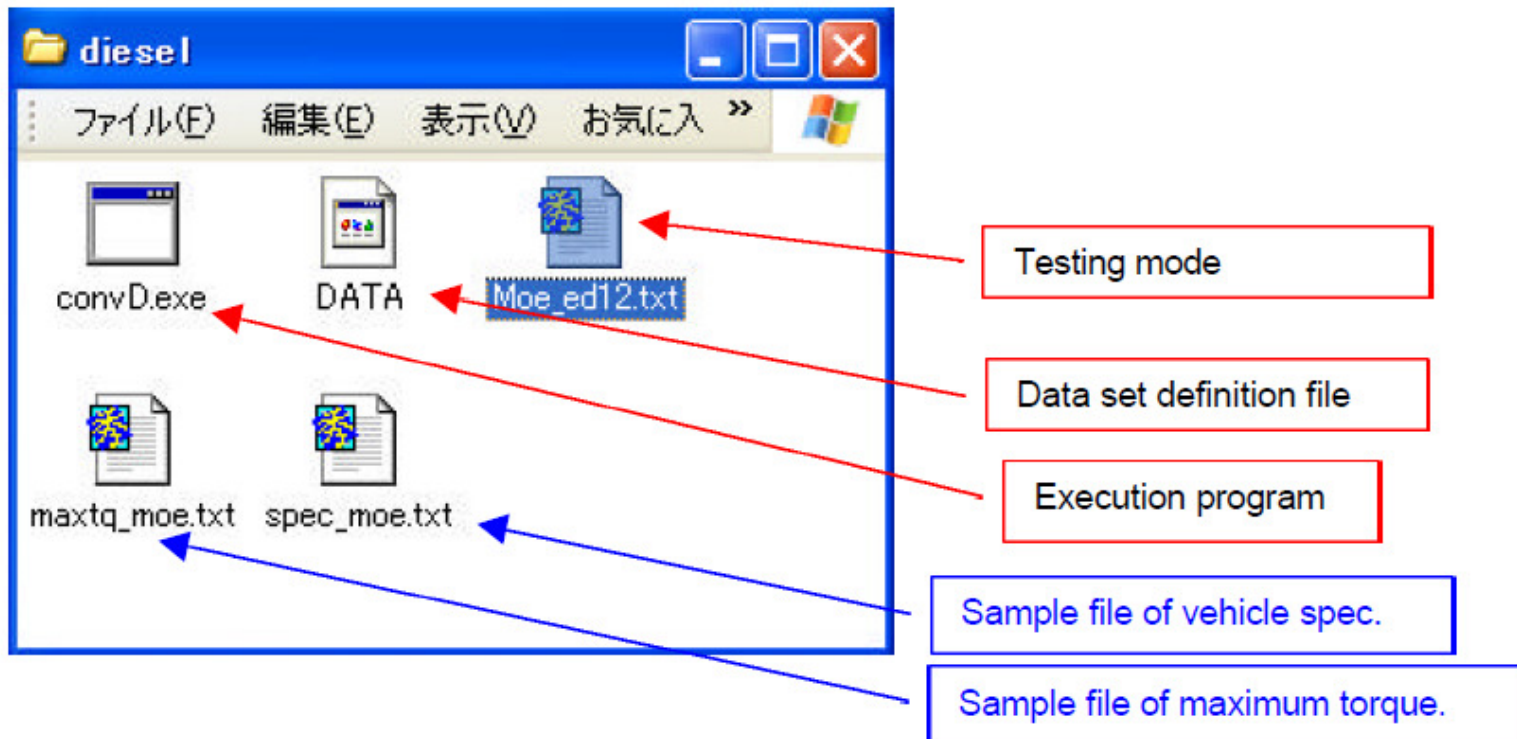
truck/ tractor category			bus category		fuel	empty vehicle mass (kg)	maximum payload (kg)	number of persons	test vehicle mass (kg)	tire dynamic radius (m)	overall height (m)	overall width (m)	transmission gear ratio							diff gear ratio
category NO	vehicle mass range GWW/ GCW(kg)	pay load range	category NO	vehicle mass range GWW(kg)									1st	2nd	3rd	4th	5th	6th	7th	
T1	3.5t<&≤7.5t	≤1.5t	-	-	D•LPG CNG	1957	1490	3	2757.0	0.313	1.982	1.695	5.076	2.713	1.529	1.000	0.795			4.615
					G•LPG CNG	1659	1458	3	2443.0	0.303	1.975	1.695	4.942	2.908	1.568	1.000	0.834			4.477
T2	3.5t<&≤7.5t	1.5t<	B1	3.5t<&≤6t	D•LPG CNG	2482	2396	3	3735.0	0.343	2.106	1.780	5.080	2.816	1.587	1.000	0.741			5.275
					G•LPG CNG	2259	2016	3	3322.0	0.327	2.052	1.722	5.089	2.773	1.577	1.000	0.777			6.051
T3	7.5t<&≤8t	-	B2	6t<&≤8t	G•D•LP G•CNG	3543	4275	2	5735.5	0.388	2.454	2.235	6.350	3.876	2.301	1.423	1.000	0.762		4.771
T4	8t<&≤16t	-	B3	8t<&≤16t	G•D•LP G•CNG	4527	7737	2	8450.5	0.469	2.617	2.374	6.416	4.096	2.385	1.475	1.000	0.760		5.208
T5	16t<&≤20t	-	B4	16t<&≤20t	G•D•LP G•CNG	8688	11089	2	14287.5	0.502	3.049	2.490	6.331	4.224	2.410	1.486	1.000	0.763	0.612	6.309
T6	20t<&≤25t	-	B5	20t<	G•D•LP G•CNG	8765	15530	2	16585.0	0.473	2.934	2.490	6.304	4.170	2.393	1.456	1.000	0.752	0.604	5.102
T7	25t<	-	-	-	G•D•LP G•CNG	12120	24974	2	24662.0	0.507	2.961	2.490	6.147	4.000	2.281	1.434	1.000	0.760	0.597	6.061

