Status report 'Sub group 2': Real world road test

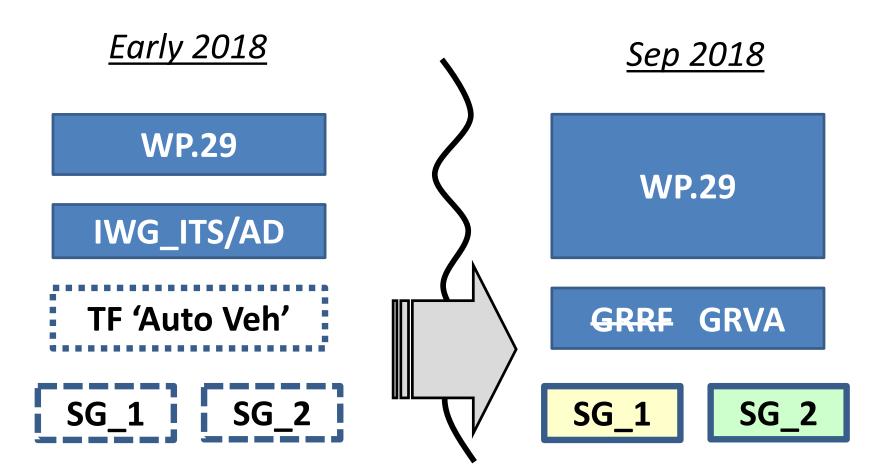
Arjan Dijkhuizen (RDW, NL) Geneva, September 2018

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Background

 How to test and assess the functionality of automated driving systems?



Timeline

In conjunction with Sub group_1:

- 1st meeting: The Hague, 4-5 June 2018
- 2nd meeting: Paris, 3-4 September 2018



- 3rd meeting: Niigata (Japan), 23-25 October 2018
- 4th meeting: Beijing, 14-15 January 2019 (to be confirmed)
- 5th meeting: Washington D.C., 1-3 April 2019
- Mandate until December 2020

Terms of reference

Approach based on three pillars:

Audit

Incl. simulation Virtual testing

Test track

Assessment in a controlled environment

Real world

General testing

Sub group 1

Chair: Onoda-san

Secretary: Oshita-san

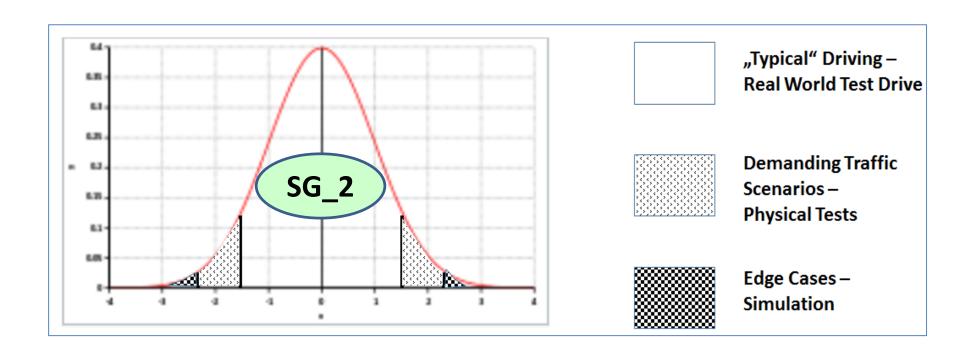
Sub group 2

Chair: P. Striekwold

Secretary: W. Gouse

Terms of reference – cont.

Testing coverage:



Terms of reference – cont.

- As part of the '3 pillar approach', to (Cat M, N on L3 -5):
 - Develop real world road tests to assess automated systems in order to ensure road safety
 - Demonstrate system compliance with traffic laws
- Develop requirements based on test scenarios
- Focus on urban traffic and motorway/highway traffic
- Consideration on ISC measures during the vehicle's life
- Implementation to be decided by WP.29 (Regulation, GTR, guideline or best practice)

Presentations

- 1. AV driving behaviour measurement (McLaren/Meridian)
- Driving a vehicle on the public road requires 'perception',
 'planning' and 'command'. Perception is the most
 difficult, human behaviour is not a mechanical system
- Human examiner is well equipped to spot the unusual but not good at monitoring a list of items
- 2. AEBS on trucks (Dutch 'Rijkswaterstaat')
- Test results of trucks approaching road work barriers, appealing to the relevance of real world road tests

More information

- ToR: informal document GRVA-01-11
- Wiki: https://wiki.unece.org/display/trans/SG-2+Real+World+Test+Drive

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