truck GWW=empty vehicle mass+maximum pay load+(number of persons) x 55kg

bus GWW=empty vehicle mass+( driver+number of passengers)x55kg

test vehicle mass=empty vehicle mass +maximum pay load/ 2+55kg

# Engine Cycle Conversion Program



# Example of Cycle Conversion


```
C:\Documents and Settings\stadashi\Desktop\diesel\convDintel.exe
GVW = 7860.00[kg]
WO = 3400.00[kg], Wtest = 5630.00[kg]
Width = 2.230[m], Height = 2.410[m], Tire radius = 0.388[m]
Crew = 2

Nidle = 550.00[rpm], Nrate = 2500.00[rpm], Nex = 2700.00[rpm]
Nes = 647.50[rpm], Nec = 628.00[rpm]
MuAir = 0.015237 [kgf/(km/h)^2], MuRoll = 0.008256 [kgf/kg]

Number of gear = 6
gear  ratio  efficiency  torq margin  DW[kg]
  1:   6.098   0.950      2.400      4030.93161
  2:   3.858   0.950      2.400      1756.18473
  3:   2.340   0.950      1.700       796.51120
  4:   1.422   0.950      1.600       444.25257
  5:   1.000   0.980      1.600       340.00000
  6:   0.761   0.950      1.600       297.07034
fin:   3.900   0.950

Type filename for output : outmoe.txt
```

# Example of Data Output

Vehicle Cycle  Engine Cycle

time (s)	Vtarget (km/h)	Vreal(km/h)	Ne (rpm)	Te (N-m)	n_norm (%)	T_norm (%)	shift
0	0	0	500.0	0.0	0	0	0
1	0	0	500.0	0.0	0	0	0
2	0	0	500.0	0.0	0	0	0
3	0	0	500.0	0.0	0	0	0
4	0	0	500.0	0.0	0	0	0
5	0	0	500.0	0.0	0	0	0
6	0	0	500.0	0.0	0	0	0
7	0	0	500.0	0.0	0	0	0
8	0	0	500.0	0.0	0	0	0
9	0	0	500.0	0.0	0	0	0
10	0	0	500.0	0.0	0	0	0
11	0	0	500.0	0.0	0	0	0
12	0	0	500.0	0.0	0	0	0
13	0	0	500.0	0.0	0	0	0
14	0	0	500.0	0.0	0	0	0
15	0	0	500.0	0.0	0	0	0
16	0	0	500.0	0.0	0	0	0
17	0	0	500.0	0.0	0	0	0
18	0	0	500.0	0.0	0	0	0
19	0	0	500.0	0.0	0	0	0
20	0	0	500.0	0.0	0	0	0
21	0	0	500.0	0.0	0	0	0
22	0	0	500.0	0.0	0	0	0
23	0	0	500.0	0.0	0	0	0
24	0	0	500.0	0.0	0	0	0
25	4.19	4.19	562.5	952.1	5	88.73	2
26	8.32	8.32	770.3	939.2	21.63	61.32	2
27	12.33	12.33	1141.6	913.4	51.33	50.64	2
28	16.05	16.05	1486.0	850.3	78.88	49.46	2
29	18.74	18.74	1020.3	864.8	41.62	47.56	3
30	20.28	20.28	1104.1	520.7	48.33	28.78	3